

Lecture Notes
on
**Th:1- Data Communication
& Computer Networks**
(5th semester E&TC) New Syllabus



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Program Outcomes (POs):

- **PO1:** Apply knowledge of basic mathematics, science, engineering fundamentals and engineering specialization to solve the engineering problems.
- **PO2:** Identify and analyze well-defined engineering problems using codified standard methods
- **PO3:** Design/development of solutions: Design solutions for well-defined technical problems and assist with the design of systems components or processes to meet specified needs.
- **PO4:** Apply modern engineering tools and appropriate technique to conduct standard tests and measurements.
- **PO5:** Apply appropriate technology in context of society, sustainability, environment and ethical practices.
- **PO6:** Use engineering management principles individually, as a team member or a leader to manage projects and effectively communicate about well-defined engineering activities.
- **PO7:** Ability to analyze individual needs and engage in updating in the context of technological changes

Course Outcomes (COs)

Course Code: ETCPC301

Course Title: Data Communication & Computer Networks

CO No.	Course Outcome
CO1	Explain the fundamentals of data communication, networking concepts, communication protocols, and the OSI and TCP/IP reference models.
CO2	Analyze data transmission techniques, channel capacity, and the characteristics of guided and unguided transmission media used in computer networks.
CO3	Describe data encoding methods, error detection and correction techniques, flow control, multiplexing, and data link control mechanisms for reliable communication.
CO4	Compare switching techniques (circuit and packet switching), routing principles, congestion control methods, and traffic management strategies in communication networks.
CO5	Explain LAN technologies, Ethernet (CSMA/CD), networking devices (Hub, Bridge, Switch), wireless LAN concepts, and the architecture and operation of the TCP/IP protocol suite for internetworking.

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UNIT-1: NETWORK & PROTOCOL

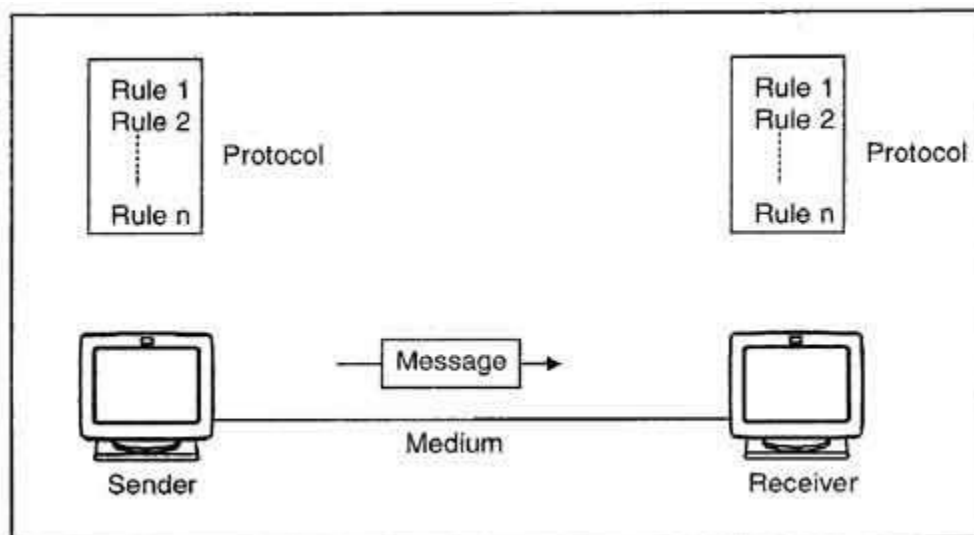
1.1 Data communication refers to the exchange of data between a source and a receiver via form of transmission media such as a wire cable. Data communication is said to be local if communicating devices are in the same building or a similarly restricted geographical area.

The meanings of source and receiver are very simple. The device that transmits the data is known as source and the device that receives the transmitted data is known as receiver. Data communication aims at the transfer of data and maintenance of the data during the process but not the actual generation of the information at the source and receiver.

1.1.1 Components of data communication system-

A Communication system has following components:

1. **Message:** It is the information or data to be communicated. It can consist of text, numbers, pictures, sound or video or any combination of these.
2. **Sender:** It is the device/computer that generates and sends that message.
3. **Receiver:** It is the device or computer that receives the message. The location of receiver computer is generally different from the sender computer. The distance between sender and receiver depends upon the types of network used in between.
4. **Medium:** It is the channel or physical path through which the message is carried from sender to the receiver. The medium can be wired like twisted pair wire, coaxial cable, fiber-optic cable or wireless like laser, radio waves, and microwaves.
5. **Protocol:** It is a set of rules that govern the communication between the devices. Both sender and receiver follow same protocols to communicate with each other.



A protocol performs the following functions:

1. **Data sequencing.** It refers to breaking a long message into smaller packets of fixed size. Data sequencing rules define the method of numbering packets to detect loss or duplication of packets, and to correctly identify packets, which belong to same message.
2. **Data routing.** Data routing defines the most efficient path between the source and destination.
3. **Data formatting.** Data formatting rules define which group of bits or characters within packet constitute data, control, addressing, or other information.
4. **Flow control.** A communication protocol also prevents a fast sender from overwhelming a slow receiver. It ensures resource sharing and protection against traffic congestion by regulating the flow of data on communication lines.
5. **Error control.** These rules are designed to detect errors in messages and to ensure transmission of correct messages. The most common method is to retransmit erroneous message block. In such a case, a block having error is discarded by the receiver and is retransmitted by the sender.
6. **Precedence and order of transmission.** These rules ensure that all the nodes get a chance to use the communication lines and other resources of the network based on the priorities assigned to them.
7. **Connection establishment and termination.** These rules define how connections are established, maintained and terminated when two nodes of a network want to communicate with each other.
8. **Data security.** Providing data security and privacy is also built into most communication software packages. It prevents access of data by unauthorized users.
9. **Log information.** Several communication software are designed to develop log information, which consists of all jobs and data communications tasks that have taken place. Such information may be used for charging the users of the network based on their usage of the network resources.

1.1.2 The effectiveness depends on four fundamental characteristics of data communications

1. Delivery:

The system must deliver data to the exact destination. Data must not be received by other devices than the target device.

2. Accuracy:

The system must deliver data to the destination in a way that the target device receives the data accurately. If the protocol needs to alter the while in transmission, it must alter it back to its original form before representing it to the target device. The accuracy must be maintained.

3. Timeliness:

The system must deliver data in timely manner. Data delivered late can become useless. Data must be delivered as they are produced, in the order they are produced and without any significant delay.

4. Jitter:

Jitter refers to the variation of packet arrival time. Data is sent as packets, that is, a fixed amount of the whole data is sent in each turn. These packets get joined back in the target device to represent the complete data as it is. Each packet is sent with a predefined delay or acceptable amount delay. If packets are sent without maintaining the predefined delay then an uneven quality in the data might result.

1.1.3 Data Representation-

Information can be in the form of text, numbers, images, audio, and video.

Text

Text symbols are represented with a sequence of bits 0 or 1. Each sequence is called a code, and the process is called coding.

Number

Numbers are also represented with a sequence of 0 and 1. ASCII is not used for number representation

Images

An image is also represented with a sequence of 0 and 1. A digital image is made up of small units called pixels. Each pixel is assigned a bit pattern whose size depends on the nature of the image.

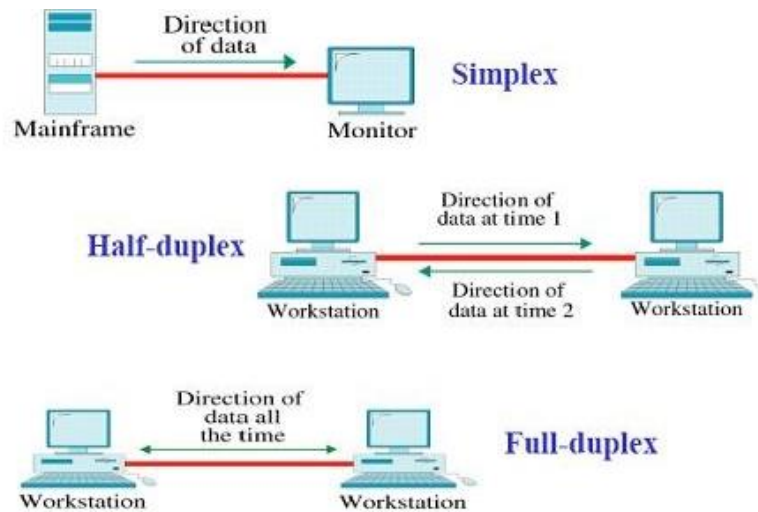
Audio

A sound which lies within the human hearing frequency range of 20 to 20000 Hertz is called audio. The sound is recorded with a microphone and then digitized to represent in the form of bit-patterns. Its transmitted form is called an audio signal.

Video

Flashing a sequence of images on the display screen which gives us a sensation of moving objects is called a video. A video is recorded with a camera and transmitted as a video signal.

1.1.4 Data Flow-



Data Flow in communication have the following types:

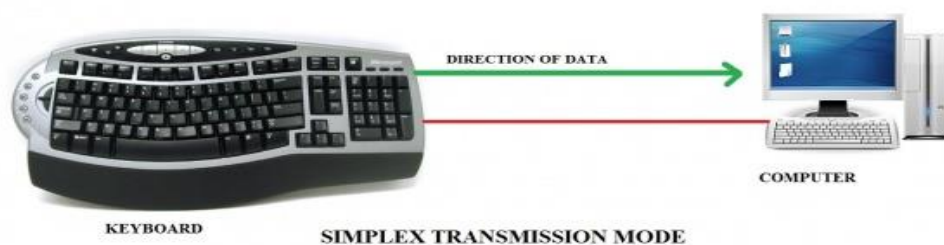
1. Simplex
2. Half duplex
3. Full duplex

1. Simplex:

In simplex data flow only in one direction. Its mean in simplex if two devices are connected only one device will send data the other device will only receive data it cannot send.

In this type channel will use all of its capacity only in sending data.

Example of this type is: Mouse (it can only input data etc)



Simplex communication



2. Half duplex:

In this type of data flow, data will flow in both directions but not at the same time. For example: If two devices are connected both of them can send information to each other but not at the same time. When one device will send data the other will receive it cannot send back at the same time after receiving it can send data.

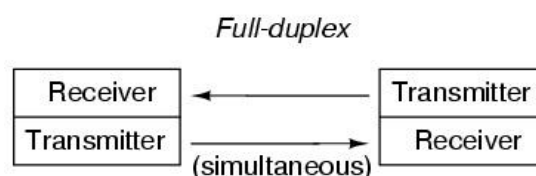
In half duplex channel will use all of its capacity for each direction. So this type will be used in the communication in which there is no need of response at the same time. Example of this type is Walkie Talkies.



3. Full Duplex:

In Full Duplex data will flow in both directions at the same time. For Example: If two devices are connected in communication both of them can send and receive data at the same time.

In Full Duplex channel will divide all of its capacity in both directions. Full Duplex is used when communication is required in both directions at the same time. Example of Full Duplex is calling on mobile phone etc.



1.2 NETWORK-

A network consists of two or more computers that are linked in order to share resources (such as printers and CDs), exchange files, or allow electronic communications. The computers on a network may be linked through cables, telephone lines, radio waves, satellites, or infrared light beams.

1.2.1 NETWORK TOPOLOGY-

The term topology refers that way in which the end points, or stations, attached to the network are interconnected or it is the arrangements of systems in a computer network. It can be either physical or logical. The physical topology refers that, how a network is placed in a physical way and it will include the devices, installation and location. Logical topology refers that how a data transfers in a network as opposed to its design.

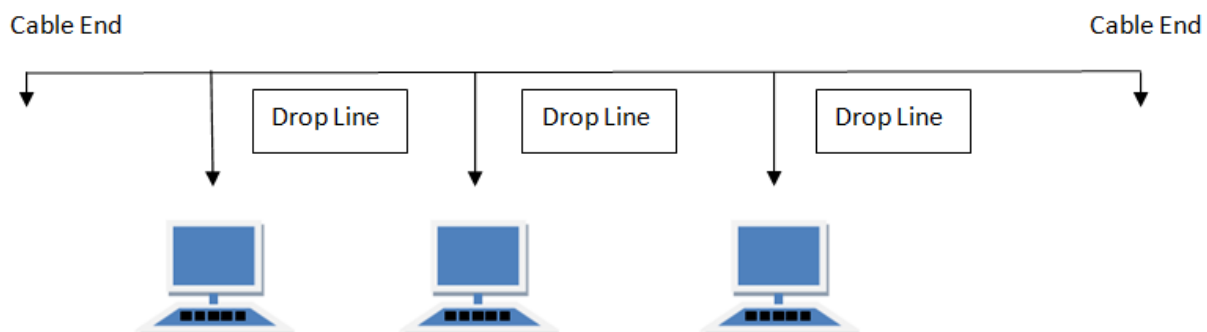
Classification of Network Topology-

The network topology can be categorized into bus, ring, star, tree and mesh.

Hybrid networks (They are the complex networks, which can be built of two or more topologies together).

Bus Topology

A bus topology is characterized by the use of a multi-point medium. A long and single cable acts as a backbone to connect all the devices in a network. In a bus topology, all computers are stations attaching through the tap (an interfacing hardware to connect to the network) and it connects directly to the bus network. Data's are transmitting and receiving to the bus, by the duplex actions between the tap and the device. Devices in the bus topology send a broadcast message to the other device for communications. But the proposed device can only accepts and processes the messages.



Advantages

- Bus topology can install very easily on a network.

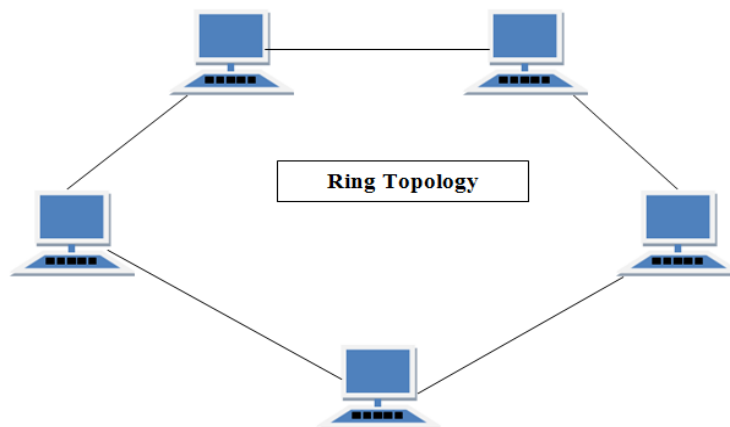
- Cabling will be less compare to other topologies because of the main backbone cable laid efficiently in the network path.
- Bus topology suited for a small network.
- If one computer fails in the network, the other computers are not affected they will continue to work.
- It is also less expensive than star topology.

Disadvantages

- The cable length will limited and there by limits the number of stations.
- The main cable (backbone cable) fails, and then the entire network will fail.
- It is very difficult to trouble shoot.
- Maintenance cost is very high in a long run.
- Terminators are required for both the ends of the cable.

Ring topology

The ring topology is the network consists of dedicated point to point connection. Signals passing through ring in a single direction until they reach to its final destination. It may be clock wise or anti clock wise. Data's are transmitted in the form of frames. These topologies are used in school campuses and some office buildings.



Advantages

- It performs better than star topology under heavy work load
- For managing the connection between the computers, there is no need for the network server.
- It is cheaper than star topology because of less wiring.
- By adding the token ring in the network, can create large network.

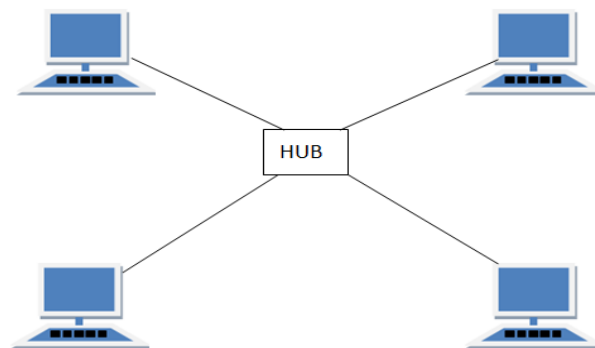
Disadvantages

- A failure or break in the ring, it can disable the entire network.
- It is much slower than an Ethernet network with under normal load.
- Any changes of the devices can affect the network.

- Network connection devices like Network adapter cards and Media Access Unit are much more expensive than Ethernet cards.

Star Topology

Star topology is the network in which each station is directly connected to a central connecting node called hub. In star topology all the devices are not directly connected to one another. All the devices are connecting to the central server (switching hub). This topology does not enable the direct traffic between the devices in the network. A controller act as the interface between the devices. This type of topology is used in local area networks (LAN) and sometimes high speed LAN often uses a star topology with central hub.



Advantages

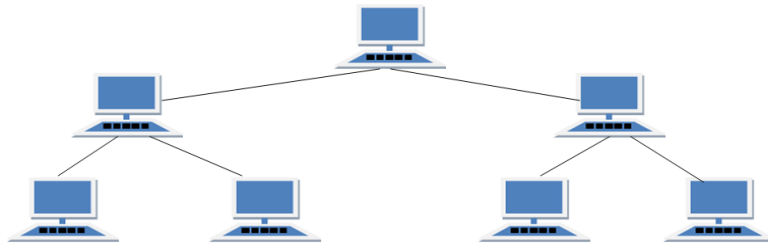
- If anyone connection is fails in the network, it will not affect the entire network. Only that connection or link affected.
- It is easy to identify the fault and fault isolation.
- Easy to expand the network in the star topology.
- No failure to the network when connecting or removing devices.
- It is very easy to manage because of its simplicity in the function.

Disadvantages

- In a star topology, if the central connecting device goes down, the entire network will fails.
- It requires more cable length compared to the linear bus topology.
- Star topology is more expensive than bus topology because of the connection ports like hub.

Tree Topology

The layout of the tree topology is beginning at the head end. These layouts have many branches and these are quite complex layouts in the topology. Any transmission from the device is going through the medium and it can receive by all other devices in the tree topology network. Tree Topology will give the expansion of the existing network.



Advantages

- Tree topology is well supported by the hardware and software vendors.
- Point to point wiring for each and every segments of the network.
- It is the best topology for the branched networks.

Disadvantages

- It is more expensive because more hubs are required to install the network.
- Tree topology is entirely depends upon the backbone line, if it fails then the entire network would fail.
- It is very difficult to configure and wire than other network topologies.
- In a tree topology, the length of network depends on the type of cable being used.

Mesh Topology

In a mesh topology, every device has connected to each other or a dedicated point to point link to every other device. (Dedicated term means that the traffic links only between the two devices it connects).

To find the number of physical links in a fully connected mesh network with n nodes, we first consider that each node must be connected to other node. Node 1 must be connected to $n-1$ nodes, node 2 must be connected to $n-1$ nodes, and finally node n must be connected $n-1$ nodes. If each physical link in the network can allow the communication in both directions, we can divide the number of links by 2. In other words we can say that in a mesh topology, we need $n(n-1)/2$.

Suppose if we are connecting 15 nodes in a mesh topology, then the number of cables required;

$$CN = n(n-1)/2 \quad \quad \quad CN = \text{Number of cables}$$

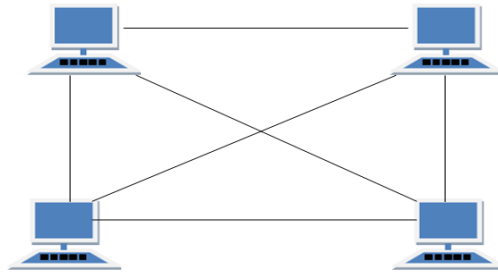
$$= 15(15 - 1)/2 \quad \quad \quad n = \text{Node}$$

$$= 15*14/2$$

$$= 15*7$$

= 105

Therefore, the total number of cables required for connecting 15 nodes = 105.



Advantages

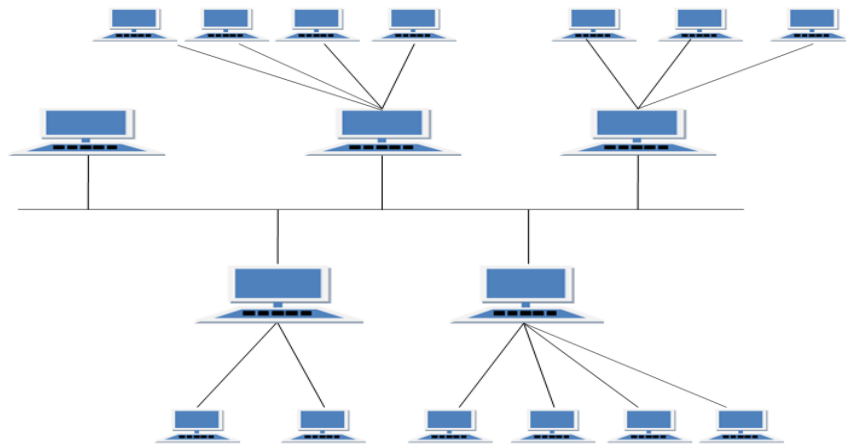
- There is no traffic problem because of the dedicated link in the mesh network.
- Mesh topology is very strong. If any link becomes not active it does not deactivate the entire system.
- Point-to-point links make full identification and fault isolation easy.
- Security or privacy for data travels along the dedicated line.
- Network can be expanded without any disruptions to the users.

Disadvantages

- Installation and reconnection are difficult.
- Mesh topology required more cabling and the number of input/output ports comparing with other network topologies.
- The hardware required to connect each link can be prohibitively expensive.

Hybrid Topology

It is two different types of topologies which is a mixture of two or more topologies. For example if in an office in one department ring topology is used and in another star topology is used, connecting these topologies will result in Hybrid Topology (ring topology and star topology).



Advantages

- Reliable as Error detecting and troubleshooting is easy.
- Effective.
- Scalable as size can be increased easily.
- Flexible.

Disadvantages

- Complex in design.
- Costly.

1.2.2 TYPES OF COMMUNICATION NETWORKS

Communication Networks can be of following 4 types:

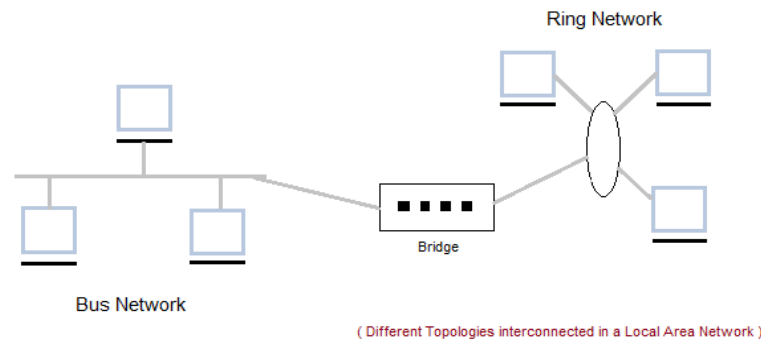
- Local Area Network (LAN)
- Metropolitan Area Network (MAN)
- Wide Area Network (WAN)
- Personal Area Network (PAN)

Local Area Network (LAN)

It is also called LAN and designed for small physical areas such as an office, group of buildings or a factory. LANs are used widely as it is easy to design and to troubleshoot. Personal computers and workstations are connected to each other through LANs. We can use different types of topologies through LAN, these are Star, Ring, Bus, Tree etc.

LAN can be a simple network like connecting two computers, to share files and network among each other while it can also be as complex as interconnecting an entire building.

LAN networks are also widely used to share resources like printers, shared hard-drive etc.



Characteristics of LAN

- LAN's are private networks, not subject to tariffs or other regulatory controls.
- LAN's operate at relatively high speed when compared to the typical WAN.
- There are different types of Media Access Control methods in a LAN, the prominent ones are Ethernet, Token ring.
- It connects computers in a single building, block or campus, i.e. they work in a restricted geographical area.

Applications

- One of the computer in a network can become a server serving all the remaining computers called clients. Software can be stored on the server and it can be used by the remaining clients.
- Connecting locally all the workstations in a building to let them communicate with each other locally without any internet access.
- Sharing common resources like printers etc. are some common applications of LAN.

Advantages

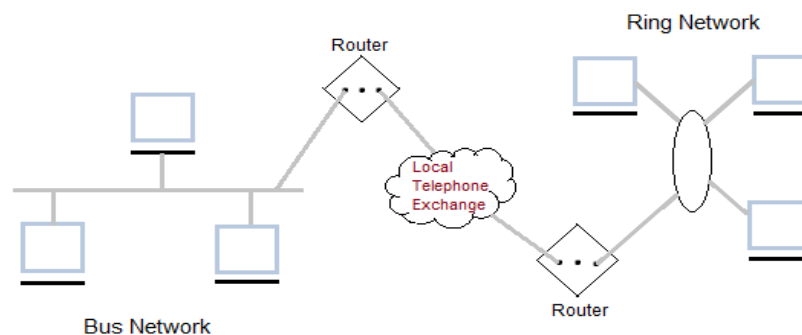
- 1. Resource Sharing:** Computer resources like printers, modems, DVD-ROM drives and hard disks can be shared with the help of local area networks. This reduces cost and hardware purchases.
- 2. Software Applications Sharing:** It is cheaper to use same software over network instead of purchasing separate licensed software for each client a network.
- 3. Easy and Cheap Communication:** Data and messages can easily be transferred over networked computers.
- 4. Centralized Data:** The data of all network users can be saved on hard disk of the server computer. This will help users to use any workstation in a network to access their data. Because data is not stored on workstations locally.
- 5. Data Security:** Since, data is stored on server computer centrally, it will be easy to manage data at only one place and the data will be more secure too.
- 6. Internet Sharing:** Local Area Network provides the facility to share a single internet connection among all the LAN users. In Net Cafes, single internet connection sharing system keeps the internet expenses cheaper.

Disadvantages

- 1. High Setup Cost:** Although the LAN will save cost over time due to shared computer resources, but the initial setup costs of installing Local Area Networks is high.
- 2. Privacy Violations:** The LAN administrator has the rights to check personal data files of each and every LAN user. Moreover he can check the internet history and computer use history of the LAN user.
- 3. Data Security Threat:** Unauthorized users can access important data of an organization if centralized data repository is not secured properly by the LAN administrator.
- 4. LAN Maintenance Job:** Local Area Network requires a LAN Administrator because, there are problems of software installations or hardware failures or cable disturbances in Local Area Network. A LAN Administrator is needed at this full time job.
- 5. Covers Limited Area:** Local Area Network covers a small area like one office, one building or a group of nearby buildings.

Metropolitan Area Network (MAN)

It was developed in 1980s. It is basically a bigger version of LAN. It is also called MAN and uses the similar technology as LAN. It is designed to extend over the entire city. It can be means to connecting a number of LANs into a larger network or it can be a single cable. It is mainly hold and operated by single private company or a public company.



Characteristics of MAN

It generally covers towns and cities (50 km)

Communication medium used for MAN are optical fibers, cables etc.

Advantages of MAN

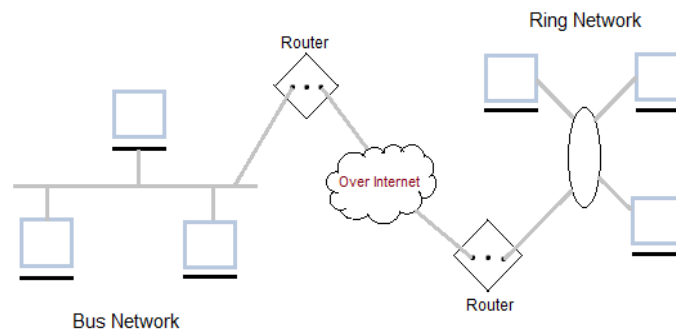
1. Extremely efficient and provide fast communication via high-speed carriers, such as fiber optic cables.
2. It provides a good back bone for large network and provides greater access to WANs. The dual bus used in MAN helps the transmission of data in both directions simultaneously.
3. A MAN usually encompasses several blocks of a city or an entire city.

Disadvantages of MAN

1. More cable required for a MAN connection from one place to another.
2. It is difficult to make the system secure from hackers and industrial espionage (spying) graphical regions.

Wide Area Network (WAN)

It is also called WAN. WAN can be private or it can be public leased network. It is used for the network that covers large distance such as cover states of a country. It is not easy to design and maintain. Communication medium used by WAN are PSTN or Satellite links. WAN operates on low data rates.



Characteristics

1. It generally covers large distances (states, countries, continents).
2. Communication medium used are satellite, public telephone networks which are connected by routers.

Advantages

1. It covers a large geographical area. Suppose if the branch of our office is in a different city then we can connect with them through WAN. The internet provides a leased line through which we can connect with another branch.
2. Shares software and resources with connecting workstations.
3. Messages can be sent very quickly to anyone else on the network. These messages can have picture, sounds or data included with them (called attachments).
4. Expensive things (such as printers or phone lines to the internet) can be shared by all the computers on the network without having to buy a different peripheral for each computer.

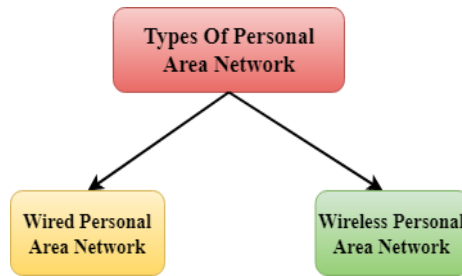
Disadvantages

1. Need a good firewall to restrict outsiders from entering and disrupting the network.
2. Setting up a network can be an expensive, slow and complicated. The bigger the network the more expensive it is.
3. Once set up, maintaining a network is a full-time job which requires network supervisors and technicians to be employed.
4. Security is a real issue when many different people have the ability to use information from other computers. Protection against hackers and viruses adds more complexity and expense.

Personal Area Network

- Personal Area Network is a network arranged within an individual person, typically within a range of 10 meters.
- Personal Area Network is used for connecting the computer devices of personal use is known as Personal Area Network.
- Personal Area Network covers an area of **30 feet**.

- Personal computer devices that are used to develop the personal area network are the laptop, mobile phones, media player and play stations.



Wireless Personal Area Network: Wireless Personal Area Network is developed by simply using wireless technologies such as WiFi, Bluetooth. It is a low range network.

Wired Personal Area Network: Wired Personal Area Network is created by using the USB.

1.3 NEED FOR PROTOCOL ARCHITECTURE

When computers, terminals and other data processing devices exchange data, the procedures involved can be quite complex. Consider for example, the transfer of a file between two computers. There must be a data path between the two computers, either directly or via a communication network.

Typical task to be performed are as follows-

- The source system must either activate the direct data communication path or inform the communication network of the identity of the desired destination system.
- The source system must ascertain that the destination system is prepared to receive data.
- The file transfer application on the source system must ascertain that the file management program on the destination system is prepared to accept and store the file for this particular user.
- If the file formats used on the two systems are different, one or the other system must perform a format translation function.

Instead of implementing the logic for this as a single module, the task is broken up into subtasks, each of which is implemented separately. In a protocol architecture, the modules are arranged in a vertical stack. Each layer in the stack performs a related subset of the functions required to communicate with another system.

It takes two to communicate so the same set of layered functions must exist in two systems. Communication is achieved by having the corresponding, or peer, layers in two systems communicate. The peer layers communicate by means of formatted blocks of data that obey a set of rules known as a protocol.

The key features of a protocol are as follows-

- **Syntax:** – Syntax refers to the structure or format of the data, meaning the order in which they are presented.
- **Semantics:** – Semantics refer to the meaning of each section of bits. How is a particular pattern to be interpreted, and what action is to be taken based on that interpretation?
- **Timing:** – Timing refers to two characteristics: when data should be sent and how fast they can be sent.

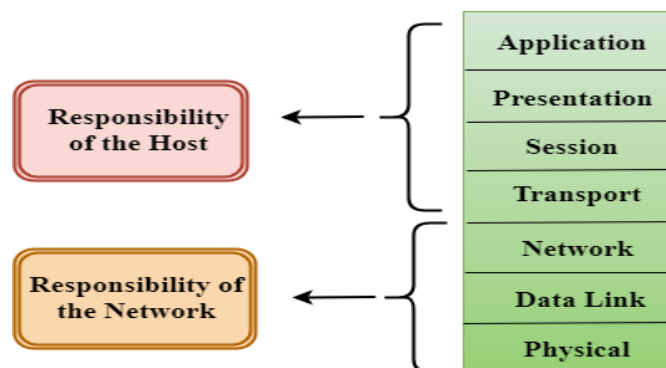
1.4 STANDARDIZED PROTOCOL ARCHITECTURES

- Required for devices to communicate
- Vendors have more marketable products
- Customers can insist on standards based equipment
- Two standards:-
 - ✓ OSI Reference model
 - ✓ TCP/IP protocol suite

1.4.1 OSI Model

- OSI stands for **Open System Interconnection** is a reference model that describes how information from a software application in one computer moves through a physical medium to the software application in another computer.
- OSI consists of seven layers, and each layer performs a particular network function.
- OSI model was developed by the International Organization for Standardization (ISO) in 1984, and it is now considered as an architectural model for the inter-computer communications.
- OSI model divides the whole task into seven smaller and manageable tasks. Each layer is assigned a particular task.
- Each layer is self-contained, so that task assigned to each layer can be performed independently.

Characteristics of OSI Model:



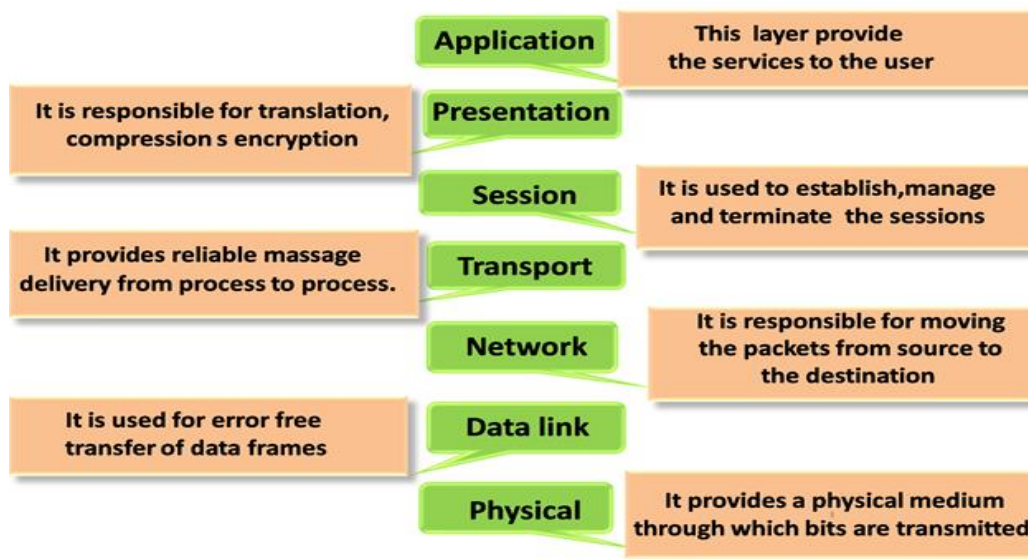
- The OSI model is divided into two layers: upper layers and lower layers.
- The upper layer of the OSI model mainly deals with the application related issues, and they are implemented only in the software.

- The lower layer of the OSI model deals with the data transport issues. The data link layer and the physical layer are implemented in hardware and software. The physical layer is the lowest layer of the OSI model and is closest to the physical medium. The physical layer is mainly responsible for placing the information on the physical medium.

Functions of the OSI Layers

There are the seven OSI layers. Each layer has different functions. A list of seven layers are given below:

1. Physical Layer
2. Data-Link Layer
3. Network Layer
4. Transport Layer
5. Session Layer
6. Presentation Layer
7. Application Layer



Physical layer

- The main functionality of the physical layer is to transmit the individual bits from one node to another node.
- It is the lowest layer of the OSI model.
- It establishes, maintains and deactivates the physical connection.

Functions of a Physical layer:

- **Line Configuration:** It defines the way how two or more devices can be connected physically.
- **Data Transmission:** It defines the transmission mode whether it is simplex, half-duplex or full-duplex mode between the two devices on the network.
- **Topology:** It defines the way how network devices are arranged.
- **Signals:** It determines the type of the signal used for transmitting the information.

Data-Link Layer

- This layer is responsible for the error-free transfer of data frames.
- It defines the format of the data on the network.
- It provides a reliable and efficient communication between two or more devices.
- It is mainly responsible for the unique identification of each device that resides on a local network.
- It contains two sub-layers:
 - **Logical Link Control Layer**
 - It is responsible for transferring the packets to the Network layer of the receiver that is receiving.
 - It identifies the address of the network layer protocol from the header.
 - It also provides flow control.
 - **Media Access Control Layer**
 - A Media access control layer is a link between the Logical Link Control layer and the network's physical layer.
 - It is used for transferring the packets over the network.

Functions of the Data-link layer

- **Framing:** The data link layer translates the physical's raw bit stream into packets known as Frames. The Data link layer adds the header and trailer to the frame. The header which is added to the frame contains the hardware destination and source address.



- **Physical Addressing:** The Data link layer adds a header to the frame that contains a destination address. The frame is transmitted to the destination address mentioned in the header.
- **Flow Control:** Flow control is the main functionality of the Data-link layer. It is the technique through which the constant data rate is maintained on both the sides so that no data get corrupted. It ensures that the transmitting station such as a server with higher processing speed does not exceed the receiving station, with lower processing speed.
- **Error Control:** Error control is achieved by adding a calculated value CRC (Cyclic Redundancy Check) that is placed to the Data link layer's trailer which is added to the message frame before it is sent to the physical layer. If any error seems to occur, then the receiver sends the acknowledgment for the retransmission of the corrupted frames.
- **Access Control:** When two or more devices are connected to the same communication channel, then the data link layer protocols are used to determine which device has control over the link at a given time.

Network Layer

- It is a layer 3 of OSI model. It works for the transmission of data from one node to the other located in different networks.
- It takes care of packet routing i.e, selection of the shortest path to transmit the packet, from the number of routers available.
- The sender and receiver's IP address are placed in the header of the packet.

Functions of Network Layer:

- **Logical Addressing:** in order to identify each device, network layer defines an addressing scheme. The sender and receiver's IP address are placed in the header by network layer. Such an address distinguishes each device uniquely and universally.
- **Routing:** Routing is the major component of the network layer, and it determines the best optimal path out of the multiple paths from source to the destination.
- **Packetizing:** A Network Layer receives the packets from the upper layer and converts them into packets. This process is known as Packetizing. It is achieved by internet protocol (IP).

Transport Layer

- The Transport layer is a Layer 4 ensures that messages are transmitted in the order in which they are sent and there is no duplication of data.
- The main responsibility of the transport layer is to transfer the data completely.

Functions of Transport Layer:

- **Service-point addressing:** The transport layer adds the header that contains the address known as a service-point address or port address. The responsibility of the network layer is to transmit the data from one computer to another computer and the responsibility of the transport layer is to transmit the message to the correct process.
- **Segmentation and reassembly:** When the transport layer receives the message from the upper layer, it divides the message into multiple segments, and each segment is assigned with a sequence number that uniquely identifies each segment. When the message has arrived at the destination, then the transport layer reassembles the message based on their sequence numbers.
- **Connection control:** Transport layer provides two services i.e, Connection-oriented service and connectionless service. A connectionless service treats each segment as an individual packet, and they all travel in different routes to reach the destination. A connection-oriented service makes a connection with the transport layer at the destination machine before delivering the packets. In connection-oriented service, all the packets travel in the single route.
- **Flow control:** The transport layer also responsible for flow control but it is performed end-to-end rather than across a single link.
- **Error control:** The transport layer is also responsible for Error control. Error control is performed end-to-end rather than across the single link. The sender transport layer ensures that message reach at the destination without any error.

Session Layer

The session layer is a Layer 5 responsible for establishment of connection, maintenance of sessions, authentication and also ensures security. The layer allows the two processes to establish, use and terminate a connection.

Functions of Session layer:

- **Dialog control:** The session layer allows two systems to start communication with each other in half duplex or full duplex.
- **Synchronization:** Session layer adds some checkpoints when transmitting the data in a sequence. If some error occurs in the middle of the transmission of data, then the transmission will take place again from the checkpoint. This process is known as Synchronization and recovery.

Presentation Layer

The presentation layer is a Layer 6 of OSI model. The processes in two systems exchange the information in the form of character strings, numbers and so on.

Functions of Presentation layer:

- **Translation:** The processes in two systems exchange the information in the form of character strings, numbers and so on. It converts the data from sender-dependent format into a common format and changes the common format into receiver-dependent format at the receiving end.
- **Encryption:** Encryption is needed to maintain privacy. Encryption is a process of converting the sender-transmitted information into another form and sends the resulting message over the network.
- **Compression:** Data compression is a process of compressing the data, i.e., it reduces the number of bits to be transmitted. Data compression is very important in multimedia such as text, audio, video.

Application Layer

The application layer is a Layer 7 of OSI model. Application layer is implemented by the network applications. These applications produce the data, which has to be transferred over the network.

Examples of applications-Browsers, Messengers etc.

Functions of Application layer:

- **File transfer, access, and management (FTAM):** An application layer allows a user to access the files in a remote computer, to retrieve the files from a computer and to manage the files in a remote computer.
- **Mail services:** An application layer provides the facility for email forwarding and storage.

1.4.2 TCP/IP-

TCP/IP model

- The TCP/IP model is not exactly similar to the OSI model.
- The TCP/IP model consists of four layers: the application layer, transport layer, internet layer, network access layer (combination of data link layer and physical layer).
- The first three layers provide physical standards, network interface, internetworking, and transport functions that correspond to the first four layers of the OSI model.
- The last three layers are represented in TCP/IP model by a single layer called the application layer.
- TCP/IP is a hierarchical protocol made up of interactive modules, and each of them provides specific functionality.

Here, hierarchical means that each upper-layer protocol is supported by two or more lower-level protocols.

Functions of TCP/IP layers:

TCP/IP MODEL
Application Layer
Transport Layer
Internet Layer
Network Access Layer

OSI MODEL
Application Layer
Presentation Layer
Session Layer
Transport Layer
Network Layer
Data Link Layer
Physical Layer

Network Access Layer

- A network layer is the lowest layer of the TCP/IP model.
- A network layer is the combination of the Physical layer and Data Link layer defined in the OSI reference model.
- It defines how the data should be sent physically through the network.
- This layer is mainly responsible for the transmission of the data between two devices on the same network.
- The functions carried out by this layer are encapsulating the IP datagram into frames transmitted by the network and mapping of IP addresses into physical addresses.
- The protocols used by this layer are Ethernet, token ring, FDDI, X.25, frame relay.

Internet Layer

- An internet layer is the second layer of the TCP/IP model.
- An internet layer is also known as the network layer.
- The main responsibility of the internet layer is to send the packets from any network, and they arrive at the destination irrespective of the route they take.

Following are the protocols used in this layer are:

IP Protocol: IP protocol is used in this layer, and it is the most significant part of the entire TCP/IP suite.

Following are the responsibilities of this protocol:

- **IP Addressing:** This protocol implements logical host addresses known as IP addresses. The IP addresses are used by the internet and higher layers to identify the device and to provide internetwork routing.
- **Host-to-host communication:** It determines the path through which the data is to be transmitted.
- **Data Encapsulation and Formatting:** An IP protocol accepts the data from the transport layer protocol. An IP protocol ensures that the data is sent and received securely, it encapsulates the data into message known as IP datagram.
- **Fragmentation and Reassembly:** The limit imposed on the size of the IP datagram by data link layer protocol is known as Maximum Transmission unit (MTU). If the size of IP datagram is greater than the MTU unit, then the IP protocol splits the datagram into smaller units so that they can travel over the local network. Fragmentation can be done by the sender or intermediate router. At the receiver side, all the fragments are reassembled to form an original message.
- **Routing:** When IP datagram is sent over the same local network such as LAN, MAN, WAN, it is known as direct delivery. When source and destination are on the distant network, then the IP datagram is sent indirectly. This can be accomplished by routing the IP datagram through various devices such as routers.

ARP Protocol

- ARP stands for **Address Resolution Protocol**.
- ARP is a network layer protocol which is used to find the physical address from the IP address.
- **The two terms are mainly associated with the ARP Protocol:**
 - **ARP request:** When a sender wants to know the physical address of the device, it broadcasts the ARP request to the network.
 - **ARP reply:** Every device attached to the network will accept the ARP request and process the request, but only recipient recognize the IP address and sends back its physical address in the form of ARP reply. The recipient adds the physical address both to its cache memory and to the datagram header

ICMP Protocol

- **ICMP** stands for Internet Control Message Protocol.
- It is a mechanism used by the hosts or routers to send notifications regarding datagram problems back to the sender.
- A datagram travels from router-to-router until it reaches its destination. If a router is unable to route the data because of some unusual conditions such as disabled links, a device is on fire or network congestion, then the ICMP protocol is used to inform the sender that the datagram is undeliverable.

- The core responsibility of the ICMP protocol is to report the problems, not correct them. The responsibility of the correction lies with the sender.
- ICMP can send the messages only to the source, but not to the intermediate routers because the IP datagram carries the addresses of the source and destination but not of the router that it is passed to.

Transport Layer

The transport layer is responsible for the reliability, flow control, and correction of data which is being sent over the network.

The two protocols used in the transport layer are **User Datagram protocol and Transmission control protocol.**

- **User Datagram Protocol (UDP)**
 - It provides connectionless service and end-to-end delivery of transmission.
 - It is an unreliable protocol as it discovers the errors but not specify the error.
 - User Datagram Protocol discovers the error, and ICMP protocol reports the error to the sender that user datagram has been damaged.
- **Transmission Control Protocol (TCP)**
 - It provides a full transport layer services to applications.
 - It creates a virtual circuit between the sender and receiver, and it is active for the duration of the transmission.
 - TCP is a reliable protocol as it detects the error and retransmits the damaged frames. Therefore, it ensures all the segments must be received and acknowledged before the transmission is considered to be completed and a virtual circuit is discarded.
 - At the sending end, TCP divides the whole message into smaller units known as segment, and each segment contains a sequence number which is required for reordering the frames to form an original message.
 - At the receiving end, TCP collects all the segments and reorders them based on sequence numbers.

Application Layer

- An application layer is the topmost layer in the TCP/IP model.
- This layer allows the user to interact with the application.
- When one application layer protocol wants to communicate with another application layer, it forwards its data to the transport layer.

Following are the main protocols used in the application layer:

- **HTTP:** HTTP stands for Hypertext transfer protocol. This protocol allows us to access the data over the World Wide Web.
- **SNMP:** SNMP stands for Simple Network Management Protocol. It is a framework used for managing the devices on the internet by using the TCP/IP protocol suite.
- **SMTP:** SMTP stands for Simple mail transfer protocol. The TCP/IP protocol that supports the e-mail is known as a Simple mail transfer protocol. This protocol is used to send the data to another e-mail address.
- **DNS:** DNS stands for Domain Name System. An IP address is used to identify the connection of a host to the internet uniquely. But, people prefer to use the names instead of addresses. Therefore, the system that maps the name to the address is known as Domain Name System.
- **TELNET:** It is an abbreviation for Terminal Network. It establishes the connection between the local computer and remote computer in such a way that the local terminal appears to be a terminal at the remote system.
- **FTP:** FTP stands for File Transfer Protocol. FTP is a standard internet protocol used for transmitting the files from one computer to another computer.

UNIT-2: DATA TRANSMISSION & MEDIA

2.1 CONCEPTS AND TERMINOLOGY

Transmission Terminology-

Guided media- In guided media, the waves are guided along a physical path, examples of guided media are twisted pair, coaxial cable and optical fiber.

Unguided media- Unguided media also called wireless, provide means for transmitting electromagnetic waves but do not guide them.

Point to Point- A guided transmission medium is point to point if it provides a direct link between two devices and those are the only two devices sharing the medium.

Multipoint- A guided transmission medium is multipoint if more than two devices share the same medium.

Simplex- In simplex transmission signals are transmitted in only one direction. One transmitter and the other is receiver.

Half duplex- In half duplex operation both station may transmit or receive, but only one at a time.

Full duplex- In full duplex operation both stations may transmit simultaneously.

Signals can be described- a) in the time domain, b) in the frequency domain

Time domain concepts-

An **analog signal** is one in which the signal intensity varies in a smooth fashion over time. In other words there are no breaks or discontinuities in the signal.

A **digital signal** is one in which the signal intensity maintains a constant level for some period of time and then abruptly changes to another constant level.

Periodic signal is a signal in which the same signal pattern repeats over time.

Mathematically, a signal $S(t)$ is defined to be periodic if and only if

$$S(t+T) = S(t) \quad -\infty < t < +\infty$$

Where the constant T is the period of the signal otherwise, a signal is **aperiodic**.

Frequency domain concepts

Spectrum- The spectrum of a signal is the range of frequencies that it contains.

Absolute Bandwidth- The absolute bandwidth of a signal is the width of the spectrum.

Effective Bandwidth- The band of frequencies which contains most of the energy of the signal.

DC component- If a signal includes a component of zero frequency, that component is a direct current or constant component.

Relationship between data rate and bandwidth-

- Consider the case binary data is encoded into digital signal, and to be transmitted by a transmission medium.
- Digital signal contains an infinite bandwidth but a real transmission medium has a finite bandwidth, which can limit the data rate that can be carried on the transmission medium.
- Limited bandwidth creates distortions of the input signal, which makes the task of interpreting the received signal more difficult.
- The more limited bandwidth, the greater the distortion and the greater the potential for error by the receiver.
- The higher the data rate of a signal, the greater is its effective bandwidth.
- The greater the bandwidth of a transmission system, the higher is the data rate that can be transmitted.

ANALOG AND DIGITAL DATA

Analog data take on continuous values in some interval. For example, voice and video are continuously varying patterns of intensity. Most data collected by sensors, such as temperature and pressure, are continuous valued.

Digital data take on discrete values; examples are text and integers. The most familiar example of analog data is audio, which, in the form of acoustic sound waves, can be perceived directly by human beings

Another common example of analog data is video. Here it is easier to characterize the data in terms of the TV screen (destination) rather than the original scene (source) recorded by the TV camera. To produce a picture on the screen, an electron beam scans across the surface of the screen from left to right and top to bottom. For black-and-white television, the amount of illumination produced (on a scale from black to white) at any point is proportional to the intensity of the beam as it passes that point. Thus at any instant in time the beam takes on an analog value of intensity to produce the desired brightness at that point on the screen.

Analog and Digital Signals

In a communications system, data are propagated from one point to another by means of electromagnetic signals.

An analog signal is a continuously varying electromagnetic wave that may be propagated over a variety of media, depending on spectrum; examples are wire media, such as twisted pair and coaxial cable; fiber optic cable; and unguided media, such as atmosphere or space propagation.

A digital signal is a sequence of voltage pulses that may be transmitted over a wire medium; for example, a constant positive voltage level may represent binary 0 and a constant negative voltage level may represent binary 1. The principal advantages of digital signaling are that it is generally cheaper than analog signaling and is less susceptible to noise

interference. The principal disadvantage is that digital signals suffer more from attenuation than do analog signals.

Data and Signals

Analog signals used to represent analog data and digital signals used to represent digital data. Generally, analog data are a function of time and occupy a limited frequency spectrum; such data can be represented by an electromagnetic signal occupying the same spectrum. Digital data can be represented by digital signals, with a different voltage level for each of the two binary digits.

Digital data can also be represented by analog signals by use of a modem (modulator/demodulator). The modem converts a series of binary (two-valued) voltage pulses into an analog signal by encoding the digital data onto a carrier frequency. The resulting signal occupies a certain spectrum of frequency centered about the carrier and may be propagated across a medium suitable for that carrier. The most common modems represent digital data in the voice spectrum and hence allow those data to be propagated over ordinary voice-grade telephone lines.

At the other end of the line, another modem demodulates the signal to recover the original data. In an operation very similar to that performed by a modem, analog data can be represented by digital signals. The device that performs this function for voice data is a codec (coder-decoder). In essence, the codec takes an analog signal that directly represents the voice data and approximates that signal by a bit stream. At the receiving end, the bit stream is used to reconstruct the analog data.

2.2 ANALOG AND DIGITAL TRANSMISSION

Both analog and digital signals may be transmitted on suitable transmission media.

Analog transmission is a means of transmitting analog signals without regard to their content; the signals may represent analog data (e.g., voice) or digital data (e.g., binary data that pass through a modem). In either case, the analog signal will become weaker (attenuate) after a certain distance. To achieve longer distances, the analog transmission system includes amplifiers that boost the energy in the signal. Unfortunately, the amplifier also boosts the noise components. With amplifiers cascaded to achieve long distances, the signal becomes more and more distorted. For analog data, such as voice, quite a bit of distortion can be tolerated and the data remain intelligible. However, for digital data, cascaded amplifiers will introduce errors.

Digital transmission, in contrast, assumes a binary content to the signal. A digital signal can be transmitted only a limited distance before attenuation, noise, and other impairments endanger the integrity of the data. To achieve greater distances, repeaters are used. A repeater receives the digital signal, recovers the pattern of 1s and 0s, and retransmits a new signal. Thus the attenuation is overcome.

2.3 TRANSMISSION IMPAIRMENT

In the data communication system, analog and digital signals go through the transmission medium. Transmission media are not ideal. There are some imperfections in transmission mediums. So, the signals sent through the transmission medium are also not perfect. This imperfection cause **signal impairment**.

It means that signals that are transmitted at the beginning of the medium are not the same as the signals that are received at the end of the medium that is what is sent is not what is received. These impairments tend to deteriorate the quality of analog and digital signals.

Consequences

1. For a digital signal, there may occur bit errors.
2. For analog signals, these impairments degrade the quality of the signals.

Causes of impairment

There are three main causes of impairment are,

1. Attenuation
2. Distortion
3. Noise

1) Attenuation

- The strength of a signal falls off with distance over any transmission medium. For guided medium, this reduction in strength or attenuation is generally exponential and thus expressed as a constant number of decibels per unit distance.
- For unguided medium, attenuation is a complex function of distance.
- Attenuation introduces three considerations for the transmission engineer-
 - A received signal must have sufficient strength so that the electronic circuitry in the receiver can detect the signal.
 - The signal must maintain a level sufficiently higher than noise to be received without error.
 - Attenuation varies with frequency.

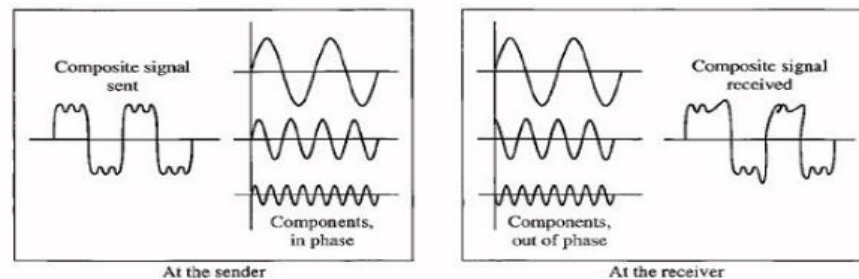
The first and second problems are dealt with by attention to signal strength and the use of amplifiers or repeaters.

The third problem is noticeable for analog signals. Because the attenuation varies as a function of frequency. To overcome this problem, techniques are available for equalizing attenuation across a band of frequencies. This is commonly done for voice grade telephone lines by using loading coils.

2) Distortion

If a signal changes its form or shape, it is referred to as distortion. Signals made up of different frequencies are composite signals. Distortion occurs in these composite signals.

- Each component of frequency has its propagation speed traveling through a medium and therefore, different components have different delay in arriving at the final destination.
- It means that signals have different phases at the receiver than they did at the source.
- This figure shows the effect of distortion on a composite signal:



Distortion

3) Noise

Noise is another problem. There are some random or unwanted signals mix up with the original signal is called noise. Noises can corrupt the signals in many ways along with the distortion introduced by the transmission media.

Different types of noises are:

- a. Thermal noise
- b. Intermodulation noise
- c. Crosstalk
- d. Impulse noise

a) Thermal noise

The thermal noise is random motion of electrons in a conductor that creates an extra signal not originally sent by the transmitter.

It is also known as white noise because it is distributed across the entire spectrum (as the frequency encompass over a broad range of frequencies).

b) Intermodulation noise

When more than one signal share a single transmission channel, intermodulation noise is generated.

For instance, two signals S1 and S2 will generate signals of frequencies (S1 + S2) and (s1 - S2), which may interfere with the signals of the same frequencies sent by the sender. Due to If nonlinearity present in any part of the communication system, intermodulation noise is introduced.

c) Cross talk

crosstalk is any phenomenon by which a signal transmitted on one circuit or channel of a transmission system creates an undesired effect in another circuit or channel..

Just like in telephone system, it is a common experience to hear conversation of other people in the background. This is known as cross talk.

d) Impulse noise

Impulse noise is irregular pulses or spikes(a signal with high energy in a very short period) generated by phenomena like that comes from power lines, lightning, spark due to loose contact in electric circuits and so on.

It is a primary source of bit-errors in digital data communication that kind of noise introduces burst errors.

2.4 CHANNEL CAPACITY-

The maximum rate at which data can be transmitted over a given communication path, or channel, under given conditions, is referred to as the channel capacity. There are four concepts here that we are trying to relate to one another.

- **Data rate:** The rate, in bits per second (bps), at which data can be communicated.
- **Bandwidth:** The bandwidth of the transmitted signal as constrained by the transmitter and the nature of the transmission medium, expressed in cycles per second, or Hertz
- **Noise:** The average level of noise over the communications path
- **Error rate:** The rate at which errors occur, where an error is the reception of a 1 when a 0 was transmitted or the reception of a 0 when a 1 was transmitted.

The problem we are addressing is this: Communications facilities are expensive and, in general, the greater the bandwidth of a facility, the greater the cost. Furthermore, all transmission channels of any practical interest are of limited bandwidth. The limitations arise from the physical properties of the transmission medium or from deliberate limitations at the transmitter on the bandwidth to prevent interference from other sources. Accordingly, we would like to make as efficient use as possible of a given bandwidth. For digital data, this means that we would like to get as high a data rate as possible at a particular limit of error rate for a given bandwidth. The main constraint on achieving this efficiency is noise.

Nyquist Bandwidth-

Nyquist states that if the rate of signal transmission is 2B, then a signal with frequencies not greater than B is sufficient to carry the signal rate.

$$C = 2B \log_2 M$$

Where M is the number of discrete signal or voltage levels.

Shannon Capacity Formula-

Nyquist formula indicates that doubling the bandwidth doubles the data rate. The presence of noise can corrupt one or more bits.

The signal-to noise ratio is important in the transmission of digital data. Shannon's result is that the maximum channel capacity in bits per second.

$$C = B \log_2 (1 + \text{SNR})$$

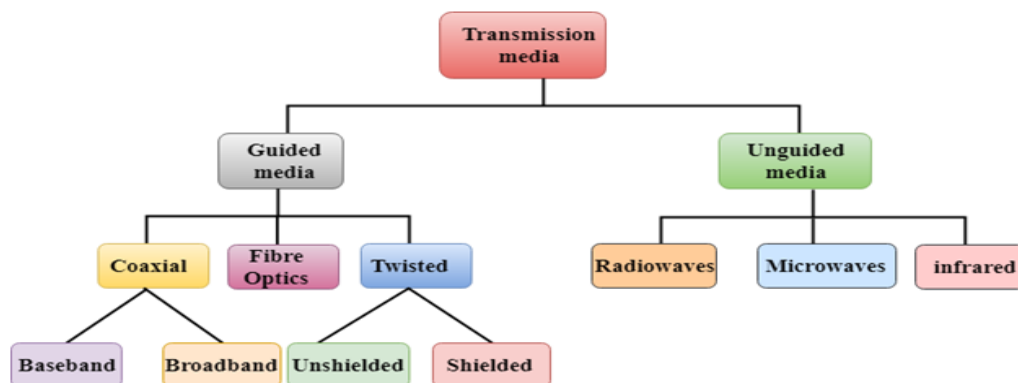
Where C is the capacity of the channel in bits per second and B is the bandwidth of the channel in Hertz.

$$\text{SNR}_{db} = 10 \log_{10} (\text{signal power} / \text{noise power})$$

2.5 TRANSMISSION MEDIA-

In data communication terminology, a transmission medium is a physical path between the transmitter and the receiver i.e it is the channel through which data is sent from one place to another.

Classification of Transmission Media:



2.5.1 GUIDED MEDIA

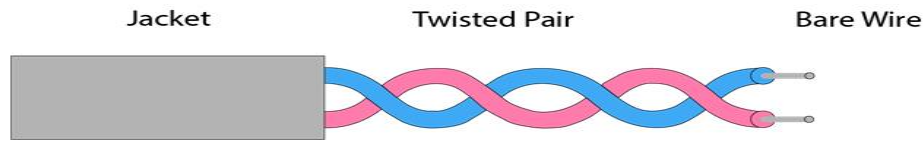
It is defined as the physical medium through which the signals are transmitted. It is also known as Bounded media.

Types of Guided media:

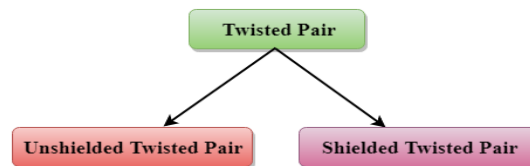
1. TWISTED PAIR:

- Twisted pair is a physical media made up of a pair of cables twisted with each other.
- A twisted pair cable is cheap as compared to other transmission media.
- Installation of the twisted pair cable is easy, and it is a lightweight cable.
- The frequency range for twisted pair cable is from 0 to 3.5KHz.
- A twisted pair consists of two insulated copper wires arranged in a regular spiral pattern.

- One of the wires is used to carry signals to the receiver and other is used only as a ground reference. The receiver uses the difference between the two.



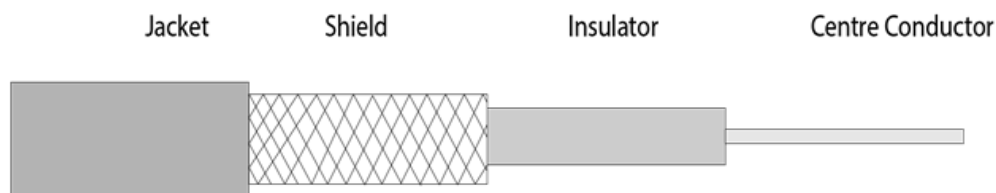
Types of Twisted pair:



- Twisted pair cables are used in telephone lines to provide voice and data channels.
- Shielded twisted pair has a metal casing. It improves the quality of cable by preventing the penetration of noise or cross talk. It is bulkier and more expensive.

2. COAXIAL CABLE

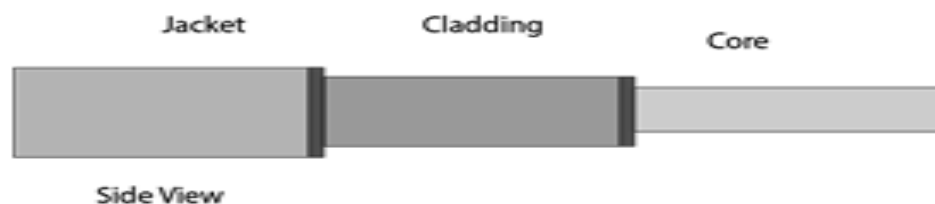
- Coaxial cable carries signals of higher frequency ranges than those in twisted pair cable.
- Coaxial cable has a central core conductor of solid or stranded wire enclosed in an insulating sheath, which is encased in an outer conductor of metal foil.
- The outer metallic wrapping serves both as a shield against noise and as the second conductor, which completes the circuit.
- This outer conductor is also enclosed in an insulating sheath and the whole cable is protected by a plastic cover.



Coaxial cable is of two types:

1. **Baseband transmission:** It is defined as the process of transmitting a single signal at high speed.
2. **Broadband transmission:** It is defined as the process of transmitting multiple signals simultaneously.
 - Coaxial cable was widely used in analog telephone networks where a single coaxial network could carry 10,000 voice signals.
 - Cable TV also use coaxial cables and it is also used in LANs.
3. **FIBRE OPTIC**
 - A fiber optic cable is made of glass or plastic and transmits signals in form of light.
 - A glass or plastic core is surrounded by a cladding of less dense glass or plastic. A protective coating given on the cladding consisting of plastic is known as a jacket.
 - Fiber optics provide faster data transmission than copper wires.

Diagrammatic representation of fiber optic cable:



- It supports two modes for propagating light along optical channels i.e, Single mode and multi-mode.
- Single mode is so named because single beam from a light source move through the core.
- Multimode is so named because multiple beams from a light source move through the core in different paths.

Advantages of fiber optic cable over copper:

- **Greater Bandwidth:** The fiber optic cable provides more bandwidth as compared copper. Therefore, the fiber optic carries more data as compared to copper cable.
- **Faster speed:** fiber optic cable carries the data in the form of light. This allows the fiber optic cable to carry the signals at a higher speed.
- **Longer distances:** The fiber optic cable carries the data at a longer distance as compared to copper cable.
- **Better reliability:** The fiber optic cable is more reliable than the copper cable as it is immune to any temperature changes while it can cause obstruct in the connectivity of copper cable.
- **Thinner and sturdier:** fiber optic cable is thinner and lighter in weight so it can withstand more pull pressure than copper cable.

Disadvantages-

- Installation and maintenance is difficult.
- Cost is high.

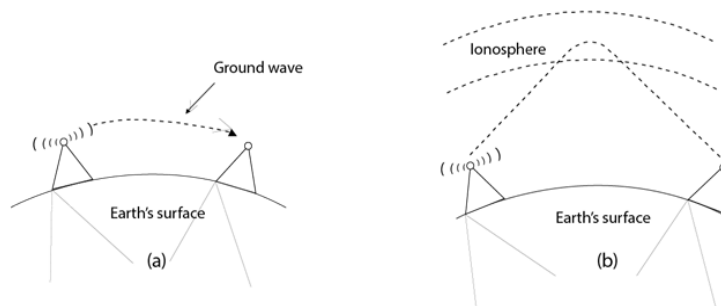
2.5.2 UNGUIDED TRANSMISSION

- An unguided transmission transmits the electromagnetic waves without using any physical medium. Therefore it is also known as **wireless transmission**.
- In unguided media, air is the media through which the electromagnetic energy can flow easily.

Unguided transmission is broadly classified into three categories:

1. Radio waves

- Radio waves are the electromagnetic waves that are transmitted in all the directions of free space.
- Radio waves are omnidirectional, i.e., the signals are propagated in all the directions.
- The range in frequencies of radio waves is from 3 KHz to 1 GHz.
- In the case of radio waves, the sending and receiving antenna are not aligned, i.e., the wave sent by the sending antenna can be received by any receiving antenna.
- Radio waves can penetrate walls. It is an advantage because an AM radio can receive signal inside a building.



Applications:

- A Radio wave is useful for multicasting when there is one sender and many receivers.
- An FM radio, television, cordless phones are examples of a radio wave.

2. Microwaves-

- Electromagnetic waves having frequencies between 1 and 300 GHz are called microwaves.
- Microwaves are unidirectional. When an antenna transmits microwaves, they can be narrowly focused. This means that the sending and receiving antenna need to be aligned.

- Microwave propagation is line of sight. Since the towers with the mounted antenna need to be in direct sight of each other. Repeaters are often needed for long distance communication.
- Very high frequency microwaves cannot penetrate walls. This characteristic can be a disadvantage of receivers that are inside buildings.
- Two types of antennas are used for microwave communications i.e, the Parabolic dish and the horn.
- Applications-
Microwaves due to their unidirectional properties are very useful when unicast communication is needed between the sender and receiver.

3. Infrared

- An infrared transmission is a wireless technology used for communication over short ranges.
- The frequency of the infrared is in the range from 300 GHz to 400 THz.
- It is used for short-range communication such as data transfer between two cell phones, TV remote operation, data transfer between a computer and cell phone resides in the same closed area.

Characteristics of Infrared:

- It supports high bandwidth, and hence the data rate will be very high.
- Infrared waves cannot penetrate the walls. Therefore, the infrared communication in one room cannot be interrupted by the nearby rooms.
- An infrared communication provides better security with minimum interference.
- Infrared communication is unreliable outside the building because the sun rays will interfere with the infrared waves.

UNIT- 3: DATA ENCODING

3.1 DATA ENCODING-

Encoding is the process of converting the data or a given sequence of characters, symbols, alphabets etc. into a specified format, for the secured transmission of data.

The data encoding technique is divided into the following types, depending upon the type of data conversion.

- Digital data to digital signal
- Analog data to digital signal
- Digital data to analog signal
- Analog data to analog signal

Digital data to digital signal-

The simplest form of digital encoding of digital data is to assign one voltage level to binary one and another to binary zero. It is less complex and less expensive than digital to analog modulation equipment.

Analog data to digital signal-

Analog data such as voice and video, are often digitized to be able to use digital transmission facilities. The simplest technique is PCM, which involves sampling the analog data and quantizing the samples.

Digital data to analog signal-

A modem converts digital data to an analog signal so that it can be transmitted over an analog line. Some transmission media such as optical fiber and unguided media will only propagate analog signals.

Analog data to analog signal-

Analog data are modulated by a carrier frequency to produce an analog signal in a different frequency band, which can be utilized on an analog transmission system.

3.2 DIGITAL DATA TO DIGITAL SIGNAL-

To convert digital data into digital signals it can be done in two ways, line coding and block coding. For all communications, line coding is necessary whereas block coding is optional.

3.2.1 LINE CODING-

line coding schemes divided into five categories:

1. Unipolar (eg. NRZ scheme).
2. Polar (eg. NRZ-L, NRZ-I, RZ, and Biphase – Manchester and differential Manchester).
3. Bipolar (eg. AMI and Pseudo ternary).
4. Multilevel
5. Multitransition

But, before learning difference between first three schemes we should first know the **characteristic** of these line coding techniques:

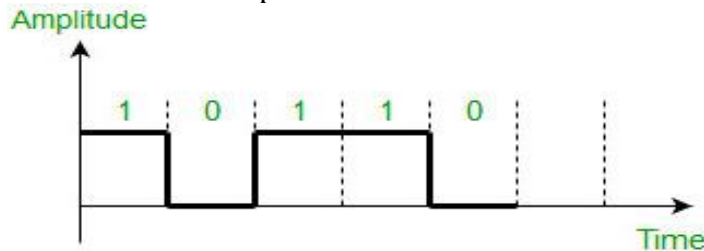
- There should be **self-synchronizing** i.e., both receiver and sender clock should be synchronized.
- There should have some error-detecting capability.
- There should be immunity to noise and interference.
- There should be less complexity.
- There should be no low frequency component (**DC-component**) as long distance transfer is not feasible for low frequency component signal.
- There should be less base line wandering.

Unipolar scheme –

In this scheme, all the signal levels are either above or below the axis.

- **Non return to zero (NRZ) –**

It is unipolar line coding scheme in which positive voltage defines bit 1 and the zero voltage defines bit 0. Signal does not return to zero at the middle of the bit thus it is called NRZ. For example: Data = 10110.



But this scheme uses more power as compared to polar scheme to send one bit per unit line resistance. Moreover for continuous set of zeros or ones there will be self-synchronization and base line wandering problem.

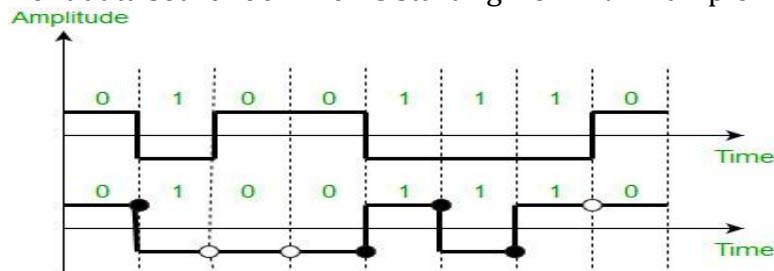
Polar schemes –

In polar schemes, the voltages are on the both sides of the axis.

- **NRZ-L and NRZ-I –**

These are somewhat similar to unipolar NRZ scheme but here we use two levels of amplitude (voltages). For **NRZ-L(NRZ-Level)**, the level of the voltage determines the value of the bit, typically binary 1 maps to logic-level high, and binary 0 maps to logic-level low, and for **NRZ-I(NRZ-Invert)**, two-level signal has a transition at a boundary if the next bit that we are going to transmit is a logical 1, and does not have a transition if the next bit that we are going to transmit is a logical 0.

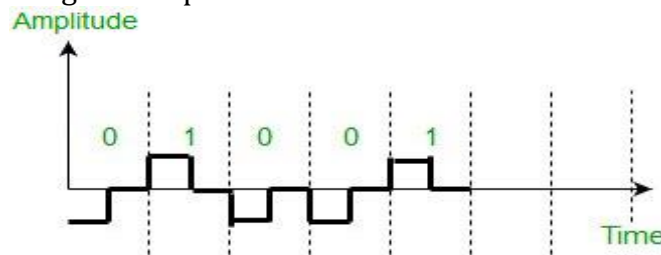
Note – For NRZ-I we are assuming in the example that previous signal before starting of data set “01001110” was positive. Therefore, there is no transition at the beginning and first bit “0” in current data set “01001110” is starting from +V. Example: Data = 01001110.



Comparison between NRZ-L and NRZ-I: Baseline wandering is a problem for both of them, but for NRZ-L it is twice as bad as compared to NRZ-I. This is because of transition at the boundary for NRZ-I (if the next bit that we are going to transmit is a logical 1). Similarly self-synchronization problem is similar in both for long sequence of 0's, but for long sequence of 1's it is more severe in NRZ-L.

- **Return to zero (RZ) –**

One solution to NRZ problem is the RZ scheme, which uses three values positive, negative and zero. In this scheme signal goes to 0 in the middle of each bit. **Note** – The logic we are using here to represent data is that for bit 1 half of the signal is represented by +V and half by zero voltage and for bit 0 half of the signal is represented by -V and half by zero voltage. Example: Data = 01001.



Main disadvantage of RZ encoding is that it requires greater bandwidth. Another problem is the complexity as it uses three levels of voltage. As a result of all these deficiencies, this scheme is not used today. Instead, it has been replaced by the better-performing Manchester and differential Manchester schemes.

- **Biphase (Manchester and Differential Manchester) –**

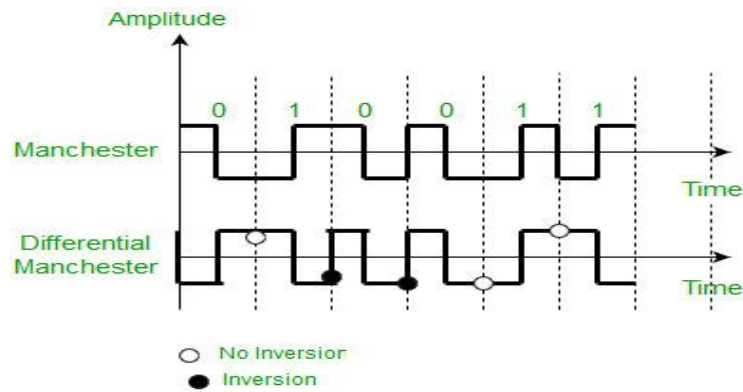
Manchester encoding is somewhat combination of the RZ (transition at the middle of the bit) and NRZ-L schemes. The duration of the bit is divided into two halves. The voltage remains at one level during the first half and moves to the other level in the second half. The transition at the middle of the bit provides synchronization.

Differential Manchester is somewhat combination of the RZ and NRZ-I schemes. There is always a transition at the middle of the bit but the bit values are determined at the beginning of the bit. If the next bit is 0, there is a transition, if the next bit is 1, there is no transition.

Note –

1. The logic we are using here to represent data using Manchester is that for bit 1 there is transition from -V to +V volts in the middle of the bit and for bit 0 there is transition from +V to -V volts in the middle of the bit.

2. For differential Manchester we are assuming in the example that previous signal before starting of data set "010011" was positive. Therefore there is transition at the beginning and first bit "0" in current data set "010011" is starting from -V. Example: Data = 010011.



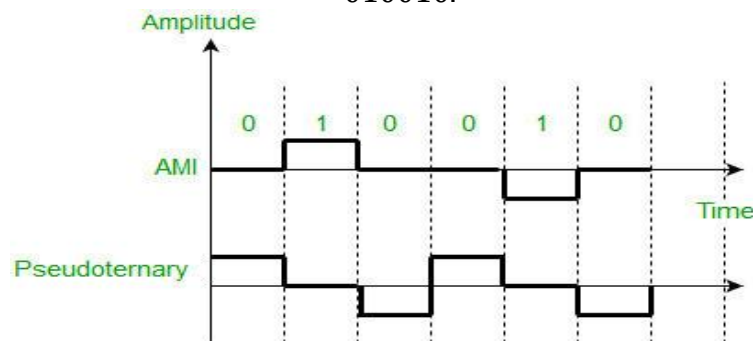
The Manchester scheme overcomes several problems associated with NRZ-L, and differential Manchester overcomes several problems associated with NRZ-I as there is no baseline wandering and no DC component because each bit has a positive and negative voltage contribution.

Only limitation is that the minimum bandwidth of Manchester and differential Manchester is twice that of NRZ.

Bipolar schemes -

In this scheme there are three voltage levels positive, negative, and zero. The voltage level for one data element is at zero, while the voltage level for the other element alternates between positive and negative.

- **Alternate Mark Inversion (AMI)** – A neutral zero voltage represents binary 0. Binary 1's are represented by alternating positive and negative voltages.
- **Pseudoternary** – Bit 1 is encoded as a zero voltage and the bit 0 is encoded as alternating positive and negative voltages i.e., opposite of AMI scheme. Example: Data = 010010.



The bipolar scheme is an alternative to NRZ. This scheme has the same signal rate as NRZ, but there is no DC component as one bit is represented by voltage zero and other alternates every time.

Multilevel Scheme-

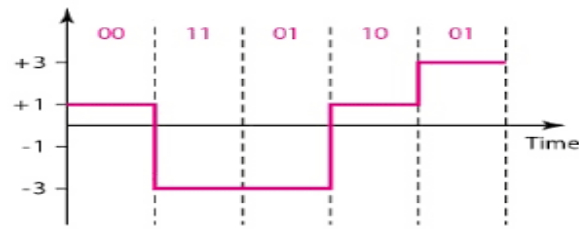
2BIQ-

In two binary one quaternary, uses data patterns of size two and encodes the two bit patterns as one signal element belonging to a four level signal.

	Previous level: positive	Previous level: negative
Next bits	Next level	Next level
00	+1	-1
01	+3	-3
10	-1	+1
11	-3	+3

Transition table

Ex.- Data- 0011011001



8B6T- (Eight binary, six ternary)

- This code is used with 100BASE-4T cable. The idea is to encode a pattern of 8 bits as a pattern of 6 signal elements.
- Each signal pattern has a weight of 0 or +1.
- The three possible signal levels are represented as -, 0 and +.

4D-PAM5- (Four dimensional five level pulse amplitude modulation)

- The 4D means that data is sent over four wires at the same time.
- It uses five voltage levels, such as -2, -1, 0, 1 and 2.
- However, one level, level 0 is used only for forward error detection.
- The technique is designed to send data over four channels.
- Gigabit LANs use this technique to send 1-Gbps data over four copper cables that can handle 125 Mband.

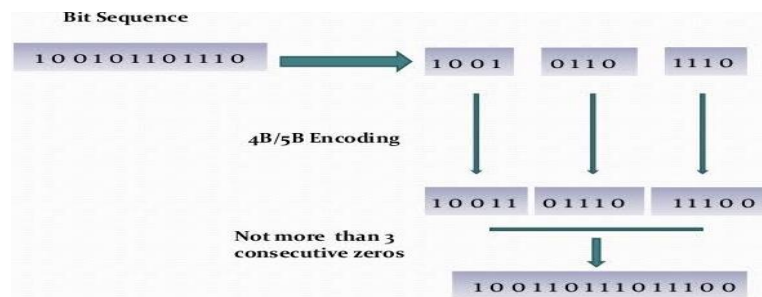
3.2.2 BLOCK CODING-

Block coding is normally referred to as mB/nB coding, it replaces each m bit group with an n bit group.

4B/5B (Four binary/ Five binary)-

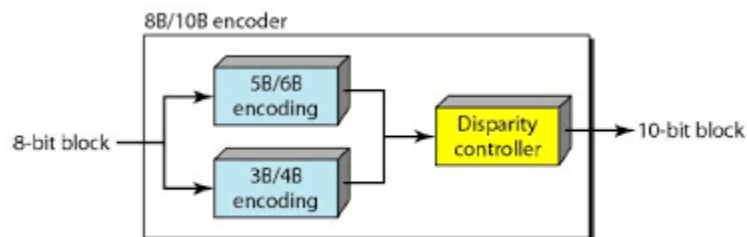
- In 4B/5B, the 5 bit output that replaces the 4 bit input has no more than one leading zero and no more than two trailing zeros.
- So, when different groups are combined to make a new sequence, there are never more than three consecutive 0s.

Data Sequence	Encoded Sequence	Control Sequence	Encoded Sequence
0000	11110	Q (Quiet)	00000
0001	01001	I (Idle)	11111
0010	10100	H (Halt)	00100
0011	10101	J (Start delimiter)	11000
0100	01010	K (Start delimiter)	10001
0101	01011	T (End delimiter)	01101
0110	01110	S (Set)	11001
0111	01111	R (Reset)	00111
1000	10010		
1001	10011		
1010	10110		
1011	10111		
1100	11010		
1101	11011		
1110	11100		
1111	11101		



8B/10B (Eight binary/ ten binary)-

- This is similar to 4B/5B encoding except that a group of 8 bits of data is substituted by a 10 bit code.
- It provides greater error detection capability than 4B/ 5B. the 8B/ 10B block coding is actually a combination of 5B/ 6B and 3B/ 4B encoding.



3.2.3. SCRAMBLING-

Scrambling is a technique that does not increase the number of bits and does provide synchronization. Problem with technique like Bipolar AMI (Alternate Mark Inversion) is that continuous sequence of zero's create synchronization problems one solution to this is Scrambling.

There are two common scrambling techniques:

1. B8ZS(Bipolar with 8-zero substitution)
2. HDB3(High-density bipolar3-zero)

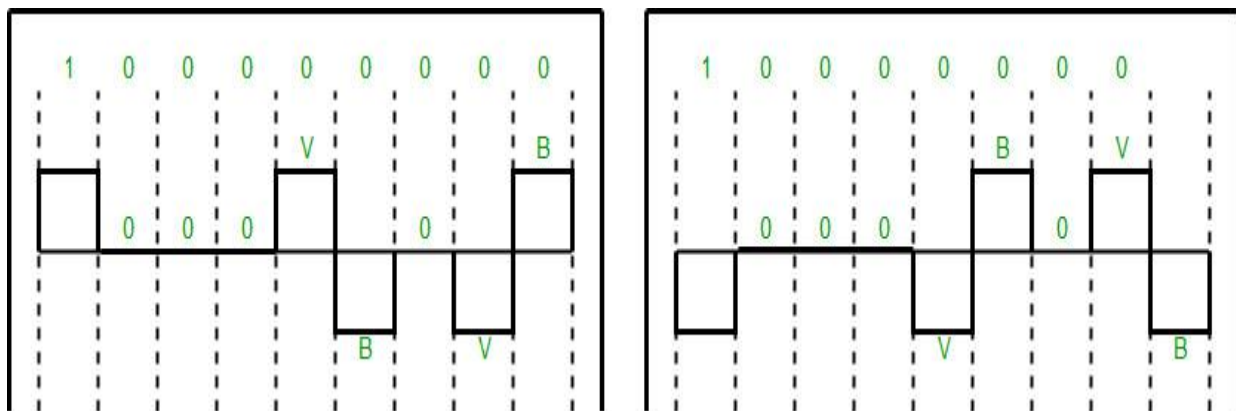
B8ZS (Bipolar with 8-zero substitution) -

This technique is similar to Bipolar AMI except when eight consecutive zero-level voltages are encountered they are replaced by the sequence,"000VB0VB".

Note -

- V (Violation), is a non-zero voltage which means signal have same polarity as the previous non-zero voltage. Thus it is violation of general AMI technique.
- B (Bipolar), also non-zero voltage level which is in accordance with the AMI rule (i.e., opposite polarity from the previous non-zero voltage).

Example: Data = 100000000



Note - Both figures (left and right one) are correct, depending upon last non-zero voltage signal of previous data sequence (i.e., sequence before current data sequence "100000000").

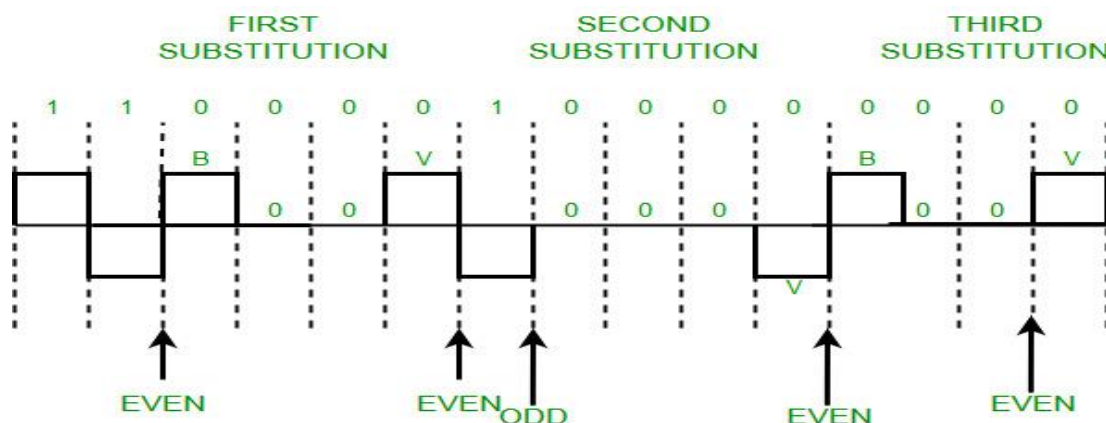
HDB3(High-density bipolar3-zero) -

In this technique four consecutive zero-level voltages are replaced with a sequence "000V" or "B00V".

Rules for using these sequences:

- If the number of nonzero pulses after the last substitution is odd, the substitution pattern will be "000V", this helps maintaining total number of nonzero pulses even.
- If the number of nonzero pulses after the last substitution is even, the substitution pattern will be "B00V". Hence even number of nonzero pulses is maintained again.

Example: Data = 1100001000000000



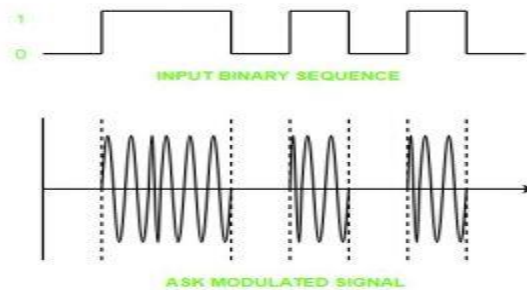
Explanation – After representing first two 1's of data we encounter four consecutive zeros. Since our last substitutions were two 1's (thus number of non-zero pulses is even). So, we substitute four zeros with "B00V".

3.3 DIGITAL DATA TO ANALOG SIGNAL-

The following techniques can be used for Digital to Analog Conversion:

1. Amplitude Shift keying – Amplitude Shift Keying is a technique in which carrier signal is analog and data to be modulated is digital. The amplitude of analog carrier signal is modified to reflect binary data.

The binary signal when modulated gives a zero value when the binary data represents 0 while gives the carrier output when data is 1. The frequency and phase of the carrier signal remain constant.



Advantages of amplitude shift Keying –

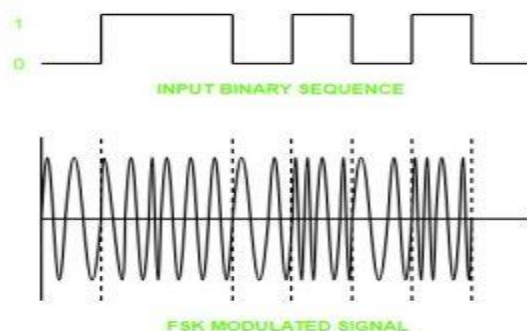
- It can be used to transmit digital data over optical fiber.
- The receiver and transmitter have a simple design which also makes it comparatively inexpensive.
- It uses lesser bandwidth as compared to FSK thus it offers high bandwidth efficiency.

Disadvantages of amplitude shift Keying –

- It is susceptible to noise interference and entire transmissions could be lost due to this.
- It has lower power efficiency.

2. Frequency Shift keying – In this modulation the frequency of analog carrier signal is modified to reflect binary data.

The output of a frequency shift keying modulated wave is high in frequency for a binary high input and is low in frequency for a binary low input. The amplitude and phase of the carrier signal remain constant.



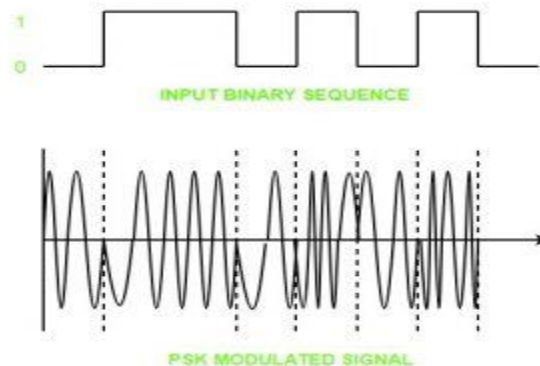
Advantages of frequency shift Keying –

- Frequency shift keying modulated signal can help avoid the noise problems beset by ASK.
- It has lower chances of an error.
- It provides high signal to noise ratio.
- The transmitter and receiver implementations are simple for low data rate application.

Disadvantages of frequency shift Keying –

- It uses larger bandwidth as compared to ASK thus it offers less bandwidth efficiency.
- It has lower power efficiency.

3. Phase Shift keying – In this modulation the phase of the analog carrier signal is modified to reflect binary data. The amplitude and frequency of the carrier signal remains constant.



It is further categorized as follows:

1. Binary Phase Shift Keying (BPSK):

BPSK also known as phase reversal keying or 2PSK is the simplest form of phase shift keying. The Phase of the carrier wave is changed according to the two binary inputs. In Binary Phase shift keying, difference of 180 phase shift is used between binary 1 and binary 0.

This is regarded as the most robust digital modulation technique and is used for long distance wireless communication.

2. Quadrature phase shift keying:

This technique is used to increase the bit rate i.e we can code two bits onto one single element. It uses four phases to encode two bits per symbol. QPSK uses phase shifts of multiples of 90 degrees.

It has double data rate carrying capacity compare to BPSK as two bits are mapped on each constellation points.

Advantages of phase shift Keying –

- It is a more power efficient modulation technique as compared to ASK and FSK.
- It has lower chances of an error.
- It allows data to be carried along a communication signal much more efficiently as compared to FSK.

Disadvantages of phase shift Keying –

- It offers low bandwidth efficiency.
- The detection and recovery algorithms of binary data is very complex.
- It is a non-coherent reference signal.

3.4 ANALOG DATA TO DIGITAL SIGNAL-

Digital Signal: A digital signal is a signal that represents data as a sequence of discrete values; at any given time it can only take on one of a finite number of values.

Analog Signal: An analog signal is any continuous signal for which the time varying feature of the signal is a representation of some other time varying quantity i.e., analogous to another time varying signal.

The following techniques can be used for Analog to Digital Conversion:

a. PULSE CODE MODULATION:

The most common technique to change an analog signal to digital data is called pulse code modulation (PCM). A PCM encoder has the following three processes:

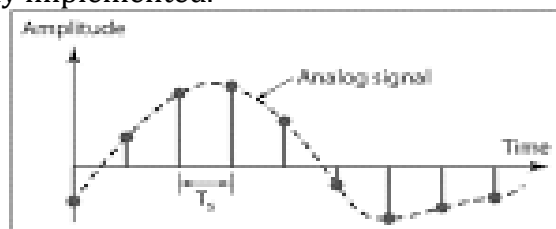
1. Sampling
2. Quantization
3. Encoding

Low pass filter:

The low pass filter eliminates the high frequency components present in the input analog signal to ensure that the input signal to sampler is free from the unwanted frequency components. This is done to avoid aliasing of the message signal.

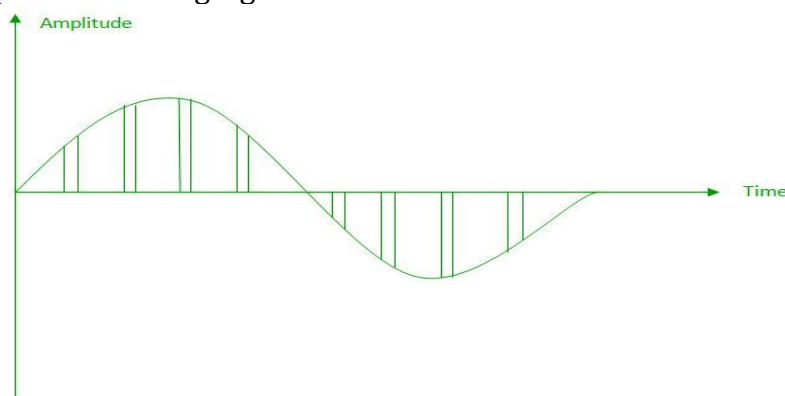
1. **Sampling** – The first step in PCM is sampling. Sampling is a process of measuring the amplitude of a continuous-time signal at discrete instants, converting the continuous signal into a discrete signal. There are three sampling methods:

(i) Ideal Sampling: In ideal sampling also known as Instantaneous sampling pulses from the analog signal are sampled. This is an ideal sampling method and cannot be easily implemented.

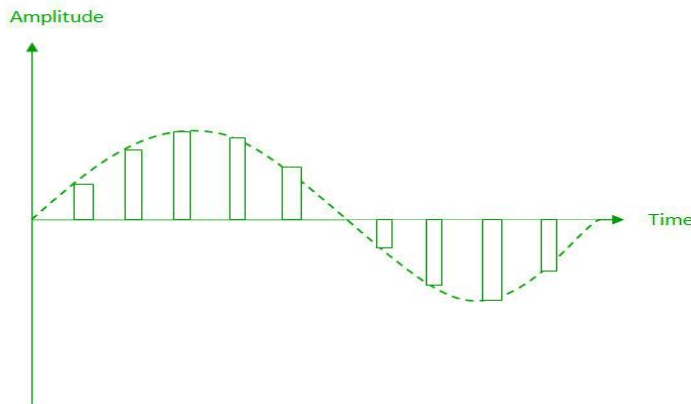


a. Ideal sampling

(ii) Natural Sampling: Natural Sampling is a practical method of sampling in which pulse have finite width equal to T . The result is a sequence of samples that retain the shape of the analog signal.



(iii) Flat top sampling: In comparison to natural sampling flat top sampling can be easily obtained. In this sampling technique, the top of the samples remains constant by using a circuit. This is the most common sampling method used.



Nyquist Theorem:

One important consideration is the sampling rate or frequency. According to the Nyquist theorem, the sampling rate must be at least 2 times the highest frequency contained in the signal. It is also known as the minimum sampling rate and given by:

$$F_s = 2 \cdot f_m$$

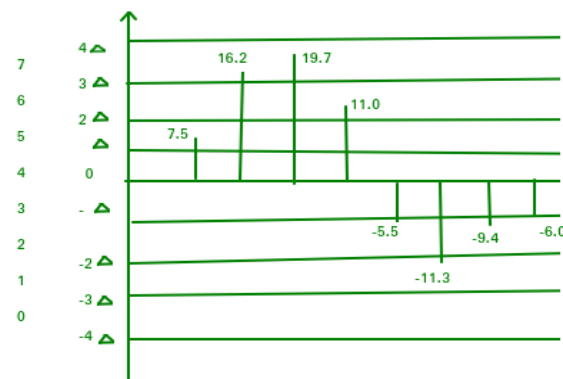
2. Quantization

The result of sampling is a series of pulses with amplitude values between the maximum and minimum amplitudes of the signal. The set of amplitudes can be infinite with non-integral values between two limits.

The following are the steps in Quantization:

1. We assume that the signal has amplitudes between V_{max} and V_{min}
2. We divide it into L zones each of height d where,

$$d = (V_{max} - V_{min}) / L$$



Normalised PAM value :	1.50	3.24	3.94	2.20	-1.10	2.26	-1.88	-1.20
Quantized Value :	1.50	3.50	3.50	2.50	-1.50	-2.50	-1.50	-1.50
Normalized Error :	0	0.26	-0.44	0.30	-0.40	-0.24	0.38	-0.30
Quantization Code :	5	7	7	6	2	1	2	2
Encoded Words :	101	111	111	110	010	001	010	010

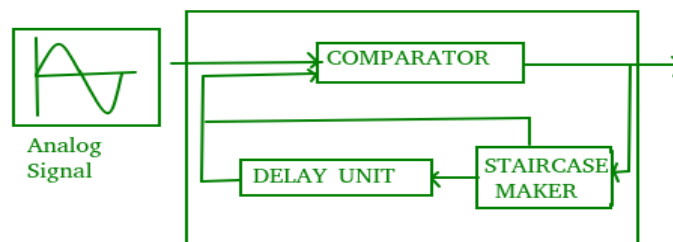
3. The value at the top of each sample in the graph shows the actual amplitude.
4. The normalized pulse amplitude modulation (PAM) value is calculated using the formula $\text{amplitude}/d$.

5. After this we calculate the quantized value which the process selects from the middle of each zone.
 6. The Quantized error is given by the difference between quantized value and normalized PAM value.
 7. The Quantization code for each sample based on quantization levels at the left of the graph.
3. **Encoding-**
The digitization of the analog signal is done by the encoder. After each sample is quantized and the number of bits per sample is decided, each sample can be changed to an n bit code. Encoding also minimizes the bandwidth used.

b. DELTA MODULATION:

Since PCM is a very complex technique, other techniques have been developed to reduce the complexity of PCM. The simplest is delta Modulation. Delta Modulation finds the change from the previous value.

Modulator – The modulator is used at the sender site to create a stream of bits from an analog signal. The process records a small positive change called delta. If the delta is positive, the process records a 1 else the process records a 0. The modulator builds a second signal that resembles a staircase. The input signal is then compared with this gradually made staircase signal.



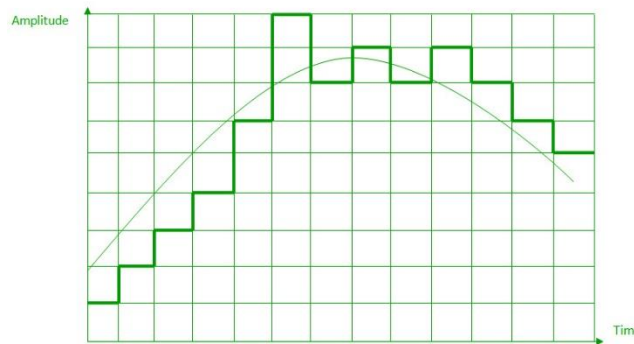
We have the following rules for output:

1. If the input analog signal is higher than the last value of the staircase signal, increase delta by 1, and the bit in the digital data is 1.
2. If the input analog signal is lower than the last value of the staircase signal, decrease delta by 1, and the bit in the digital data is 0.



c. ADAPTIVE DELTA MODULATION:

The performance of a delta modulator can be improved significantly by making the step size of the modulator assume a time-varying form. A larger step-size is needed where the message has a steep slope of modulating signal and a smaller step-size is needed where the message has a small slope. The size is adapted according to the level of the input signal. This method is known as adaptive delta modulation (ADM).



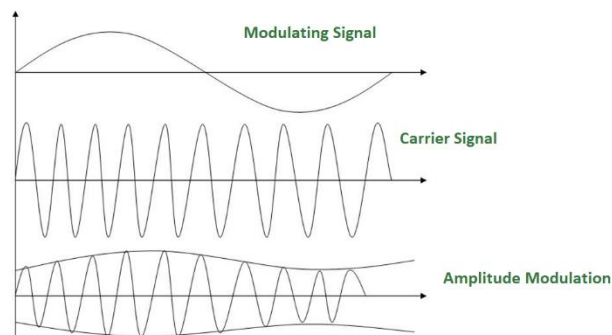
3.5 ANALOG DATA TO ANALOG DATA-

Analog to Analog conversion can be done in three ways:

1. Amplitude Modulation
2. Frequency Modulation
3. Phase Modulation

1. AMPLITUDE MODULATION:

The modulation in which the amplitude of the carrier wave is varied according to the instantaneous amplitude of the modulating signal keeping phase and frequency as constant. The figure below shows the concept of amplitude modulation:



AM is normally implemented by using a simple multiplier because the amplitude of the carrier signal needs to be changed according to the amplitude of the modulating signal.

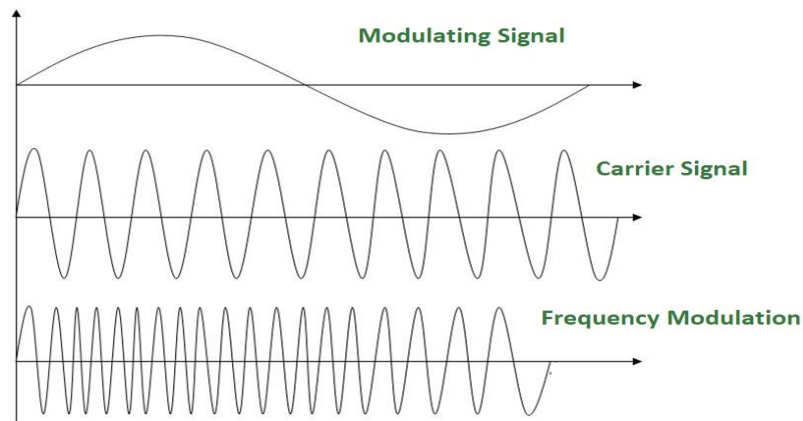
AM bandwidth:

The modulation creates a bandwidth that is twice the bandwidth of the modulating signal and covers a range centered on the carrier frequency.

Bandwidth= $2f_m$

2. FREQUENCY MODULATION –

The modulation in which the frequency of the carrier wave is varied according to the instantaneous amplitude of the modulating signal keeping phase and amplitude as constant. The figure below shows the concept of frequency modulation:



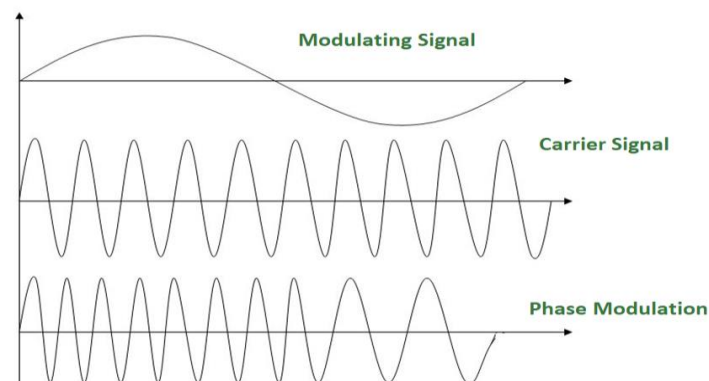
FM is normally implemented by using a voltage-controlled oscillator as with FSK. The frequency of the oscillator changes according to the input voltage which is the amplitude of the modulating signal.

FM bandwidth:

1. The bandwidth of a frequency modulated signal varies with both deviation and modulating frequency.
If modulating frequency (M_f) 0.5, wide band Fm signal.
2. For a narrow band Fm signal, bandwidth required is twice the maximum frequency of the modulation, however for a wide band Fm signal the required bandwidth can be very much larger, with detectable sidebands spreading out over large amounts of the frequency spectrum.

3. PHASE MODULATION:

The modulation in which the phase of the carrier wave is varied according to the instantaneous amplitude of the modulating signal keeping amplitude and frequency as constant. The figure below shows the concept of frequency modulation:



Phase modulation is practically similar to Frequency Modulation, but in Phase modulation frequency of the carrier signal is not increased. It is normally implemented by using a voltage-controlled oscillator along with a derivative. The frequency of the oscillator changes according to the derivative of the input voltage which is the amplitude of the modulating signal.

PM bandwidth:

1. For small amplitude signals, PM is similar to amplitude modulation (AM) and exhibits its unfortunate doubling of baseband bandwidth and poor efficiency.
2. For a single large sinusoidal signal, PM is similar to FM, and its bandwidth is approximately, **$2(h+1)F_m$** where h = modulation index.

Thus, Modulation allows us to send a signal over a bandpass frequency range. If every signal gets its own frequency range, then we can transmit multiple signals simultaneously over a single channel, all using different frequency ranges.

UNIT-4: DATA COMMUNICATION & DATA LINK CONTROL

4.1 ASYNCHRONOUS AND SYNCHRONOUS TRANSMISSION-

There are two types of serial transmission-synchronous and asynchronous both these transmissions use '**Bit synchronization**'

Bit Synchronization is a function that is required to determine when the beginning and end of the data transmission occurs.

Bit synchronization helps the receiving computer to know when data begin and end during a transmission. Therefore bit synchronization provides timing control.

Asynchronous Transmission

- Asynchronous transmission sends only one character at a time where a character is either a letter of the alphabet or number or control character *i.e.* it sends one byte of data at a time.
- Bit synchronization between two devices is made possible using start bit and stop bit.
- Start bit indicates the beginning of data *i.e.* alerts the receiver to the arrival of new group of bits. A start bit usually 0 is added to the beginning of each byte.
- Stop bit indicates the end of data *i.e.* to let the receiver know that byte is finished, one or more additional bits are appended to the end of the byte. These bits, usually 1s are called stop bits.



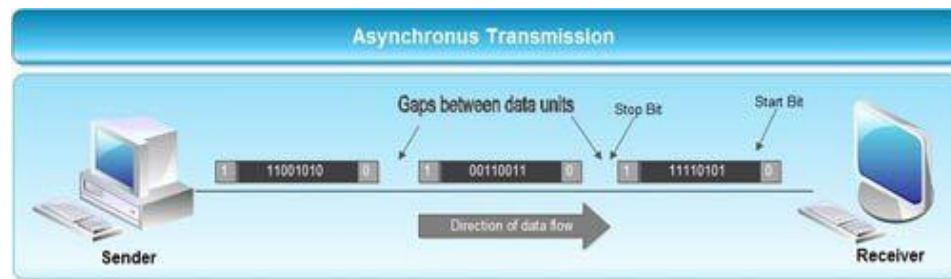
Addition of start and stop increase the number of data bits. Hence more bandwidth is consumed in asynchronous transmission.

- There is idle time between the transmissions of different data bytes. This idle time is also known as Gap
- The gap or idle time can be of varying intervals. This mechanism is called Asynchronous, because at byte level sender and receiver need not to be synchronized. But within each byte, receiver must be synchronized with the incoming bit stream.

Application of Asynchronous Transmission

1. Asynchronous transmission is well suited for keyboard type-terminals and paper tape devices. The advantage of this method is that it does not require any local storage at the terminal or the computer as transmission takes place character by character.

2. Asynchronous transmission is best suited to Internet traffic in which information is transmitted in short bursts. This type of transmission is used by modems.



Advantages of Asynchronous transmission

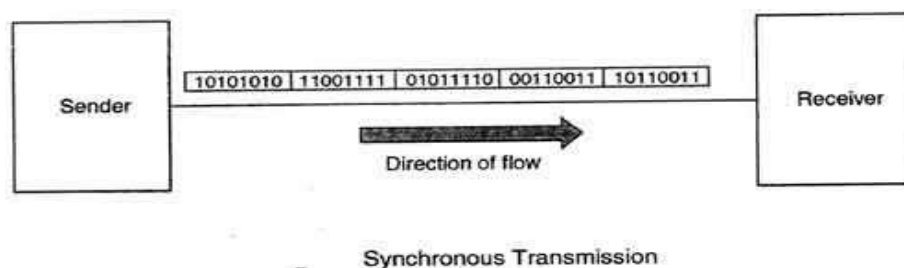
1. This method of data transmission is cheaper in cost as compared to synchronous e.g. If lines are short, asynchronous transmission is better, because line cost would be low and idle time will not be expensive.
2. In this approach each individual character is complete in itself, therefore if character is corrupted during transmission, its successor and predecessor character will not be affected.
3. It is possible to transmit signals from sources having different bit rates.
4. The transmission can start as soon as data byte to be transmitted becomes available.
5. Moreover, this mode of data transmission is easy to implement.

Disadvantages of asynchronous transmission

1. This method is less efficient and slower than synchronous transmission due to the overhead of extra bits and insertion of gaps into bit stream.
2. Successful transmission inevitably depends on the recognition of the start bits. These bits can be missed or corrupted.

Synchronous Transmission

- Synchronous transmission does not use start and stop bits.
- In this method bit stream is combined into longer frames that may contain multiple bytes.
- There is no gap between the various bytes in the data stream.



- In the absence of start & stop bits, bit synchronization is established between sender & receiver by '*timing*' the transmission of each bit.
- Since the various bytes are placed on the link without any gap, it is the responsibility of receiver to separate the bit stream into bytes so as to reconstruct the original information.
- In order to receive the data error free, the receiver and sender operates at the same clock frequency.

Application of Synchronous transmission

- Synchronous transmission is used for high speed communication between computers.

Advantage of Synchronous transmission

1. This method is faster as compared to asynchronous as there are no extra bits (start bit & stop bit) and also there is no gap between the individual data bytes.

Disadvantages of Synchronous transmission

1. It is costly as compared to asynchronous method. It requires local buffer storage at the two ends of line to assemble blocks and it also requires accurately synchronized clocks at both ends. This lead to increase in the cost.
2. The sender and receiver have to operate at the same clock frequency. This requires proper synchronization which makes the system complicated.

4.2 ERROR DETECTION-

Whenever a message is transmitted, it may get scrambled by noise or data may get corrupted. To avoid this, we use error-detecting codes which are additional data added to a given digital message to help us detect if any error has occurred during transmission of the message.

Basic approach used for error detection is the use of redundancy bits, where additional bits are added to facilitate detection of errors.

Some popular techniques for error detection are:

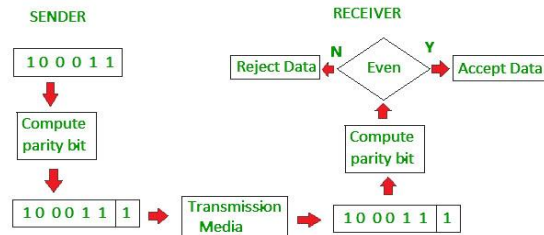
1. Simple Parity check
2. Two-dimensional Parity check
3. Checksum
4. Cyclic redundancy check

1. Simple Parity check

Blocks of data from the source are subjected to a check bit or parity bit generator form, where a parity of :

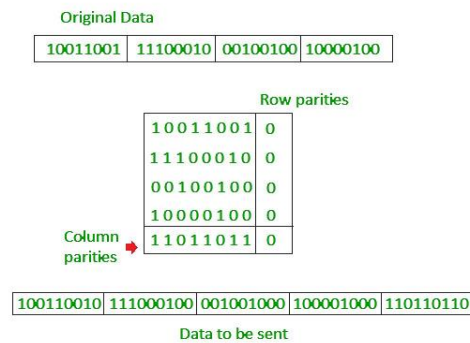
- 1 is added to the block if it contains odd number of 1's, and
- 0 is added if it contains even number of 1's

This scheme makes the total number of 1's even, that is why it is called even parity checking.



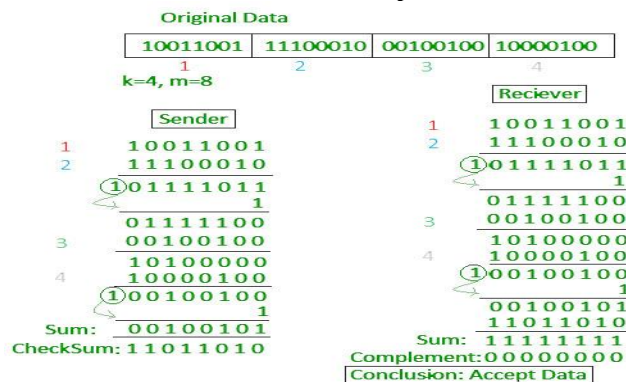
2. Two-dimensional Parity check

Parity check bits are calculated for each row, which is equivalent to a simple parity check bit. Parity check bits are also calculated for all columns, then both are sent along with the data. At the receiving end these are compared with the parity bits calculated on the received data.



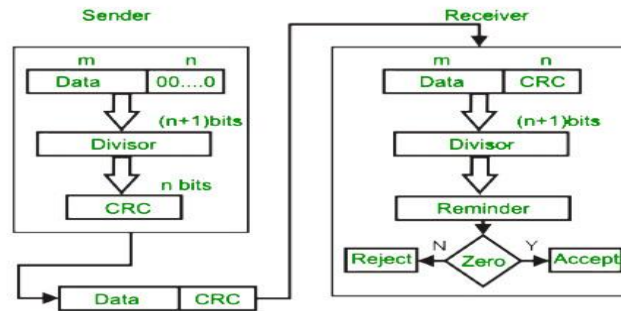
3. Checksum

- In checksum error detection scheme, the data is divided into k segments each of m bits.
- In the sender's end the segments are added using 1's complement arithmetic to get the sum. The sum is complemented to get the checksum.
- The checksum segment is sent along with the data segments.
- At the receiver's end, all received segments are added using 1's complement arithmetic to get the sum. The sum is complemented.
- If the result is zero, the received data is accepted; otherwise discarded.

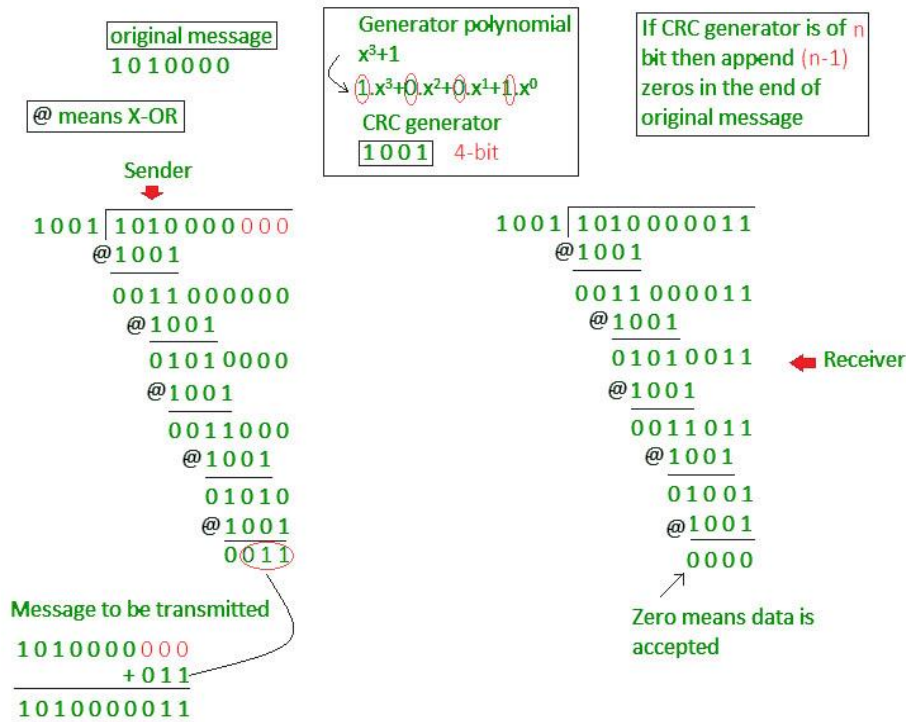


4. Cyclic redundancy check (CRC)

- Unlike checksum scheme, which is based on addition, CRC is based on binary division.
- In CRC, a sequence of redundant bits, called cyclic redundancy check bits, are appended to the end of data unit so that the resulting data unit becomes exactly divisible by a second, predetermined binary number.
- At the destination, the incoming data unit is divided by the same number. If at this step there is no remainder, the data unit is assumed to be correct and is therefore accepted.
- A remainder indicates that the data unit has been damaged in transit and therefore must be rejected.



Example:



Error Correction

Error Correction codes are used to detect and correct the errors when data is transmitted from the sender to the receiver.

Error Correction can be handled in two ways:

- **Backward error correction:** Once the error is discovered, the receiver requests the sender to retransmit the entire data unit.
- **Forward error correction:** In this case, the receiver uses the error-correcting code which automatically corrects the errors.

A single additional bit can detect the error, but cannot correct it.

For correcting the errors, one has to know the exact position of the error. For example, If we want to calculate a single-bit error, the error correction code will determine which one of seven bits is in error. To achieve this, we have to add some additional redundant bits.

Suppose r is the number of redundant bits and d is the total number of the data bits. The number of redundant bits r can be calculated by using the formula:

$$2^r \geq d + r + 1$$

The value of r is calculated by using the above formula. For example, if the value of d is 4, then the possible smallest value that satisfies the above relation would be 3.

To determine the position of the bit which is in error, a technique developed by R.W Hamming is Hamming code which can be applied to any length of the data unit and uses the relationship between data units and redundant units.

Hamming Code

Parity bits: The bit which is appended to the original data of binary bits so that the total number of 1s is even or odd.

Even parity: To check for even parity, if the total number of 1s is even, then the value of the parity bit is 0. If the total number of 1s occurrences is odd, then the value of the parity bit is 1.

Odd Parity: To check for odd parity, if the total number of 1s is even, then the value of parity bit is 1. If the total number of 1s is odd, then the value of parity bit is 0.

Algorithm of hamming code:

- An information of ' d ' bits are added to the redundant bits ' r ' to form $d+r$.
- The location of each of the $(d+r)$ digits is assigned a decimal value.
- The ' r ' bits are placed in the positions $1, 2, \dots, 2^{k-1}$.
- At the receiving end, the parity bits are recalculated. The decimal value of the parity bits determines the position of an error.

Relationship b/w Error position & binary number.

Error Position	Binary Number
0	000
1	001
2	010
3	011
4	100
5	101
6	110
7	111

Let's understand the concept of Hamming code through an example:

Suppose the original data is 1010 which is to be sent.

Total number of data bits 'd' = 4

Number of redundant bits r: $2^r \geq d+r+1$

$$2^r \geq 4+r+1$$

Therefore, the value of r is 3 that satisfies the above relation.

Total number of bits = d+r = 4+3 = 7;

Determining the position of the redundant bits

The number of redundant bits is 3. The three bits are represented by r1, r2, r4. The position of the redundant bits is calculated with corresponds to the raised power of 2. Therefore, their corresponding positions are **1, 2¹, 2²**.

1. The position of r1 = 1
2. The position of r2 = 2
3. The position of r4 = 4

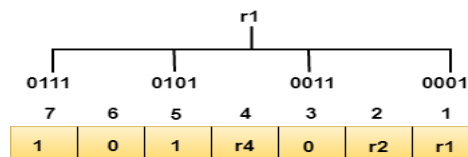
Representation of Data on the addition of parity bits:

7	6	5	4	3	2	1
1	0	1	r4	0	r2	r1

Determining the Parity bits

Determining the r1 bit

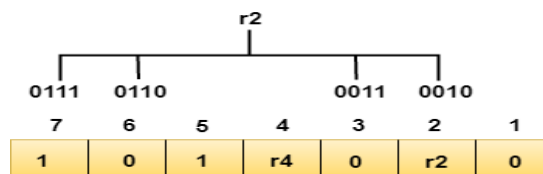
The r1 bit is calculated by performing a parity check on the bit positions whose binary representation includes 1 in the first position.



We observe from the above figure that the bit positions that includes 1 in the first position are 1, 3, 5, 7. Now, we perform the even-parity check at these bit positions. The total number of 1 at these bit positions corresponding to r1 is **even, therefore, the value of the r1 bit is 0.**

Determining r2 bit

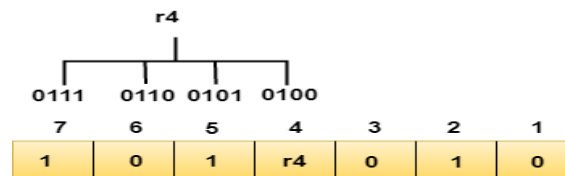
The r2 bit is calculated by performing a parity check on the bit positions whose binary representation includes 1 in the second position.



We observe from the above figure that the bit positions that includes 1 in the second position are **2, 3, 6, 7**. Now, we perform the even-parity check at these bit positions. The total number of 1 at these bit positions corresponding to r2 is **odd, therefore, the value of the r2 bit is 1**.

Determining r4 bit

The r4 bit is calculated by performing a parity check on the bit positions whose binary representation includes 1 in the third position.



We observe from the above figure that the bit positions that includes 1 in the third position are **4, 5, 6, 7**. Now, we perform the even-parity check at these bit positions. The total number of 1 at these bit positions corresponding to r4 is **even, therefore, the value of the r4 bit is 0**.

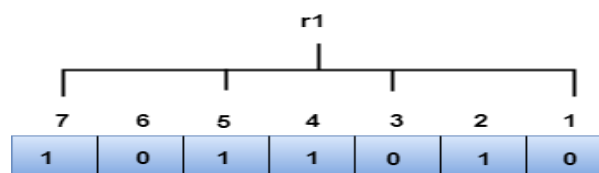
Data transferred is given below:

7	6	5	4	3	2	1
1	0	1	0	0	1	0

Suppose the 4th bit is changed from 0 to 1 at the receiving end, then parity bits are recalculated.

R1 bit

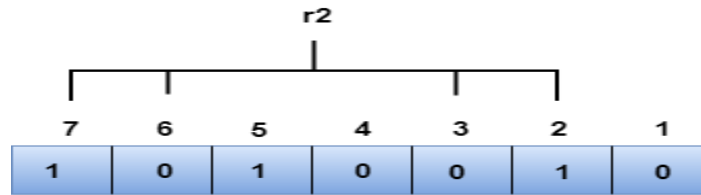
The bit positions of the r1 bit are 1,3,5,7



We observe from the above figure that the binary representation of r1 is 1100. Now, we perform the even-parity check, the total number of 1s appearing in the r1 bit is an even number. Therefore, the value of r1 is 0.

R2 bit

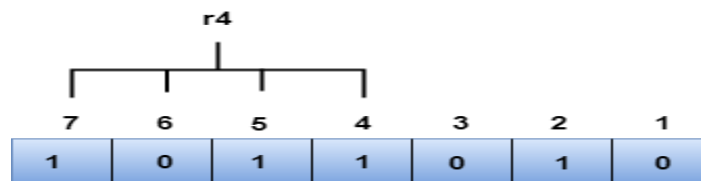
The bit positions of r2 bit are 2,3,6,7.



We observe from the above figure that the binary representation of r2 is 1001. Now, we perform the even-parity check, the total number of 1s appearing in the r2 bit is an even number. Therefore, the value of r2 is 0.

R4 bit

The bit positions of r4 bit are 4,5,6,7.



We observe from the above figure that the binary representation of r4 is 1011. Now, we perform the even-parity check, the total number of 1s appearing in the r4 bit is an odd number. Therefore, the value of r4 is 1.

- The binary representation of redundant bits, i.e., r4r2r1 is 100, and its corresponding decimal value is 4. Therefore, the error occurs in a 4th bit position. The bit value must be changed from 1 to 0 to correct the error.

4.2 LINE CONFIGURATION

Line configuration refers to the way two or more communication devices attached to a link. Line configuration is also referred to as connection. A Link is the physical communication pathway that transfers data from one device to another. For communication to occur, two devices must be connected in same way to the same link at the same time.

There are two possible line configurations.

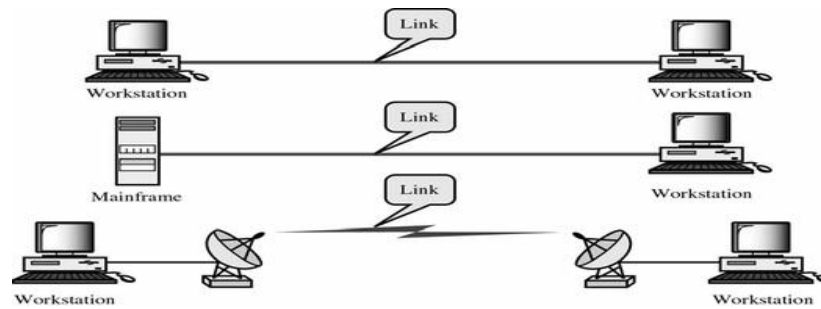
1. Point-to-Point.
2. Multipoint.

Point-to-Point

A Point to Point Line Configuration Provide dedicated link between two devices use actual length of wire or cable to connect the two end including microwave & satellite link. Infrared remote control & tvs remote control.

The entire capacity of the channel is reserved for transmission between those two devices. Most point-to-point line configurations use an actual length of wire or cable to connect the two ends, but other options, such as microwave or satellite links, are also possible.

Point to point network topology is considered to be one of the easiest and most conventional network topologies. It is also the simplest to establish and understand. To visualize, one can consider point to point network topology as two phones connected end to end for a two way communication

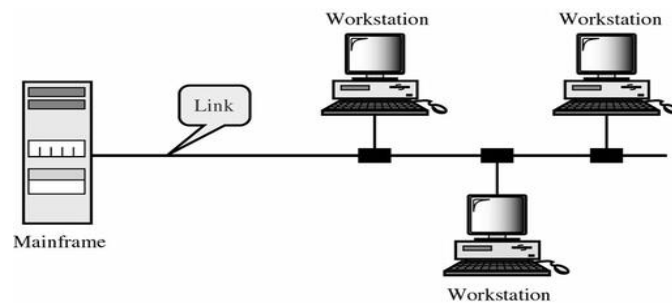


Multipoint Configuration

Multipoint Configuration also known as **Multidrop line configuration** one or more than two specific devices share a single link capacity of the channel is shared.

More than two devices share the Link that is the capacity of the channel is shared now. With shared capacity, there can be two possibilities in a Multipoint Line Config:

- **Spatial Sharing:** If several devices can share the link simultaneously, its called Spatially shared line configuration
- **Temporal (Time) Sharing:** If users must take turns using the link , then its called Temporally shared or Time Shared Line Configuration



4.4 FLOW CONTROL-

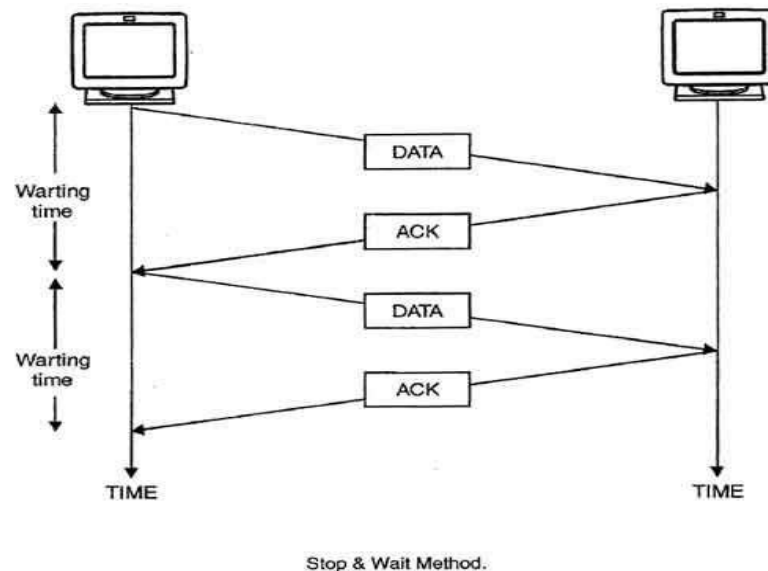
When a data frame (Layer-2 data) is sent from one host to another over a single medium, it is required that the sender and receiver should work at the same speed. That is, sender sends at a speed on which the receiver can process and accept the data. What if the speed (hardware/software) of the sender or receiver differs? If sender is sending too fast the receiver may be overloaded, (swamped) and data may be lost.

Two types of mechanisms can be deployed to control the flow:

Stop and wait protocol-

- In this method of flow control, the sender sends a single frame to receiver & waits for an acknowledgment.
- The next frame is sent by sender only when acknowledgment of previous frame is received.
- This process of sending a frame & waiting for an acknowledgment continues as long as the sender has data to send.

- To end up the transmission sender transmits end of transmission (EOT) frame.
- The main advantage of stop & wait protocols is its accuracy. Next frame is transmitted only when the first frame is acknowledged. So there is no chance of frame being lost.
- The main disadvantage of this method is that it is inefficient. It makes the transmission process slow. In this method single frame travels from source to destination and single acknowledgment travels from destination to source. As a result each frame sent and received uses the entire time needed to traverse the link. Moreover, if two devices are distance apart, a lot of time is wasted waiting for ACKs that leads to increase in total transmission time.



SLIDING WINDOW-

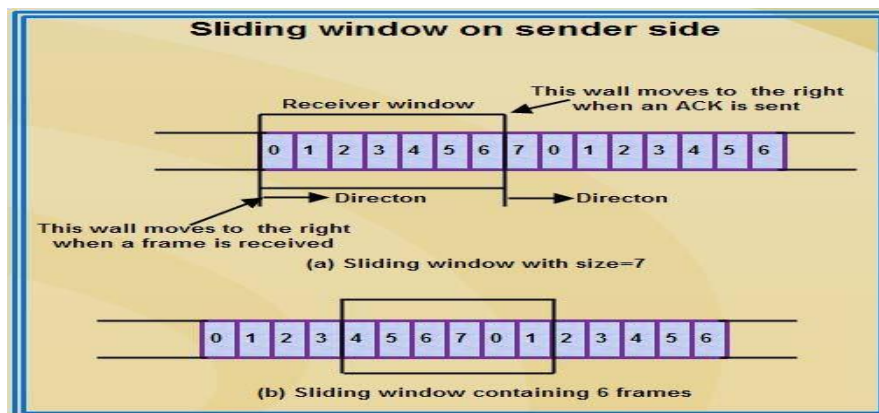
- In sliding window method, multiple frames are sent by sender at a time before needing an acknowledgment.
- Multiple frames sent by source are acknowledged by receiver using a single ACK frame.
- Sliding window refers to an imaginary boxes that hold the frames on both sender and receiver side.
- It provides the upper limit on the number of frames that can be transmitted before requiring an acknowledgment.
- Frames may be acknowledged by receiver at any point even when window is not full on receiver side.
- Frames may be transmitted by source even when window is not yet full on sender side.
- The windows have a specific size in which the frames are numbered modulo- n , which means they are numbered from 0 to $n-1$. For e.g. if $n = 8$, the frames are numbered 0, 1, 2, 3, 4, 5, 6, 7, 0, 1, 2, 3, 4, 5, 6, 7, 0, 1,
- The size of window is $n-1$. For e.g. In this case it is 7. Therefore, a maximum of $n-1$ frames may be sent before an acknowledgment.
- When the receiver sends an ACK, it includes the number of next frame it expects to receive. For example in order to acknowledge the group of frames ending in frame 4, the receiver

sends an ACK containing the number 5. When sender sees an ACK with number 5, it comes to know that all the frames up to number 4 have been received.



Sliding Window on Sender Side

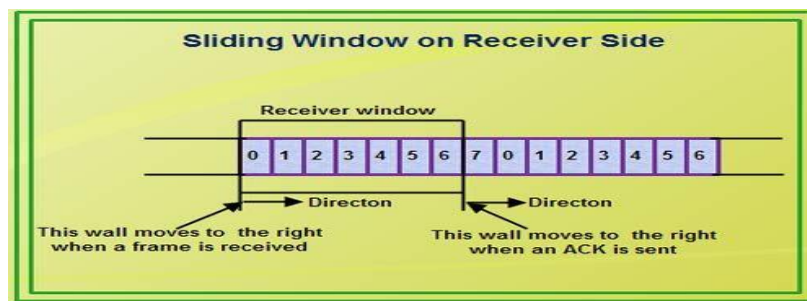
- At the beginning of a transmission, the sender's window contains $n-1$ frames.
- As the frames are sent by source, the left boundary of the window moves inward, shrinking the size of window. This means if window size is w , if four frames are sent by source after the last acknowledgment, then the number of frames left in window is $w-4$.
- When the receiver sends an ACK, the source's window expand i.e. (right boundary moves outward) to allow in a number of new frames equal to the number of frames acknowledged by that ACK.
- For example, Let the window size is 7 (see diagram (a)), if frames 0 through 3 have been sent and no acknowledgment has been received, then the sender's window contains three frames - 4,5,6.
- Now, if an ACK numbered 3 is received by source, it means three frames (0, 1, 2) have been received by receiver and are undamaged.
- The sender's window will now expand to include the next three frames in its buffer. At this point the sender's window will contain six frames (4, 5, 6, 7, 0, 1). (See diagram (b)).



Sliding Window on Receiver Side

- At the beginning of transmission, the receiver's window contains $n-1$ spaces for frame but not the frames.
- As the new frames come in, the size of window shrinks.
- Therefore the receiver window represents not the number of frames received but the number of frames that may still be received without an acknowledgment ACK must be sent.
- Given a window of size w , if three frames are received without an ACK being returned, the number of spaces in a window is $w-3$.
- As soon as acknowledgment is sent, window expands to include the number of frames equal to the number of frames acknowledged.

- For example, let the size of receiver's window is 7 as shown in diagram. It means window contains spaces for 7 frames.
- With the arrival of the first frame, the receiving window shrinks, moving the boundary from space 0 to 1. Now, window has shrunk by one, so the receiver may accept six more frame before it is required to send an ACK.
- If frames 0 through 3 have arrived but have not been acknowledged, the window will contain three frame spaces.
- As receiver sends an ACK, the window of the receiver expands to include as many new placeholders as newly acknowledged frames.
- The window expands to include a number of new frame spaces equal to the number of the most recently acknowledged frame minus the number of previously acknowledged frame. For *e.g.*, If window size is 7 and if prior ACK was for frame 2 & the current ACK is for frame 5 the window expands by three (5-2).



- Therefore, the sliding window of sender shrinks from left when frames of data are sending. The sliding window of the sender expands to right when acknowledgments are received.
- The sliding window of the receiver shrinks from left when frames of data are received. The sliding window of the receiver expands to the right when acknowledgement is sent.

4.5 ERROR CONTROL-

Error control in data link layer is the process of detecting and correcting data frames that have been corrupted or lost during transmission.

In case of lost or corrupted frames, the receiver does not receive the correct data-frame and sender is ignorant about the loss. Data link layer follows a technique to detect transit errors and take necessary actions, which is retransmission of frames whenever error is detected or frame is lost. The process is called Automatic Repeat Request (ARQ).

Phases in Error Control

The error control mechanism in data link layer involves the following phases:

- **Detection of Error** – Transmission error, if any, is detected by either the sender or the receiver.
- **Acknowledgment** – acknowledgment may be positive or negative.
 - **Positive ACK** – on receiving a correct frame, the receiver sends a positive acknowledge.

- **Negative ACK** – on receiving a damaged frame or a duplicate frame, the receiver sends a negative acknowledgment back to the sender.
- **Retransmission** – the sender maintains a clock and sets a timeout period. If an acknowledgment of a data-frame previously transmitted does not arrive before the timeout, or a negative acknowledgment is received, the sender retransmits the frame.

Error Control Techniques

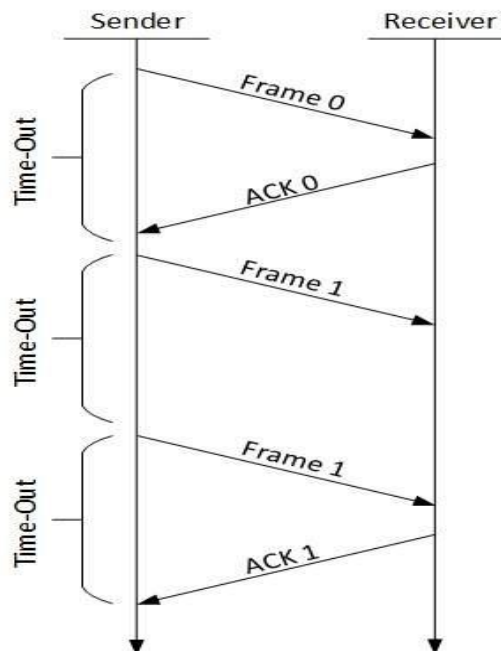
There are three main techniques for error control:



• Stop and Wait ARQ

This protocol involves the following transitions:

- A timeout counter is maintained by the sender, which is started when a frame is sent.
- If the sender receives acknowledgment of the sent frame within time, the sender is confirmed about successful delivery of the frame. It then transmits the next frame in queue.
- If the sender does not receive the acknowledgment within time, the sender assumes that either the frame or its acknowledgment is lost in transit. It then retransmits the frame.
- If the sender receives a negative acknowledgment, the sender retransmits the frame.

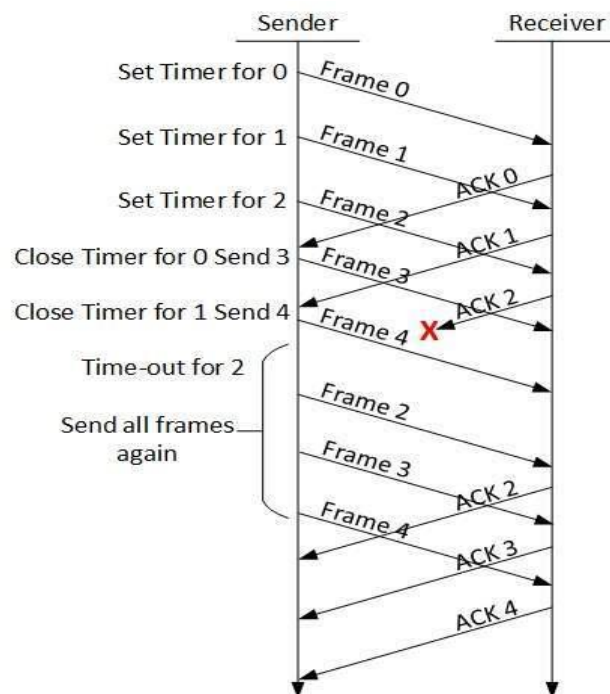


• Go-Back-N ARQ

The working principle of this protocol is:

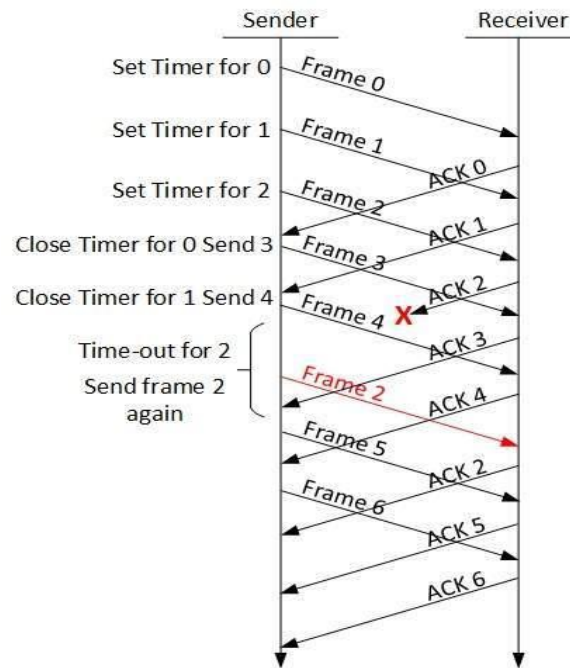
- The sender has buffers called sending window.

- The sender sends multiple frames based upon the sending-window size, without receiving the acknowledgment of the previous ones.
- The receiver receives frames one by one. It keeps track of incoming frame's sequence number and sends the corresponding acknowledgment frames.
- After the sender has sent all the frames in window, it checks up to what sequence number it has received positive acknowledgment.
- If the sender has received positive acknowledgment for all the frames, it sends next set of frames.
- If sender receives NACK or has not receive any ACK for a particular frame, it retransmits all the frames after which it does not receive any positive ACK.



• Selective Repeat ARQ

- Both the sender and the receiver have buffers called sending window and receiving window respectively.
- The sender sends multiple frames based upon the sending-window size, without receiving the acknowledgment of the previous ones.
- The receiver also receives multiple frames within the receiving window size.
- The receiver keeps track of incoming frame's sequence numbers, buffers the frames in memory.
- It sends ACK for all successfully received frames and sends NACK for only frames which are missing or damaged.
- The sender in this case, sends only packet for which NACK is received.



4.6 MULTIPLEXING

Multiplexing is a technique used to combine and send the multiple data streams over a single medium. The process of combining the data streams is known as multiplexing and hardware used for multiplexing is known as a multiplexer.

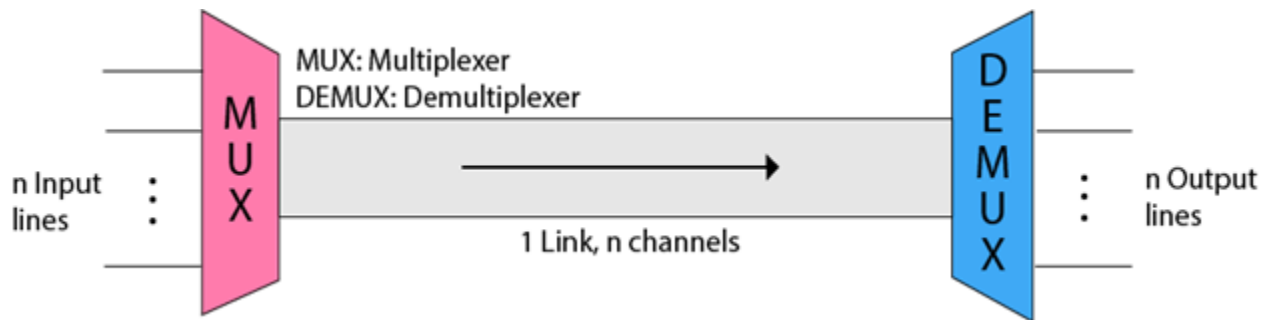
Multiplexing is achieved by using a device called Multiplexer (**MUX**) that combines n input lines to generate a single output line. Multiplexing follows many-to-one, i.e., n input lines and one output line.

De-multiplexing is achieved by using a device called De-multiplexer (**DEMUX**) available at the receiving end. DEMUX separates a signal into its component signals (one input and n outputs). Therefore, we can say that de-multiplexing follows the one-to-many approach.

Why Multiplexing?

- The transmission medium is used to send the signal from sender to receiver. The medium can only have one signal at a time.
- If there are multiple signals to share one medium, then the medium must be divided in such a way that each signal is given some portion of the available bandwidth. For example: If there are 10 signals and bandwidth of medium is 100 units, then the 10 unit is shared by each signal.
- When multiple signals share the common medium, there is a possibility of collision. Multiplexing concept is used to avoid such collision.
- Transmission services are very expensive.

Concept of Multiplexing



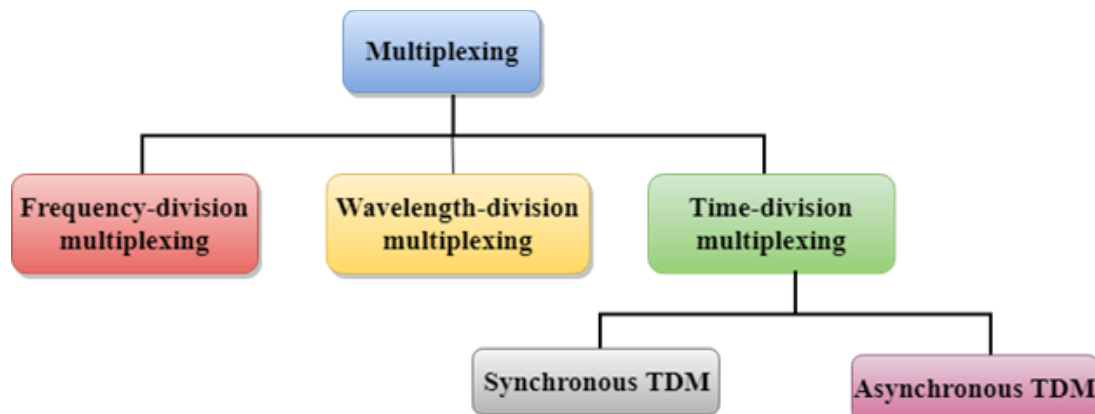
- The 'n' input lines are transmitted through a multiplexer and multiplexer combines the signals to form a composite signal.
- The composite signal is passed through a Demultiplexer and demultiplexer separates a signal to component signals and transfers them to their respective destinations.

Advantages of Multiplexing:

- More than one signal can be sent over a single medium.
- The bandwidth of a medium can be utilized effectively.

Multiplexing Techniques

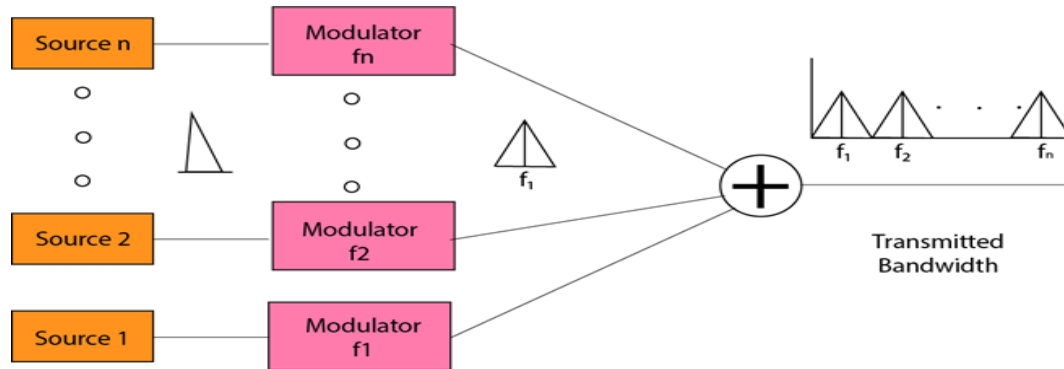
Multiplexing techniques can be classified as:



4.7 FREQUENCY-DIVISION MULTIPLEXING (FDM)

- When the carrier is frequency, FDM is used.
- FDM is an analog technology.
- FDM divides the spectrum or carrier bandwidth in logical channels and allocates one user to each channel.
- Each user can use the channel frequency independently and has exclusive access of it.
- All channels are divided in such a way that they do not overlap with each other.

- Channels are separated by guard bands. Guard band is a frequency which is not used by either channel.



Advantages of FDM:

- FDM is used for analog signals.
- FDM process is very simple and easy modulation.
- A Large number of signals can be sent through an FDM simultaneously.
- It does not require any synchronization between sender and receiver.

Disadvantages of FDM:

- FDM technique is used only when low-speed channels are required.
- It suffers the problem of crosstalk.
- A Large number of modulators are required.
- It requires a high bandwidth channel.

Applications of FDM:

- FDM is commonly used in TV networks.
- It is used in FM and AM broadcasting. Each FM radio station has different frequencies, and they are multiplexed to form a composite signal. The multiplexed signal is transmitted in the air.

4.8 TIME DIVISION MULTIPLEXING

- It is a digital technique.
- In Frequency Division Multiplexing Technique, all signals operate at the same time with different frequency, but in case of Time Division Multiplexing technique, all signals operate at the same frequency with different time.
- In **Time Division Multiplexing technique**, the total time available in the channel is distributed among different users. Therefore, each user is allocated with different time interval known as a Time slot at which data is to be transmitted by the sender.
- A user takes control of the channel for a fixed amount of time.
- In Time Division Multiplexing technique, data is not transmitted simultaneously rather the data is transmitted one-by-one.
- In TDM, the signal is transmitted in the form of frames. Frames contain a cycle of time slots in which each frame contains one or more slots dedicated to each user.

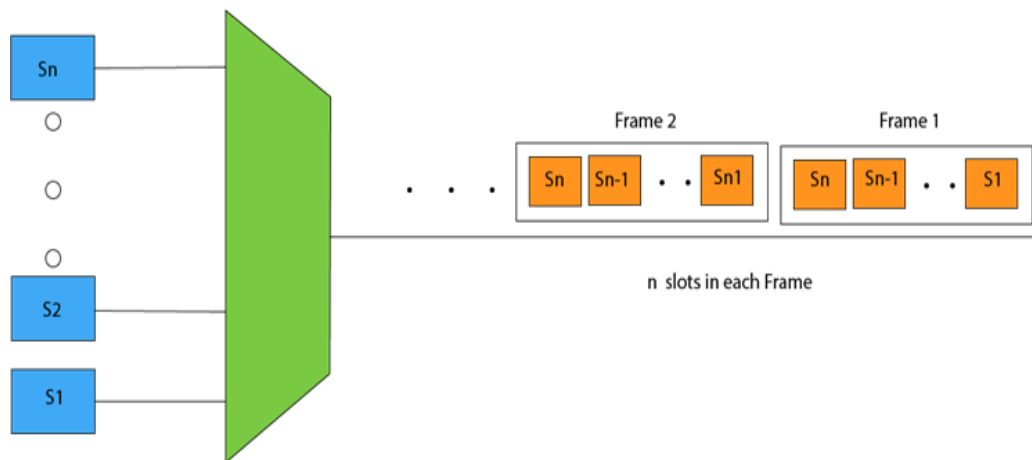
- It can be used to multiplex both digital and analog signals but mainly used to multiplex digital signals.

There are two types of TDM:

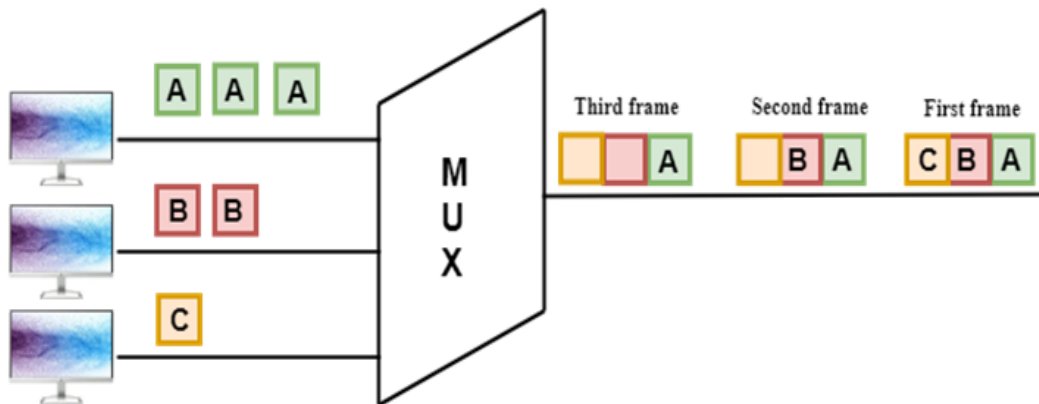
- Synchronous TDM
- Asynchronous TDM

4.8.1 SYNCHRONOUS TDM

- A Synchronous TDM is a technique in which time slot is preassigned to every device.
- In Synchronous TDM, each device is given some time slot irrespective of the fact that the device contains the data or not.
- If the device does not have any data, then the slot will remain empty.
- In Synchronous TDM, signals are sent in the form of frames. Time slots are organized in the form of frames. If a device does not have data for a particular time slot, then the empty slot will be transmitted.
- The most popular Synchronous TDM are T-1 multiplexing, ISDN multiplexing, and SONET multiplexing.
- If there are n devices, then there are n slots.



Concept of Synchronous TDM



In the above figure, the Synchronous TDM technique is implemented. Each device is allocated with some time slot. The time slots are transmitted irrespective of whether the sender has data to send or not.

Disadvantages of Synchronous TDM:

- The capacity of the channel is not fully utilized as the empty slots are also transmitted which is having no data. In the above figure, the first frame is completely filled, but in the last two frames, some slots are empty. Therefore, we can say that the capacity of the channel is not utilized efficiently.
- The speed of the transmission medium should be greater than the total speed of the input lines. An alternative approach to the Synchronous TDM is Asynchronous Time Division Multiplexing.

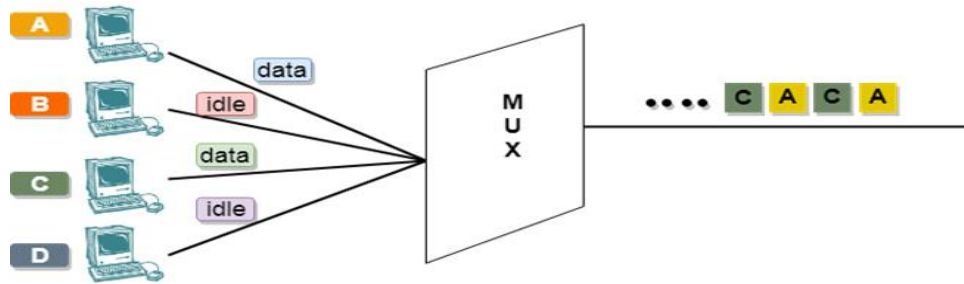
4.8.2 STATISTICAL TIME DIVISION MULTIPLEXING- (ASYNCHRONOUS TDM)

- An asynchronous TDM is also known as Statistical TDM.
- An asynchronous TDM is a technique in which time slots are not fixed as in the case of Synchronous TDM. Time slots are allocated to only those devices which have the data to send. Therefore, we can say that Asynchronous Time Division multiplexor transmits only the data from active workstations.
- An asynchronous TDM technique dynamically allocates the time slots to the devices.
- In Asynchronous TDM, total speed of the input lines can be greater than the capacity of the channel.
- Asynchronous Time Division multiplexor accepts the incoming data streams and creates a frame that contains only data with no empty slots.
- In Asynchronous TDM, each slot contains an address part that identifies the source of the data.

ADDRESS	DATA
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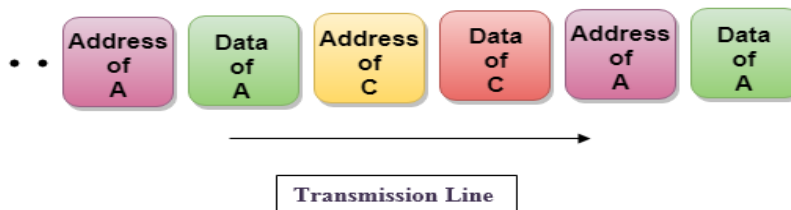
- The difference between Asynchronous TDM and Synchronous TDM is that many slots in Synchronous TDM are unutilized, but in Asynchronous TDM, slots are fully utilized. This leads to the smaller transmission time and efficient utilization of the capacity of the channel.
- In Synchronous TDM, if there are n sending devices, then there are n time slots. In Asynchronous TDM, if there are n sending devices, then there are m time slots where m is less than n ($m < n$).
- The number of slots in a frame depends on the statistical analysis of the number of input lines.

Concept Of Asynchronous TDM



In the above diagram, there are 4 devices, but only two devices are sending the data, i.e., A and C. Therefore, the data of A and C are only transmitted through the transmission line.

Frame of above diagram can be represented as:



The above figure shows that the data part contains the address to determine the source of the data.

Advantages of Time Division Multiplexing (TDM)

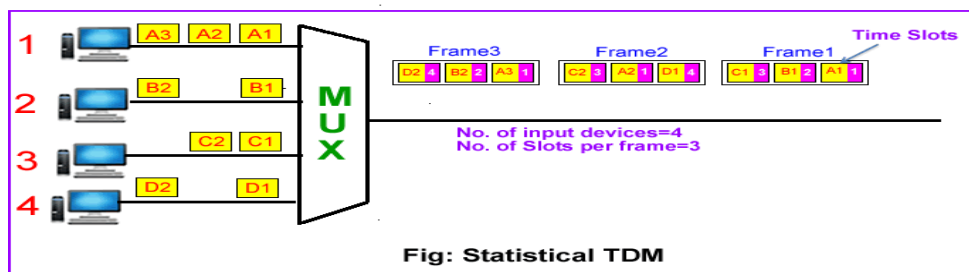
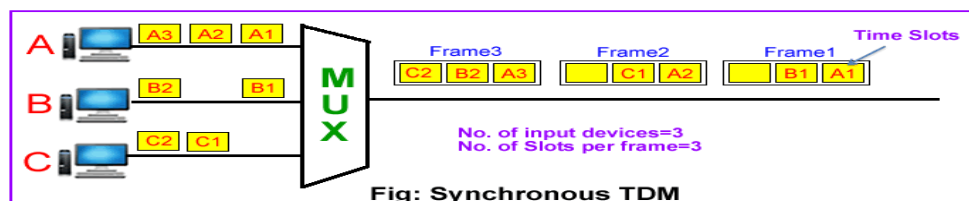
1. Full bandwidth is utilized by a user at a particular time.
2. The time division multiplexing technique is more flexible than frequency division multiplexing.
3. In time division multiplexing, the problem of crosstalk is very less.

Disadvantages of Time Division Multiplexing (TDM)

In time division multiplexing, synchronization is required.

4.9 DIFFERENCE BETWEEN SYNCHRONOUS TDM AND STATISTICAL TDM

Parameter	Synchronous TDM	Statistical TDM
Working	In Synchronous TDM data flow of each input connection is divided into units and each input occupies one output time slot.	In Statistical TDM slots are allotted dynamically. i.e. input line is given slots in output frame if and only if it has data to send.
No. of Slots	In Synchronous TDM no. of slots in each frame are equal to no. of input lines.	In Statistical TDM, No. of slots in each frame are less than the no. of input lines.
Buffers	Buffering is not done, frame is sent after a particular interval of time whether someone has data to send or not.	Buffering is done and only those inputs are given slots in output frame whose buffer contains data to send.
Addressing	Slots in Synchronous TDM carry data only and there is no need of addressing. Synchronization and pre assigned relationships between input and outputs that serve as an address.	Slots in Statistical TDM contain both data and address of the destination.
Synchronization	Synchronization bits are used at the beginning of each frame.	No synchronization bits are used
Capacity	Max. Bandwidth utilization if all inputs have data to send.	The capacity of link is normally is less than the sum of the capacity of each channel.
Data Separation	In Synchronous TDM de-multiplexer at receiving end decomposes each frame, discards framing bits and extracts data unit in turn. This extracted data unit from frame is then passed to destination device.	In Statistical TDM de-multiplexer at receiving end decomposes each frame by checking local address of each data unit. This extracted data unit from frame is then passed to destination device.



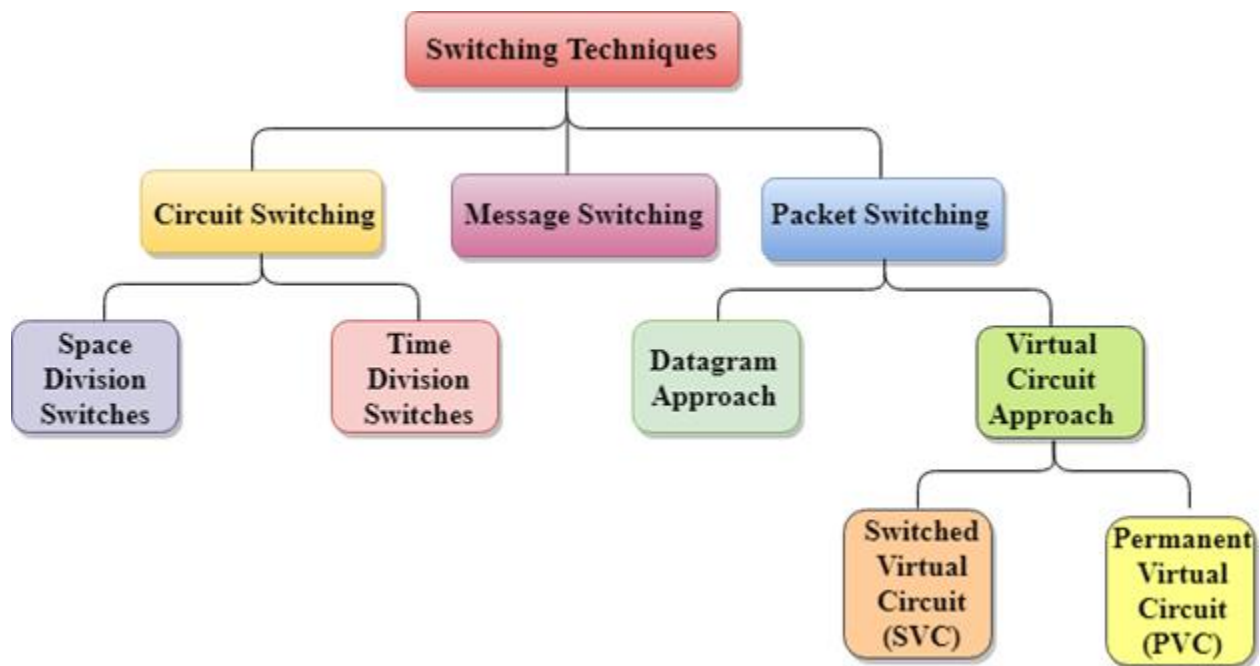
UNIT-5: SWITCHING & ROUTING

5.1 SWITCHING TECHNIQUES

In large networks, there can be multiple paths from sender to receiver. The switching technique will decide the best route for data transmission.

Switching technique is used to connect the systems for making one-to-one communication.

Classification of Switching Techniques

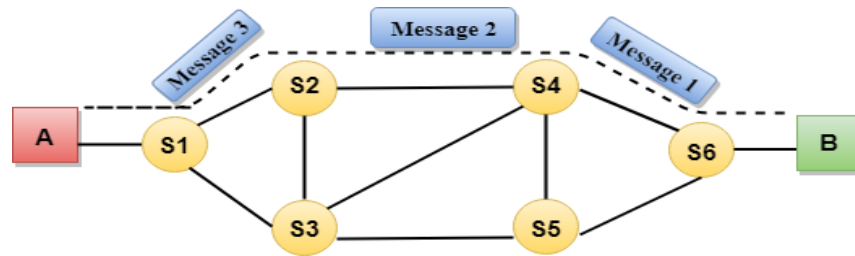


5.1.1 CIRCUIT SWITCHING

- Circuit switching is a switching technique that establishes a dedicated path between sender and receiver.
- In the Circuit Switching Technique, once the connection is established then the dedicated path will remain to exist until the connection is terminated.
- Circuit switching in a network operates in a similar way as the telephone works.
- A complete end-to-end path must exist before the communication takes place.
- In case of circuit switching technique, when any user wants to send the data, voice, video, a request signal is sent to the receiver then the receiver sends back the acknowledgment to ensure the availability of the dedicated path. After receiving the acknowledgment, dedicated path transfers the data.
- Circuit switching is used in public telephone network. It is used for voice transmission.
- Fixed data can be transferred at a time in circuit switching technology.

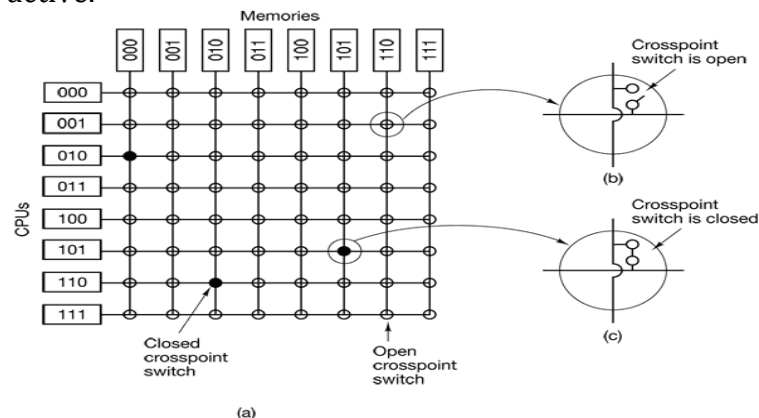
Communication through circuit switching has 3 phases:

- Circuit establishment
- Data transfer
- Circuit Disconnect



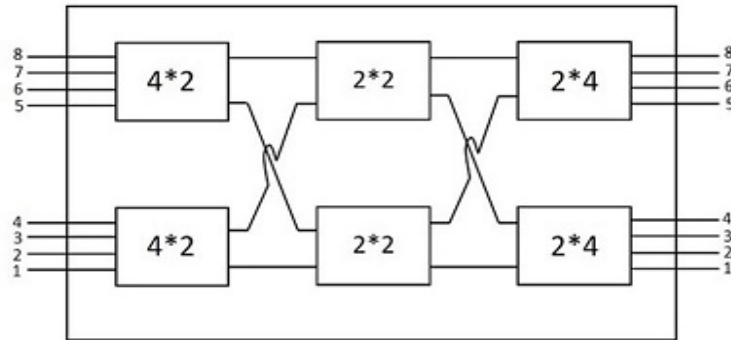
Space Division Switches:

- In space division switching, the paths in the circuit are separated with each other spatially, i.e. different ongoing connections at a same instant of time, uses different switching paths.
- This was originally developed for the analog environment and has been carried over to the digital domain. The space switches are crossbar switches and multi stage switches.
- **Crossbar switch-**
 1. Basic building block of the switch is a metallic cross points or semiconductor gate that can be enabled or disabled by a control unit.
 2. The number of cross points grows with the square of the number of attached stations.
 3. Costly for a large switch.
 4. The failure of a cross point prevents connection between the two devices whose lines intersect at that cross point.
 5. The cross points are inefficiently utilized.
 6. Only a small fraction of cross points are engaged even if all of the attached devices are active.



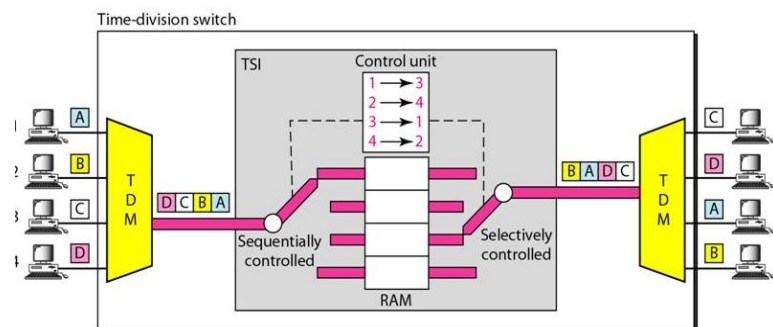
- Multistage space division switch-
 1. Some of the problem in crossbar switch can be overcome with the help of multistage space division switches.
 2. By splitting the crossbar switch into smaller units and interconnecting them it is possible to build multistage switches with fewer cross points.
 3. There is more than one path through the network to connect two endpoints, thereby increasing reliability.
 4. Multistage switches may lead to blocking.

5. The problem may be tackled by increasing the number or size of the intermediate switches, which also increases the cost.



Time Division Switching

Time Division switching uses Time Division Multiplexing (TDM) inside a switch. The most popular technology is called the Time Slot Interchange (TSI).



Advantages Of Circuit Switching:

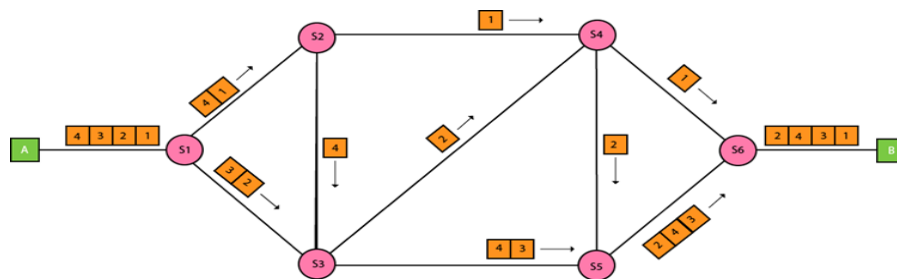
- In the case of Circuit Switching technique, the communication channel is dedicated.
- It has fixed bandwidth.

Disadvantages of Circuit Switching:

- Once the dedicated path is established, the only delay occurs in the speed of data transmission.
- It takes a long time to establish a connection approx. 10 seconds during which no data can be transmitted.
- It is more expensive than other switching techniques as a dedicated path is required for each connection.
- It is inefficient to use because once the path is established and no data is transferred, then the capacity of the path is wasted.
- In this case, the connection is dedicated therefore no other data can be transferred even if the channel is free.

5.1.2 PACKET SWITCHING

- The packet switching is a switching technique in which the message is sent in one go, but it is divided into smaller pieces, and they are sent individually.
- The message splits into smaller pieces known as packets and packets are given a unique number to identify their order at the receiving end.
- Every packet contains some information in its headers such as source address, destination address and sequence number.
- Packets will travel across the network, taking the shortest path as possible.
- All the packets are reassembled at the receiving end in correct order.
- If any packet is missing or corrupted, then the message will be sent to resend the message.
- If the correct order of the packets is reached, then the acknowledgment message will be sent.



Approaches of Packet Switching:

There are two approaches to Packet Switching:

Datagram Packet switching:

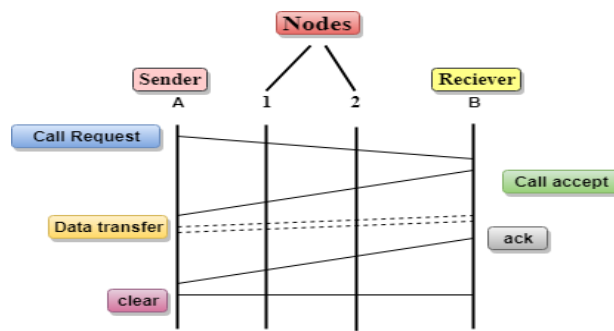
- It is a packet switching technology in which packet is known as a datagram, is considered as an independent entity. Each packet contains the information about the destination and switch uses this information to forward the packet to the correct destination.
- The packets are reassembled at the receiving end in correct order.
- In Datagram Packet Switching technique, the path is not fixed.
- Intermediate nodes take the routing decisions to forward the packets.
- Datagram Packet Switching is also known as connectionless switching.

Virtual Circuit Switching

- Virtual Circuit Switching is also known as connection-oriented switching.
- In the case of Virtual circuit switching, a preplanned route is established before the messages are sent.
- Call request and call accept packets are used to establish the connection between sender and receiver.

- In this case, the path is fixed for the duration of a logical connection.

Let's understand the concept of virtual circuit switching through a diagram:



- In the above diagram, A and B are the sender and receiver respectively. 1 and 2 are the nodes.
- Call request and call accept packets are used to establish a connection between the sender and receiver.
- When a route is established, data will be transferred.
- After transmission of data, an acknowledgment signal is sent by the receiver that the message has been received.
- If the user wants to terminate the connection, a clear signal is sent for the termination.

Advantages of Packet Switching:

- **Cost-effective:** In packet switching technique, switching devices do not require massive secondary storage to store the packets, so cost is minimized to some extent. Therefore, we can say that the packet switching technique is a cost-effective technique.
- **Reliable:** If any node is busy, then the packets can be rerouted. This ensures that the Packet Switching technique provides reliable communication.
- **Efficient:** Packet Switching is an efficient technique. It does not require any established path prior to the transmission, and many users can use the same communication channel simultaneously, hence makes use of available bandwidth very efficiently.

Disadvantages of Packet Switching:

- Packet Switching technique cannot be implemented in those applications that require low delay and high-quality services.
- The protocols used in a packet switching technique are very complex and requires high implementation cost.
- If the network is overloaded or corrupted, then it requires retransmission of lost packets. It can also lead to the loss of critical information if errors are not recovered.

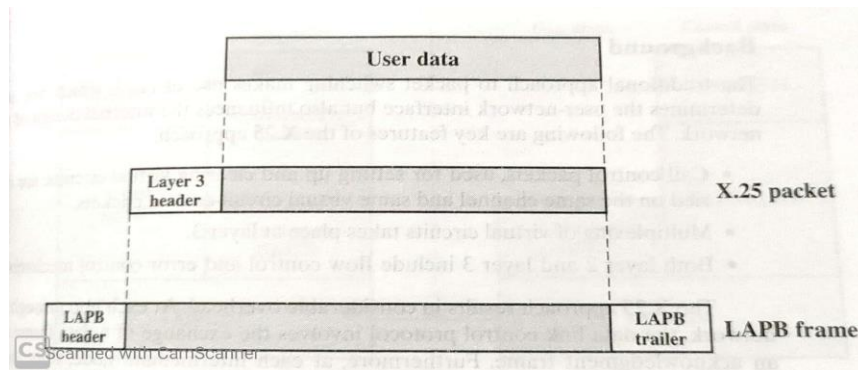
5.2 DIFFERENCE BETWEEN CIRCUIT SWITCHING AND PACKET SWITCHING

CIRCUIT SWITCHING	PACKET SWITCHING
In circuit switching there are 3 phases i) Connection Establishment. ii) Data Transfer. iii) Connection Released.	In Packet switching directly data transfer takes place.
In circuit switching, each data unit know the entire path address which is provided by the source	In Packet switching, each data unit just know the final destination address intermediate path is decided by the routers.
In Circuit switching, data is processed at source system only	In Packet switching, data is processed at all intermediate node including source system.
Delay between data units in circuit switching is uniform.	Delay between data units in packet switching is not uniform.
Resource reservation is the feature of circuit switching because path is fixed for data transmission.	There is no resource reservation because bandwidth is shared among users.
Circuit switching is more reliable.	Packet switching is less reliable.
Wastage of resources are more in Circuit Switching	Less wastage of resources as compared to Circuit Switching
It is not a store and forward technique.	It is a store and forward technique.
Transmission of the data is done by the source	Transmission of the data is done not only by the source, but also by the intermediate routers
Congestion can occur during connection establishment time, there might be a case will requesting for channel the channel is already occupied.	Congestion can occur during data transfer phase, large number of packets comes in no time

5.3 X.25-

- X.25 is an ITU-T standard that specifies an interface between a host system and a packet switching network.
- The functionality of X.25 is specified on three levels:
 - (a) Physical level
 - (b) Link level
 - (c) Packet level
- The physical level deals with the physical interface between an attached station (computer) and the link that attaches that station to the packet switching node.
- The link level provides for the reliable transfer of data across the physical link, by transmitting the data as a sequence of frames.
- The link level standard is referred to as LAPB (Link Access Protocol- Balanced)

- The packet level provides a virtual circuit service. This service enables any subscriber to the network to set up logical connections, called virtual circuits to other subscribers.
- The term virtual circuit refers to the logical connection between two stations through the network.



- The above diagram shows the relationship among the levels of X.25. User data are passed down to X.25 level 3, which appends control information as a header, creating a packet.
- This control information serves several purposes including-
 - 1) Identifying by number a particular virtual circuit with which this data is to be associated.
 - 2) Providing sequence numbers that can be used for flow and error control.
- The entire X.25 packet is then passed down to the LAPB entity, which appends control information at the front and back of the packet forming a LAPB frame.

X.25 permits a DTE user on an **X.25 network** to communicate with a number of remote DTE's simultaneously. Connections occur on logical channels of two types:

- **Switched virtual circuits (SVC's)** – SVC's are very much like telephone calls; a connection is established, data are transferred and then the connection is released. Each DTE on the network is given a unique DTE address which can be used much like a telephone number.
- **Permanent virtual circuits (PVC's)** – a PVC is similar to a leased line in that the connection is always present. The logical connection is established permanently by the Packet Switched Network administration. Therefore, data may always be sent, without any call setup.

To establish a connection on an SVC, the calling DTE sends a **Call Request** Packet, which includes the address of the remote DTE to be contacted.

The destination DTE decides whether or not to accept the call (the Call Request packet includes the sender's DTE address, as well as other information that the called DTE can use to decide whether or not to accept the call).

A call is accepted by issuing a **Call Accepted** packet, or cleared by issuing a **Clear Request** packet.

Once the originating DTE receives the Call Accepted packet, the virtual circuit is established and data transfer may take place. When either DTE wishes to terminate the call, a **Clear Request** packet is sent to the remote DTE, which responds with a **Clear Confirmation** packet.

Advantages:

1. X.25 is a protocol designed for data transfer over public telephone lines. It was first developed in the 1960s to support host-to-host data transfer over noisy lines.
2. To provide redress for the problems with noisy transmission, X.25 performs extensive error checking and error recovery.
3. In a switching network, X.25 checks packets from each switch. Packets are only forwarded when a positive acknowledgment is received. Thus the X.25 protocol achieves high reliability at the expense of low data transfer speed.

Disadvantages:

1. The disadvantages of X.25 become apparent when we look at how it differs from frame relay.
2. The area of error checking shows the main differences with the two protocols. As mentioned earlier, X.25 provides error correction and retransmission functions.
3. The link layer peer protocol specified in X.25 is called LAP-B (Link Access Procedure-Balanced).
4. The LAP-B provides link management, error control, flow control and failure recovery. These operations take place in the Data Link and Network layers.
5. A high level of guarantee is given to the originator that the data is received with no errors and in the correct sequence.

5.4 ROUTING IN PACKET SWITCHING NETWORKS-

Characteristics-

The primary function of a packet-switching network is to accept packets from a source station and deliver them to a destination station. To accomplish this, a path or route through the network must be determined; generally, more than one route is possible. Thus, a routing function must be performed. The requirements for this function include

- Correctness
- Fairness
- Simplicity
- Optimality
- Robustness
- Efficiency
- Stability

The first two items on the list, correctness and simplicity, are self-explanatory. Robustness has to do with the ability of the network to deliver packets via some route in the face of localized failures and overloads. Ideally, the network can react to such contingencies without the loss of packets or the breaking of virtual circuits.

The designer who seeks robustness must cope with the competing requirement for stability. Techniques that react to changing conditions have an unfortunate tendency to either react too slowly to events or to experience unstable swings from one extreme to another. For example, the network may react to congestion in one area by shifting most of the load to a second area.

Now the second area is overloaded and the first is underutilized, causing a second shift. During these shifts, packets may travel in loops through the network. A tradeoff also exists between fairness and optimality. Some performance criteria may give higher priority to the exchange of packets between nearby stations compared to an exchange between distant stations. This policy may maximize average throughput but will appear unfair to the station that primarily needs to communicate with distant stations. Finally, any routing technique involves some processing overhead at each node and often a transmission overhead as well, both of which impair network efficiency. The penalty of such overhead needs to be less than the benefit accrued based on some reasonable metric, such as increased robustness or fairness.

Performance Criteria

- The simplest criterion is to choose the minimum-hop route (one that passes through the least number of nodes) through the network.
- Minimum-hop criterion is least-cost routing.
- The least cost route should provide the highest throughput.
- The least cost route should minimize delay.

Decision Time and Place

- Routing decisions are made on the basis of some performance criterion. Two key characteristics of the decision are the time and place that the decision is made.
- Decision time is determined by whether the routing decision is made on a packet or virtual circuit basis.
- The term decision place refers to which node or nodes in the network are responsible for the routing decision. Most common is distributed routing, in which each node has the responsibility of selecting an output link for routing packets as they arrive.
- For centralized routing, the decision is made by some designated node, such as a network control center.

5.5 ROUTING STRATEGIES-

In most of the situations, packets require multiple hops to make a journey towards the destination. Routing is one of the most complex and crucial aspects of packet switched network design.

Routing Strategies:

1. Fixed Routing
2. Flooding
3. Random Routing
4. Adaptive Routing

Fixed Routing –

- For fixed routing a single permanent route is configured for each source-destination pair of nodes in the network.
- The routes are fixed or at least only change when there is a change in the topology of the network.
- A central routing matrix is created based on the least cost path which is stored in the network control center.
- The matrix shows for each source –destination route, the identity of the next node on the route.
- With fixed routing, there is no difference between routing for datagrams and virtual circuits. All packets from a given source to a given destination follow the same route.

Flooding –

- This technique requires no network information like topology, load condition, cost of diff. paths.
- A packet is sent by a source node to every one of its neighbors.
- At each node, an incoming packet is retransmitted on all outgoing links except for the link on which it arrived.
- All nodes which are directly or indirectly connected are visited. So, there are no chances for any node to be left out. This is a main criteria in case of broadcast messages.
- Flooding tends to create an infinite number of duplicate data packets.

Random Routing:

- Random routing has the simplicity and robustness of flooding with far less traffic load.
- With random routing, a node selects only one outgoing path for retransmission of an incoming packet.
- The outgoing link is chosen at random, excluding the link on which the packet arrived.
- If all links are equally likely to be chosen, then a node may simply utilize outgoing links in a round-robin fashion.
- Like flooding, random routing technique requires the use of no network information. Because the route taken is random.

Adaptive Routing:

- The routing decisions that are made change as conditions on the network change is known as adaptive routing.
- The conditions that influence routing decisions are-
 - 1) Failure: When a node or link fails, it can no longer be used as part of a route.
 - 2) Congestion: When a particular portion of the network is heavily congested.
- The routing decision is more complex.
- Adaptive strategies depend on status information that is collected at one place but used at another.
- An adaptive strategy may react too quickly causing congestions or too slowly.
- This strategy can improve performance, as seen by the network user.
- This strategy helps in congestion control.

5.6 CONGESTION

- Congestion is an important issue that can arise in packet switched network.
- Congestion is a situation in Communication Networks in which too many packets are present in a part of the subnet, performance degrades.

- Congestion in a network may occur when the load on the network (*i.e.* the number of packets sent to the network) is greater than the capacity of the network (*i.e.* the number of packets a network can handle.).
- Network congestion occurs in case of traffic overloading.
- In other words when too much traffic is offered, congestion sets in and performance degrades sharply

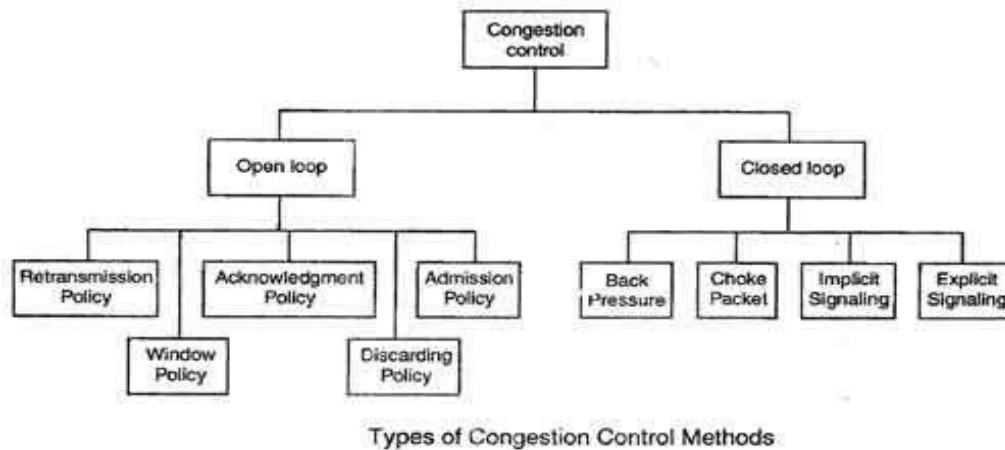
5.7 EFFECTS OF CONGESTION

- There are two buffers or queues at each port one to accept arriving packets and one to hold packets that are waiting to depart. There might be two fixed size buffers associated with each port.
- As packets arrive they are stored in the input buffer of the corresponding port. The node examines each incoming packet, makes a routing decision and then moves the packet to the appropriate output buffer.
- Packets queued for output are transmitted as rapidly as possible. If packets arrive too fast for the node to process them or faster than packets can be cleared from the outgoing buffers, then eventually packets will arrive for which no memory is available.
- When such a saturation point is reached, one of two strategies can be adopted.
- The first strategy is to discard any incoming packet for which there is no available buffer space.
- The alternative is the node that is experiencing these problems to exercise some sort of flow control over its neighbors so that the traffic flow remains manageable.
- Hence as delay increases performance decreases.

5.8 CONGESTION CONTROL

- Congestion Control refers to techniques and mechanisms that can either prevent congestion, before it happens, or remove congestion, after it has happened.

- Congestion control mechanisms are divided into two categories, one category prevents the congestion from happening and the other category removes congestion after it has taken place.



These two categories are:

1. Open loop
2. Closed loop

1. Open Loop Congestion Control

- In this method, policies are used to prevent the congestion before it happens.
- Congestion control is handled either by the source or by the destination.
- The various methods used for open loop congestion control are:

❖ Retransmission Policy

- The sender retransmits a packet, if it feels that the packet it has sent is lost or corrupted.
- However retransmission in general may increase the congestion in the network. But we need to implement good retransmission policy to prevent congestion.
- The retransmission policy and the retransmission timers need to be designed to optimize efficiency and at the same time prevent the congestion.

❖ Window Policy

- To implement window policy, selective reject window method is used for congestion control.
- Selective Reject method is preferred over Go-back-n window as in Go-back-n method, when timer for a packet times out, several packets are resent, although some may have arrived safely at the receiver. Thus, this duplication may make congestion worse.
- Selective reject method sends only the specific lost or damaged packets.

❖ Acknowledgement Policy

- The acknowledgement policy imposed by the receiver may also affect congestion.
- If the receiver does not acknowledge every packet it receives it may slow down the sender and help prevent congestion.

- Acknowledgments also add to the traffic load on the network. Thus, by sending fewer acknowledgements we can reduce load on the network.

❖ **Discarding Policy**

- A router may discard less sensitive packets when congestion is likely to happen.
- Such a discarding policy may prevent congestion and at the same time may not harm the integrity of the transmission.

❖ **Admission Policy**

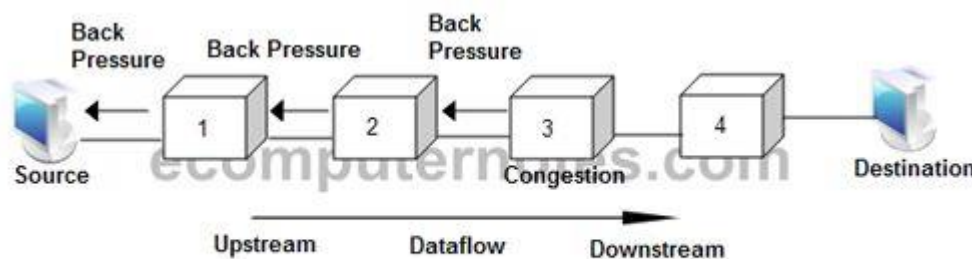
- An admission policy, which is a quality-of-service mechanism, can also prevent congestion in virtual circuit networks.
- Switches in a flow first check the resource requirement of a flow before admitting it to the network.
- A router can deny establishing a virtual circuit connection if there is congestion in the "network or if there is a possibility of future congestion.

2. Closed Loop Congestion Control

- Closed loop congestion control mechanisms try to remove the congestion after it happens.
- The various methods used for closed loop congestion control are:

❖ **Backpressure**

- This technique produces an effect similar to backpressure in fluids flowing down a pipe. When the end of the pipe is closed, the fluid pressure backs up the pipe to the point of origin, where the flow is stopped .



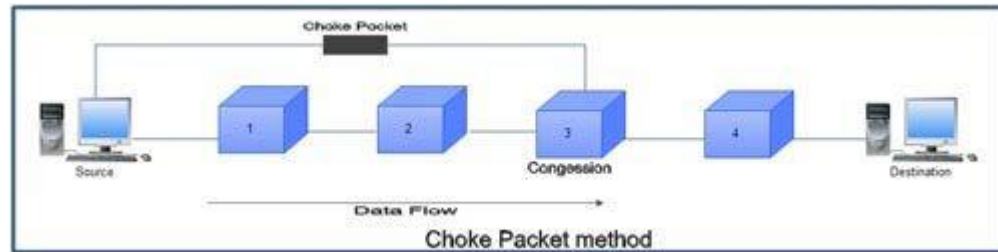
Backpressure Method

- Backpressure can be selectively applied to logical connections, so that the flow from one node to the next is only restricted or halted on some connections, generally the ones with the most traffic.
- It can be used in a connection oriented network.

Choke Packet

- In this method of congestion control, congested router or node sends a special type of packet called choke packet to the source to inform it about the congestion.

- Here, congested node does not inform its upstream node about the congestion as in backpressure method.
- In choke packet method, congested node sends a warning directly to the source station *i.e.* the intermediate nodes through which the packet has traveled are not warned.



❖ Implicit Signaling

- In implicit signaling, there is no communication between the congested node or nodes and the source.
- The source guesses that there is congestion somewhere in the network when it does not receive any acknowledgment. Therefore the delay in receiving an acknowledgment is interpreted as congestion in the network.
- On sensing this congestion, the source slows down.
- This type of congestion control policy is used by TCP.

❖ Explicit Signaling

- In this method, the congested nodes explicitly send a signal to the source or destination to inform about the congestion.
- Explicit signaling is different from the choke packet method. In choke packet method, a separate packet is used for this purpose whereas in explicit signaling method, the signal is included in the packets that carry data.
- Explicit signaling can occur in either the forward direction or the backward direction.
- In backward signaling, a bit is set in a packet moving in the direction opposite to the congestion. This bit warns the source about the congestion and informs the source to slow down.
- In forward signaling, a bit is set in a packet moving in the direction of congestion. This bit warns the destination about the congestion. The receiver in this case uses policies such as slowing down the acknowledgements to remove the congestion.

5.9 TRAFFIC MANAGEMENT-

Congestion control is concerned with efficient use of a network at high load. There are a number of issues related to congestion control that might be included under the general category of traffic management.

- 1) Fairness
- 2) Quality of Service
- 3) Reservations

Fairness-

- As congestion develops, flows of packets between sources and destinations will experience increased delays and, with high congestion, packet losses.
- Simply to discard on a last-in-first-discarded basis may not be fair.
- As an example of a technique that might promote fairness, a node can maintain a separate queue for each logical connection or for each source-destination pair.
- If all of the queue buffers are of equal length, then the queues with the highest traffic load will suffer discards more often, allowing lower-traffic connections a fair share of the capacity.

Quality of Service-

- Quality of Service (QoS) refers to any technology that manages data traffic to reduce packet loss, latency and jitter on the network.
- Quality of Service controls and manages network resources by setting priorities for specific types of data on the network.
- For example, a node might transmit higher-priority packets ahead of lower-priority packets in the same queue.

Reservations-

- One way to avoid congestion and also to provide assured service to applications is to use a reservation scheme. Such a scheme is an integral part of ATM networks.
- When a logical connection is established, the network and the user enter into a traffic contract, which specifies a data rate and other characteristics of the traffic flow.
- The network agrees to give a defined QoS so long as the traffic flow is within contract parameters; excess traffic is either discarded or handled on a best-effort basis, subject to discard.
- If the current outstanding reservations are such that the network resources are inadequate to meet the new reservation, then the new reservation is denied.

5.10 CONGESTION CONTROL IN PACKET SWITCHING NETWORKS-

A number of control mechanisms for congestion control in packet-switching networks have been suggested and tried. The following are examples:

1. Send a control packet from a congested node to some or all source nodes. This choke packet will have the effect of stopping or slowing the rate of transmission from sources and hence limit the total number of packets in the network. This approach requires additional traffic on the network during a period of congestion.
2. Rely on routing information. Routing algorithms, such as ARPANET's, provide link delay information to other nodes, which influences routing decisions. This information could also be used to influence the rate at which new packets are produced. Because these delays are

being influenced by the routing decision, they may vary too rapidly to be used effectively for congestion control.

3. Make use of an end-to-end probe packet. Such a packet could be timestamped to measure the delay between two particular endpoints. This has the disadvantage of adding overhead to the network.

4. Allow packet-switching nodes to add congestion information to packets as they go by. There are two possible approaches here. A node could add such information to packets going in the direction opposite of the congestion. This information quickly reaches the source node, which can reduce the flow of packets into the network. Alternatively, a node could add such information to packets going in the same direction as the congestion. The destination either asks the source to adjust the load or returns the signal back to the source in the packets (or acknowledgments) going in the reverse direction.

UNIT-6: LAN TECHNOLOGY

6.1 TOPOLOGY AND TRANSMISSION MEDIA-

The key elements of a LAN are

- Topology
- Transmission medium
- Wiring layout
- Medium access control

These elements determine not only the cost and capacity of the LAN, but also the type of data that may be transmitted, the speed and efficiency of communications and even the kinds of applications that can be supported.

Choice of Topology

The choice of topology depends on a variety of factors, including reliability, expandability and performance.

This choice is part of the overall task of designing a LAN and thus cannot be made in isolation, independent of the choice of transmission medium. There are four alternative media that can be used for a bus LAN.

- **Twisted pair:** In the early days of LAN development, voice-grade twisted pair was used to provide an inexpensive, easily installed bus LAN.
- **Baseband coaxial cable:** A baseband coaxial cable is one that makes use of digital signaling. The original Ethernet scheme makes use of baseband coaxial cable.
- **Broadband coaxial cable:** Broadband coaxial cable is the type of cable used in cable television systems. Analog signaling is used at radio and television frequencies. This type of system is more expensive and more difficult to install and maintain than baseband coaxial cable.
- **Optical fiber:** There has been considerable research relating to this alternative over the years, but the expense of the optical fiber taps.

Thus, for a bus topology, only baseband coaxial cable has achieved widespread use, primarily for Ethernet systems. Compared to a star-topology twisted pair or optical fiber installation, the bus topology using baseband coaxial cable is difficult to work with.

Very-high-speed links over considerable distances can be used for the ring topology. Hence, the ring has the potential of providing the best throughput of any topology.

Choice of Transmission Medium

The choice of transmission medium is determined by a number of factors. It is, we shall see, constrained by the topology of the LAN. Other factors come into play, including

- Capacity: to support the expected network traffic
- Reliability: to meet requirements for availability
- Types of data supported: tailored to the application
- Environmental scope: to provide service over the range of environments required

Office buildings are wired to meet the anticipated telephone system demand plus a healthy margin; thus, there are no cable installation costs in the use of Category 3 UTP.

Category 5 UTP supports high data rates for a small number of devices, but larger installations can be supported by the use of the star topology and the interconnection of the switching elements in multiple star-topology configurations.

Optical fiber has a number of attractive features, such as electromagnetic isolation, high capacity, and small size, which have attracted a great deal of interest.

6.2 LAN PROTOCOL ARCHITECTURE-

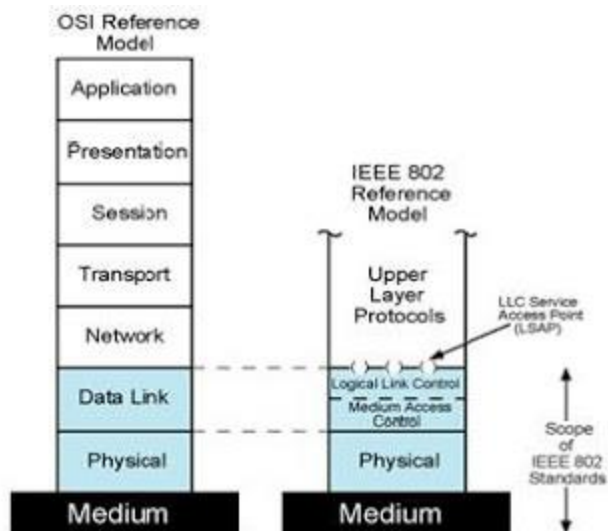
IEEE 802 Reference Model Protocols defined specifically for LAN and MAN transmission address issues relating to the transmission of blocks of data over the network. In OSI terms, higher layer protocols (layer 3 or 4 and above) are independent of network architecture and are applicable to LANs, MANs and WANs.

This architecture was developed by the IEEE 802 LAN standards committee² and has been adopted by all organizations working on the specification of LAN standards. It is generally referred to as the IEEE 802 reference model. Working from the bottom up, the lowest layer of the IEEE 802 reference model corresponds to the physical layer of the OSI model and includes such functions as

- Encoding/decoding of signals
- Preamble generation/removal (for synchronization)
- Bit transmission/reception

The physical layer of the 802 model includes a specification of the transmission medium and the topology. Above the physical layer are the functions associated with providing service to LAN users. These include

- On transmission, assemble data into a frame with address and error detection fields.
- On reception, disassemble frame, and perform address recognition and error detection.
- Govern access to the LAN transmission medium.
- Provide an interface to higher layers and perform flow and error control.



These are functions typically associated with OSI layer 2. The set of functions in the last bullet item are grouped into a logical link control (LLC) layer. The functions in the first three bullet items are treated as a separate layer, called medium access control (MAC).

Higher-level data are passed down to LLC, which appends control information as a header, creating an LLC protocol data unit (PDU). This control information is used in the operation of the LLC protocol. The entire LLC PDU is then passed down to the MAC layer, which appends control information at the front and back of the packet, forming a MAC frame.

Medium Access Control & Logical Link Control:

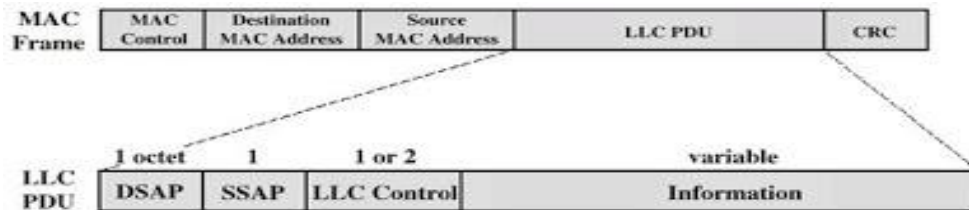
The OSI layer 2 (data link) is divided into two in LAN.

1) Medium Access Control (MAC): It performs assembling of data into frames with address and error detection field (for transmission), and disassembling of frame (on reception), MAC layer receives data from LLC layer and perform the error detection and address recognition.

2) Logical Link Control (LLC):

- LLC has two characteristics-
 - 1) It must support the multi-access, shared medium nature of the link.
 - 2) It is relieved of some details of link access by the MAC layer.
- LLC provide services-
 - 1) Unacknowledged connectionless service- This service is a datagram style service. It is a very simple service that does not involve any of the flow and error control mechanisms.
 - 2) Connection mode service- A logical connection is set up between two users exchanging data and flow control and error control are provided.
 - 3) Acknowledged connectionless service- This is a cross between the previous two services. It provides that datagrams are to be acknowledged but no prior logical connection is set up.
- LLC Protocol-

- 1) LLC protocol PDU format consists of four fields. The DSAP (Destination Service Access Point) and SSAP (Source Service Access Point) fields each contain a 7 bit address which specify the destination and source users of LLC.
- 2) One bit of the DSAP indicates whether the DSAP is an individual or group address.
- 3) One bit of the SSAP indicates whether the PDU is a command or response PDU.
The rest two fields are control field and information field.



6.3 MEDIUM ACCESS CONTROL

- All LANs and MANs consist of collections of devices that must share the network's transmission capacity. Some means of controlling access to the transmission medium is needed to provide for an orderly and efficient use of that capacity.
- This is the function of a medium access control (MAC) protocol. The key parameters in any medium access control technique are where and how. Where refers to whether control is exercised in a centralized or distributed fashion.
- In a centralized scheme, a controller is designated that has the authority to grant access to the network. A station wishing to transmit must wait until it receives permission from the controller.
- In a decentralized network, the stations collectively perform a medium access control function to determine dynamically the order in which stations transmit. A centralized scheme has certain advantages, including
 1. It may afford greater control over access for providing such things as priorities, overrides and guaranteed capacity.
 2. It enables the use of relatively simple access logic at each station.
 3. It avoids problems of distributed coordination among peer entities.
- The principal disadvantages of centralized schemes are
 1. It creates a single point of failure; that is, there is a point in the network that, if it fails, causes the entire network to fail.
 2. It may act as a bottleneck, reducing performance.

- The second parameter, **how**, is constrained by the topology and is a tradeoff among competing factors, including cost, performance, and complexity.
- In general, we can categorize access control techniques as being either synchronous or asynchronous. With synchronous techniques, a specific capacity is dedicated to a connection. This is the same approach used in circuit switching, frequency division multiplexing (FDM), and synchronous time division multiplexing (TDM). Such techniques are generally not optimal in LANs and MANs because the needs of the stations are unpredictable.
- It is preferable to be able to allocate capacity in an asynchronous (dynamic) fashion, more or less in response to immediate demand. The asynchronous approach can be further subdivided into three categories: round robin, reservation and contention.

1. Round Robin

- With round robin, each station in turn is given the opportunity to transmit. During that opportunity, the station may decline to transmit
- When many stations have data to transmit over an extended period of time, round-robin techniques can be very efficient.
- If only a few stations have data to transmit over an extended period of time, then there is a considerable overhead in passing the turn from station to station, because most of the stations will not transmit but simply pass their turns.

2. Reservation

For stream traffic, reservation techniques are well suited. In general, for these techniques, time on the medium is divided into slots, much as with synchronous TDM. A station wishing to transmit reserves future slots for an extended or even an indefinite period. Again, reservations may be made in a centralized or distributed fashion.

3. Contention

For bursty traffic, contention techniques are usually appropriate. With these techniques, no control is exercised to determine whose turn it is; all stations contend for time.

MAC Frame Format

The MAC layer receives a block of data from the LLC layer and is responsible for performing functions related to medium access and for transmitting the data. As with other protocol layers, MAC implements these functions making use of a protocol data unit at its layer. In this case, the PDU is referred to as a MAC frame.

The fields of this frame are

- **MAC Control:** This field contains any protocol control information needed for the functioning of the MAC protocol. For example, a priority level could be indicated here.
- **Destination MAC Address:** The destination physical attachment point on the LAN for this frame.
- **Source MAC Address:** The source physical attachment point on the LAN for this frame.
- **LLC:** The LLC data from the next higher layer.
- **CRC:** The Cyclic Redundancy Check field (also known as the frame check sequence, FCS, field). This is an error-detecting code.

6.4 BRIDGES-

The bridge is designed for use between local area networks (LANs) that use identical protocols for the physical and link layers (e.g., all conforming to IEEE 802.3). Because the devices all use the same protocols, the amount of processing required at the bridge is minimal. More sophisticated bridges are capable of mapping from one MAC format to another (e.g., to interconnect an Ethernet and a token ring LAN). Depending on circumstance, there are several reasons for the use of multiple LANs connected by bridges:

• **Reliability:**

The danger in connecting all data processing devices in an organization to one network is that a fault on the network may disable communication for all devices. By using bridges, the network can be partitioned into self-contained units.

• **Performance:**

Performance on a LAN declines with an increase in the number of devices or the length of the wire. A number of smaller LANs will often give improved performance if devices can be clustered so that intra network traffic significantly exceeds internetwork traffic.

• **Security:**

The establishment of multiple LANs may improve security of communications. It is desirable to keep different types of traffic (e.g., accounting, personnel, strategic planning) that have different security needs on physically separate media.

• **Geography:**

Two separate LANs are needed to support devices clustered in two geographically distant locations. Even in the case of two buildings separated by a highway, it may be far easier to use a microwave bridge link than to attempt to string coaxial cable between the two buildings.

6.5 HUB-

The term hub in reference to a star-topology LAN. The hub is the active central element of the star layout. Each station is connected to the hub by two lines (transmit and receive). The hub acts as a repeater: When a single station transmits, the hub repeats the signal on the outgoing line to each station. Ordinarily, the line consists of two unshielded twisted pairs. Because of the high data rate and the poor transmission qualities of unshielded twisted pair, the length of a line is limited to about 100 m. As an alternative, an optical fiber link may be used. In this case, the maximum length is about 500 m.

Three basic types of hubs exist:

- **Passive hubs** don't amplify the electrical signal of incoming packets before broadcasting them out to the network.
- **Active hubs** perform amplification, much like a repeater.
- **Intelligent hubs** add extra features to an active hub that are of particular importance to businesses. An intelligent hub is typically stackable, meaning that it's built in such a way that multiple units can be placed one on top of the other to conserve space. Intelligent Ethernet hubs often include remote management capabilities via SNMP and virtual LAN (VLAN) support.

6.6 SWITCHES-

A switch is a multiport bridge with a buffer and a design that can boost its efficiency (a large number of ports imply less traffic) and performance. A switch is a data link layer device. The switch can perform error checking before forwarding data that makes it very efficient as it does not forward packets that have errors and forward good packets selectively to correct port only. In other words, switch divides collision domain of hosts, but broadcast domain remains same.

Two types of layer 2 switches are available as commercial products:

- **Store-and-forward switch:** The layer 2 switch accepts a frame on an input line, buffers it briefly, and then routes it to the appropriate output line.
- **Cut-through switch:** The layer 2 switch takes advantage of the fact that the destination address appears at the beginning of the MAC (medium access control) frame. The layer 2 switch begins repeating the incoming frame onto the appropriate output line as soon as the layer 2 switch recognizes the destination address.

The cut-through switch yields the highest possible throughput but at some risk of propagating bad frames, because the switch is not able to check the CRC prior to retransmission. The store-and-forward switch involves a delay between sender and receiver

but boosts the overall integrity of the network. A layer 2 switch can be viewed as a full-duplex version of the hub. It can also incorporate logic that allows it to function as a multiport bridge. Lists the following differences between layer 2 switches and bridges:

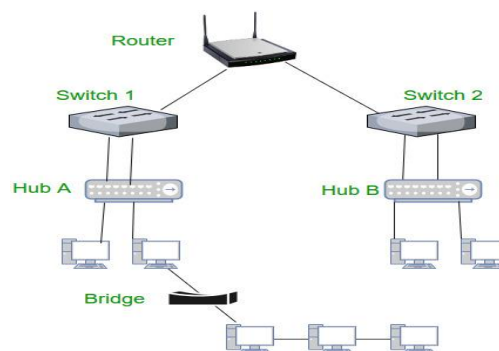
- Bridge frame handling is done in software. A layer 2 switch performs the address recognition and frame forwarding functions in hardware.
- A bridge can typically only analyze and forward one frame at a time, whereas a layer 2 switch has multiple parallel data paths and can handle multiple frames at a time.
- A bridge uses store-and-forward operation. With a layer 2 switch, it is possible to have cut-through instead of store-and-forward operation.

Because a layer 2 switch has higher performance and can incorporate the functions of a bridge, the bridge has suffered commercially. New installations typically include layer 2 switches with bridge functionality rather than bridges.

Layer 2 switches provide increased performance to meet the needs of high-volume traffic generated by personal computers, workstations and servers.

However, as the number of devices in a building or complex of buildings grows, layer 2 switches reveal some inadequacies. Two problems in particular present themselves: broadcast overload and the lack of multiple links.

To overcome these problems, it seems logical to break up a large local network into a number of subnetworks connected by routers (Layer3 Switch). A router is a device like a switch that routes data packets based on their IP addresses. Router is mainly a Network Layer device. Routers normally connect LANs and WANs together and have a dynamically updating routing table based on which they make decisions on routing the data packets. Router divide broadcast domains of hosts connected through it.



6.7 ETHERNET:-

- Ethernet is most widely used LAN Technology, which is defined under IEEE standards 802.3.
- The reason behind its wide usability is Ethernet is easy to understand, implement, maintain and allows low-cost network implementation. Also, Ethernet offers flexibility in terms of topologies which are allowed.

- Ethernet operates in two layers of the OSI model, Physical Layer, and Data Link Layer.
- For Ethernet, the protocol data unit is Frame.
- In order to handle collision, the Access control mechanism used in Ethernet is CSMA/CD.

CSMA (Carrier Sense Multiple Access)

- CSMA Protocols stands for Carrier Sense Multiple Access Protocols.
- CSMA is a network access method used on shared network topologies such as Ethernet to control access to the network.
- Devices attached to the network cable listen (carrier sense) before transmitting.
- If the channel is in use, devices wait before transmitting.
- MA (Multiple Access) indicates that many devices can connect to and share the same network.
- All devices have equal access to use the network when it is clear.

1-Persistent CSMA

1-persistent CSMA is an aggressive version of Carrier Sense Multiple Access (CSMA) protocol that operates in the Medium Access Control (MAC) layer. Using CSMA protocols, more than one users or nodes send and receive data through a shared medium that may be a single cable or optical fiber connecting multiple nodes, or a portion of the wireless spectrum.

In 1-persistent CSMA, when a transmitting station has a frame to send and it senses a busy channel, it waits for the end of the transmission, and transmits immediately. Since, it sends with a probability 1, the name 1 – persistent CSMA is given.

It is used in CSMA/CD (Carrier Sense Multiple Access with Collision Detection) systems including Ethernet.

P-persistent CSMA protocol

P-persistent CSMA is an approach of Carrier Sense Multiple Access (CSMA) protocol that combines the advantages of 1-persistent CMSA and non-persistent CSMA. Using CSMA protocols, more than one users or nodes send and receive data through a shared medium that may be a single cable or optical fiber connecting multiple nodes, or a portion of the wireless spectrum.

In p-persistent CSMA, when a transmitting station has a frame to send and it senses a busy channel, it waits for the end of the transmission, and then transmits with a probability p. Since, it sends with a probability p, the name p – persistent CSMA is given.

Non-persistent CSMA protocol

Non-persistent CSMA is a non – aggressive version of Carrier Sense Multiple Access (CSMA) protocol that operates in the Medium Access Control (MAC) layer. Using CSMA protocols, more than one users or nodes send and receive data through a shared medium that may be a single cable or optical fiber connecting multiple nodes, or a portion of the wireless spectrum.

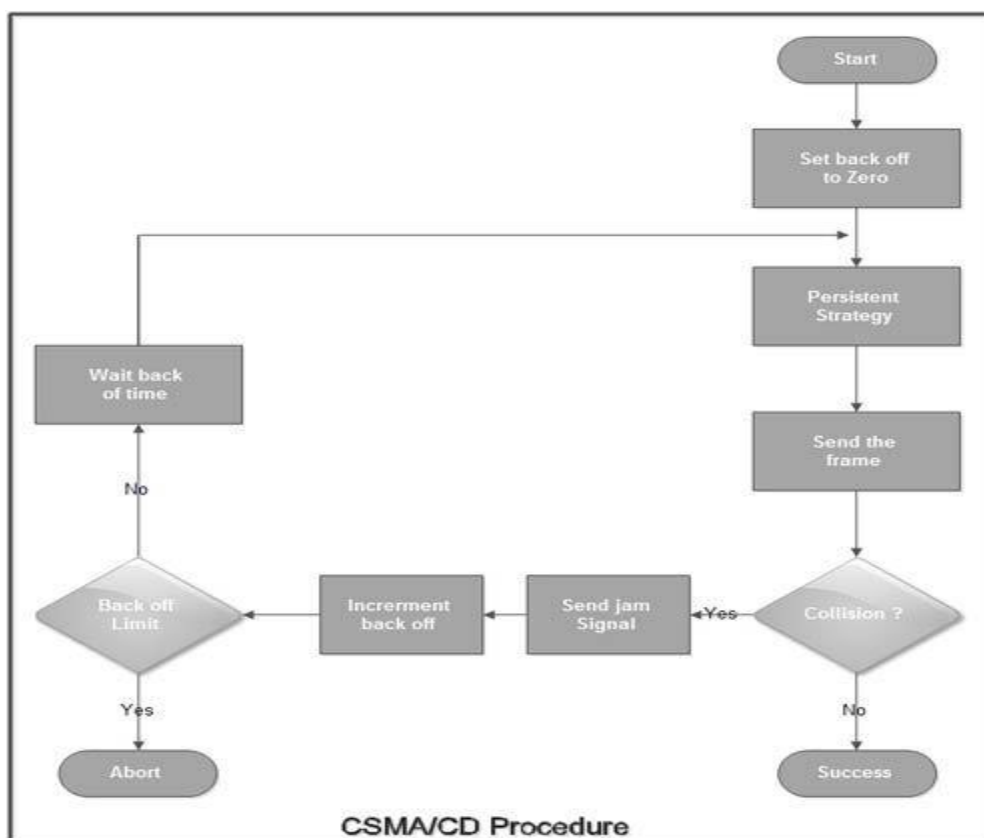
In non-persistent CSMA, when a transmitting station has a frame to send and it senses a busy channel, it waits for a random period of time without sensing the channel in the interim, and repeats the algorithm again.

6.8 CSMA/ CD

- To reduce the impact of collisions on the network performance, Ethernet uses an algorithm called CSMA with Collision Detection (CSMA / CD).
- CSMA/CD is a protocol in which the station senses the carrier or channel before transmitting frame just as in persistent and non-persistent CSMA.
- If the channel is busy, the station waits. it listens at the same time on communication media to ensure that there is no collision with a packet sent by another station.
- In a collision, the issuer immediately cancel the sending of the package.
- This allows to limit the duration of collisions: we do not waste time to send a packet complete if it detects a collision.
- After a collision, the transmitter waits again silence and again, he continued his hold for a random number; but this time the random number is nearly double the previous one: this is called back-off exponential.
- In fact, the window collision is simply doubled (unless it has already reached a maximum).
- From a packet is transmitted successfully, the window will return to its original size.

CSMA/CD Procedure:

Fig. Shows a flow chart for the *CSMA/CD* protocol.



Explanation:

- The station that has a ready frame sets the back off parameter to zero.
- Then it senses the line using one of the persistent strategies.
- If then sends the frame. If there is no collision for a period corresponding to one complete frame, then the transmission is successful.
- Otherwise the station sends the jam signal to inform the other stations about the collision.
- The station then increments the back off time and waits for a random back off time and sends the frame again.
- If the back off has reached its limit then the station aborts the transmission.
- *CSMA/CD* is used for the traditional Ethernet.
- *CSMA/CD* is an important protocol. IEEE 802.3 (Ethernet) is an example of *CSMA/CD*. It is an international standard.
- The MAC sublayer protocol does not guarantee reliable delivery. Even in absence of collision the receiver may not have copied the frame correctly.

6.9 FIBER CHANNEL-

- Fiber channel is a high speed networking technology primarily used for transmitting data among data centers, computer servers, switches and storage at data rates of upto 128 Gbps.
- Fiber channel suited for connecting servers to shared storage devices and interconnecting storage controllers and drives.
- Fiber channel devices can be as far as 10 Km apart if multimodal optical fiber is used as the physical medium.
- Optical fiber is not required for shorter distances. Fiber channel also works using coaxial cable and ordinary telephone twisted pair.
- The key elements of a fiber channel network are the end systems, called nodes and the network itself, which consists of one or more switching elements.
- The collection of switching elements is referred to as a fabric.
- These elements are interconnected by point to point links between ports on the individual nodes and switches.
- The fiber channel protocol architecture is organized into five levels. Each level defines a function or set of related functions. The layers are as follows-
 - 1) FC-0 Physical Media-It includes optical fiber for long distance applications, coaxial cable for high speeds over short distances and shielded twisted pair for lower speeds over short distances.
 - 2) FC-1 Transmission Protocol- It defines the signal encoding scheme
 - 3) FC-2 Framing Protocol- It deals with defining topologies, frame format, flow and error control and grouping of frames into logical entities called sequences.
 - 4) FC-3 common services- It includes multicasting.
 - 5) FC-4 Mapping- It defines the mapping of various channel and network protocols to fiber channel.

Fiber Channel Elements

The key elements of a Fiber Channel network are the end systems, called nodes, and the network itself, which consists of one or more switching elements. The collection of switching elements is referred to as a fabric. These elements are interconnected by point-to-point links between ports on the individual nodes and switches. Communication consists of the transmission of frames across the point-to-point links.

6.10 WIRELESS LAN TECHNOLOGY-

Wireless LANs are generally categorized according to the transmission technique that is used. All current wireless LAN products fall into one of the following categories:

- Infrared (IR) LANs
- Spread spectrum LANs

Infrared LANs

- Infrared LANs use infrared signals to transmit data. This is same technology used in products like remote controls for televisions and VCRs.
- These LANs can be setup using a point to point configuration is known as Directed- Beam IR.
- An omnidirectional configuration involves a single base station that is within Line of Sight of all other stations on the LAN. This station is mounted on the ceiling. The ceiling transmitter broadcasts an omnidirectional signal that can be received by all of the other IR Tran receivers in the area. These other Trans receivers transmit a directional beam aimed at the ceiling base unit.
- In a diffused configuration, all of the IR transmitters are focused and aimed at a point on a diffusely reflecting ceiling. IR radiation striking the ceiling is reradiated Omni directionally and picked up by all of the receivers in the area.
- Infrared equipment is inexpensive and simple.
- Many indoor environments experience rather intense infrared background radiation, from sunlight and indoor lighting.

Spread Spectrum LANs

- Spread spectrum is currently the most widely used transmission technique for wireless LANs.
- It was initially developed by the military to avoid jamming.
- This is done by spreading the signal over a range of frequencies that consist of the industrial, scientific and medical bands of the electromagnetic spectrum.
- The first type of spread spectrum developed is known as frequency hopping spread spectrum.
- The other type of spread spectrum is called direct sequence spread spectrum.
- Frequency hopping radios currently use less power than direct sequence radios and generally cost less.
- While direct sequence data rate of 8 Mbps and frequency hopping have a limit of 2 Mbps.

UNIT-7: TCP/IP

7.1 TCP/IP PROTOCOL SUITE-

- The internet protocol suit is the conceptual model and set of communications protocols used in the internet and similar computer networks. It is known as TCP/IP because the foundational protocols in the suite are the Transmission Control Protocol (TCP) and the Internet Protocol (IP).
- The Internet Protocol suite provides end to end data communication specifying how data should be packetized, addressed, transmitted, routed and received.
- This functionality is organized into four abstraction layers.
- From lowest to highest, the layers are the link layer, containing communication methods for data that remains within a single network segment, the internet layer, providing inter networking between independent networks, the transport layer, handling host to host communication and the application layer, providing process to process data exchange for application.

7.2 BASIC PROTOCOL FUNCTIONS IN TCP/IP

The protocol functions are grouped into the following categories:

- Encapsulation
- Fragmentation and reassembly
- Connection control
- Ordered delivery
- Flow control
- Error control
- Addressing
- Multiplexing
- Transmission services

Encapsulation-

- For virtually all protocols, data are transferred in blocks, called Protocol Data Units (PDU).
- Each PDU contains not only data but also control information. The control information falls into three categories: Address, Error detecting code, protocol control.

The addition of control information to data is referred to as encapsulation.

Fragmentation and Reassembly

- A protocol is concerned with exchanging data between two entities.
- Protocol may need to divide a block received from a higher layer into multiple blocks of some smaller bounded size. This process is called fragmentation.

The counterpart of fragmentation is reassembly. Eventually, the segmented data must be reassembled into messages appropriate to the application level. If PDUs arrive out of order, the task is complicated

Connection Control

- An entity may transmit data to another entity in such a way that each PDU is treated independently of all prior PDUs. This is known as connectionless data transfer, an example is the use of the datagram.
- Connection-oriented data transfer is preferred (even required) if stations anticipate a lengthy exchange of data.

A logical association is established between the entities using three phases.

- Connection establishment
- Data transfer
- Connection termination

Ordered Delivery

- If two communicating entities are in different hosts²connected by a network, there is a risk that PDUs will not arrive in the order in which they were sent, because they may traverse different paths through the network.

- In connection-oriented protocols, it is generally required that PDU order always be maintained.
- If each PDU is given a unique number, and numbers are assigned sequentially, then it is a logically simple task for the receiving entity to reorder received PDUs on the basis of sequence number.

Flow Control

- Flow control is a function performed by a receiving entity to limit the amount or rate of data that is sent by a transmitting entity.
- The simplest form of flow control is a stop-and-wait procedure, in which each PDU must be acknowledged before the next can be sent.
- More efficient protocols involve some form of credit provided to the transmitter, which is the amount of data that can be sent without an acknowledgment. The HDLC sliding-window technique is an example of this mechanism.

Error Control

- Error control techniques are needed to guard against loss or damage of data and control information.
- Error control is implemented as two separate functions:
 - 1) Error detection
 - 2) Retransmission

Addressing

The concept of addressing in a communications architecture is a complex one and covers a number of issues, including

- Addressing level
- Addressing scope
- Connection identifiers
- Addressing mode
- **Addressing level** refers to the level in the communications architecture at which an entity is named.
- Another issue that relates to the address of an end system or intermediate system is **addressing scope**.

- The concept of **connection identifiers** comes into play when we consider connection-oriented data transfer (e.g., virtual circuit) rather than connectionless data transfer (e.g., datagram).
- For connectionless data transfer, a global identifier is used with each data transmission.
- For connection-oriented transfer, it is sometimes desirable to use only a connection identifier during the data transfer phase.
- Another addressing concept is that of addressing mode. Most commonly, an address refers to a single system or port; in this case it is referred to as an individual or unicast address
- An address for multiple recipients may be broadcast.

Multiplexing-

One form of multiplexing is supported by means of multiple connections into a single system. For example, with frame relay, there can be multiple data link connections terminating in a single end system; we can say that these data link connections are multiplexed over the single physical interface between the end system and the network.

Transmission Services

A protocol may provide a variety of additional services to the entities that use it. We mention here three common examples:

- **Priority:** Certain messages, such as control messages, may need to get through to the destination entity with minimum delay. An example would be a terminate-connection request. Thus, priority could be assigned on a message basis. Additionally, priority could be assigned on a connection basis.
- **Quality of service:** Certain classes of data may require a minimum throughput or a maximum delay threshold.
- **Security:** Security mechanisms, restricting access, may be invoked.

7.3 PRINCIPLE OF INTERNETWORKING-

Internet-

A collection of communication networks interconnected by bridges and routers.

Intranet-

An internet used by a single organization that provides the key internet applications. An internet operates within the organization for internal purposes.

End System-

A device attached to one of the networks of an internet that is used to support end-user applications or services.

Intermediate System (ISs)-

A device used to connect two networks and permit communication between end systems attached to different networks. Two types of ISs are bridges and routers.

Bridges-

A bridges at layer 2 of the Open System Interconnection (OSI). An IS used to connect two LANs that use similar LAN protocols.

Routers-

A router operates at layer 3 of the OSI architecture and routes packets between potentially different networks.

Requirements

The overall requirements for an internetworking facility are as follows:

1. Provide a link between networks. At minimum, a physical and link control connection is needed.
2. Provide for the routing and delivery of data between processes on different networks.
3. Provide an accounting service that keeps track of the use of the various networks and routers and maintains status information.
4. Provide the services just listed in such a way as not to require modifications to the networking architecture. These include
 - Different addressing schemes: The networks may use different endpoint names and addresses and directory maintenance schemes.

- Different maximum packet size: Packets from one network may have to be broken up into smaller pieces for another. This process is referred to as fragmentation.
- Different network access mechanisms: The network access mechanism between station and network may be different for stations on different networks.
- Different timeouts: Typically, a connection-oriented transport service will await an acknowledgment until a timeout expires, at which time it will retransmit its block of data. Internetwork timing procedures must allow successful transmission that avoids unnecessary retransmissions.
- Error recovery: Network procedures may provide anything from no error recovery up to reliable end-to-end (within the network) service.
- Status reporting: Different networks report status and performance differently. Yet it must be possible for the internetworking facility to provide such information on internetworking activity to interested and authorized processes.
- Routing techniques: Intra network routing may depend on fault detection and congestion control techniques. The internetworking facility must be able to coordinate these to route data adaptively between stations on different networks.
- User access control: Each network will have its own user access control technique (authorization for use of the network).
- Connection, connectionless: Individual networks may provide connection oriented (e.g., virtual circuit) or connectionless (datagram) service.

The Internet Protocol (IP) meets some of these requirements.

Connectionless Operation

Connectionless-mode operation corresponds to the datagram mechanism of a packet-switching network. Each network protocol data unit is treated independently and routed from source ES to destination ES through a series of routers and networks. The Internet Protocol (IP) meets some of these requirements.

7.4 INTERNET PROTOCOL OPERATION-

Operation of a connectionless internetworking scheme-

IP provides a connectionless, or datagram, service between end systems. There are a number of advantages to this approach:

- A connectionless internet facility is flexible.
- A connectionless internet service can be made highly robust. This is basically the same argument made for a datagram network service versus a virtual circuit service.
- A connectionless internet service is best for connectionless transport protocols, because it does not impose unnecessary overhead.

At each router, before the data can be forwarded, the router may need to fragment the datagram to accommodate a smaller maximum packet size limitation on the outgoing network.

The router may also limit the length of its queue for each network to which it attaches so as to avoid having a slow network penalize a faster one. Once the queue limit is reached, additional data units are simply dropped.

The destination end system recovers the IP datagram from its network wrapping. This service offered by IP is an unreliable one. With the Internet Protocol approach, each unit of data is passed from router to router in an attempt to get from source to destination.

Design Issues

Some design issues in greater detail:

- Routing
- Datagram lifetime
- Fragmentation and reassembly
- Error control
- Flow control

Routing-

- For the purpose of routing, each end system and router maintains a routing table that lists, for each possible destination network, the next router to which the internet datagram should be sent.
- Routing tables may also be used to support other inter-networking services, such as security and priority.
- Another routing technique is source routing.

Datagram lifetime-

- A simple way to implement lifetime is to use a hop count.
- Each time that a datagram passes through a router, the count is decremented.
- Alternatively, the life time could be a true measure of time.

Fragmentation and reassembly-

- Routers may need to fragment incoming datagrams into smaller pieces, called segments or fragments.
- To reassemble a datagram, there must be sufficient buffer space at the reassembly point.
- As fragments with the same ID arrive, their data fields are inserted in the proper position in the buffer until the entire data field is reassembled.

Error control-

- When a datagram is discarded by a router, the router should attempt to return some information to the source.
- The source Internet Protocol entity may use this information to modify its transmission strategy and may notify higher layers.

Flow control-

- Internet flow control allows routers and/or receiving stations to limit the rate at which they receive data.

For the connectionless type of service we are describing, flow control mechanisms are limited.

7.5 INTERNET PROTOCOL-

The Internet Protocol (IP) is part of the TCP/IP suite and is the most widely used internetworking protocol. As with any protocol standard, IP is specified in two parts:

- The interface with a higher layer (e.g., TCP), specifying the services that IP provides
- The actual protocol format and mechanisms

IP Services

The services to be provided across adjacent protocol layers (e.g., between IP and TCP) are expressed in terms of primitives and parameters. A primitive specifies the function to be performed, and the parameters are used to pass data and control information. The actual form of a primitive is implementation dependent. An example is a procedure call.

IP provides two service primitives at the interface to the next higher layer. The Send primitive is used to request transmission of a data unit. The Deliver primitive is used by IP to notify a user of the arrival of a data unit. The parameters associated with the two primitives are as follows:

- Source address: Internetwork address of sending IP entity.
- Destination address: Internetwork address of destination IP entity.
- Protocol: Recipient protocol entity (an IP user, such as TCP).
- Type-of-service indicators: Used to specify the treatment of the data unit in its transmission through component networks.
- Identification: Used in combination with the source and destination addresses and user protocol to identify the data unit uniquely. This parameter is needed for reassembly and error reporting.
- Don't fragment identifier: Indicates whether IP can fragment data to accomplish delivery.
- Time to live: Measured in seconds.
- Data length: Length of data being transmitted.
- Option data: Options requested by the IP user.
- Data: User data to be transmitted.

The currently defined options are as follows:

- Security: Allows a security label to be attached to a datagram.

- **Source routing:** A sequenced list of router addresses that specifies the route to be followed. Routing may be strict (only identified routers may be visited) or loose (other intermediate routers may be visited).
- **Route recording:** A field is allocated to record the sequence of routers visited by the datagram.
- **Stream identification:** Names reserved resources used for stream service. This service provides special handling for volatile periodic traffic (e.g., voice).
- **Timestamping:** The source IP entity and some or all intermediate routers add a timestamp (precision to milliseconds) to the data unit as it goes by.

Internet Protocol

The protocol between IP entities is best described with reference to the IP datagram format. The fields are as follows:

- **Version (4 bits):** Indicates version number, to allow evolution of the protocol; the value is 4.
- **Internet Header Length (IHL) (4 bits):** Length of header in 32-bit words. The minimum value is five, for a minimum header length of 20 octets.
- **Type of Service (8 bits):** Prior to the introduction of differentiated services, this field was referred to as the Type of Service field and specified reliability, precedence, delay, and throughput parameters. This interpretation has now been superseded. The first six bits of this field are now referred to as the DS (Differentiated Services) field, the remaining 2 bits are reserved for an ECN (Explicit Congestion Notification) field, currently in the process of standardization. The ECN field provides for explicit signaling of congestion in a manner similar to that discussed for frame relay.
- **Total Length (16 bits):** Total datagram length, including header plus data, in octets.
- **Identification (16 bits):** A sequence number that, together with the source address, destination address, and user protocol, is intended to identify a datagram uniquely. Thus, this number should be unique for the datagram's source address, destination address, and user protocol for the time during which the datagram will remain in the internet.

- **Flags (3 bits):** Only two of the bits are currently defined. The More bit is used for fragmentation and reassembly, as previously explained. The Don't Fragment bit prohibits fragmentation when set. This bit may be useful if it is known that the destination does not have the capability to reassemble fragments. However, if this bit is set, the datagram will be discarded if it exceeds the maximum size of an enroute network.
- **Fragment Offset (13 bits):** Indicates where in the original datagram this fragment belongs, measured in 64-bit units. This implies that fragments other than the last fragment must contain a data field that is a multiple of 64 bits in length.
- **Time to Live (8 bits):** Specifies how long, in seconds, a datagram is allowed to remain in the internet. Every router that processes a datagram must decrease the TTL by at least one, so the TTL is similar to a hop count.
- **Protocol (8 bits):** Indicates the next higher level protocol that is to receive the data field at the destination; thus, this field identifies the type of the next header in the packet after the IP header.
- **Header Checksum (16 bits):** An error-detecting code applied to the header only. Because some header fields may change during transit (e.g., Time to Live, fragmentation-related fields), this is reverified and recomputed at each router. The checksum is formed by taking the ones complement of the 16-bit ones complement addition of all 16-bit words in the header.
- **Source Address (32 bits):** Coded to allow a variable allocation of bits to specify the network and the end system attached to the specified network, as discussed subsequently.
- **Destination Address (32 bits):** Same characteristics as source address.
- **Options (variable):** Encodes the options requested by the sending user.
- **Padding (variable):** Used to ensure that the datagram header is a multiple of 32 bits in length.
- **Data (variable):** The data field must be an integer multiple of 8 bits in length. The maximum length of the datagram (data field plus header) is 65,535 octets.

IP Addresses

The source and destination address fields in the IP header each contain a 32-bit global internet address, generally consisting of a network identifier and a host identifier.

Network Classes

The address is coded to allow a variable allocation of bits to specify network and host. This encoding provides flexibility in assigning addresses to hosts and allows a mix of network sizes on an internet. The three principal network classes are best suited to the following conditions:

- **Class A:** Few networks, each with many hosts
- **Class B:** Medium number of networks, each with a medium number of hosts
- **Class C:** Many networks, each with a few hosts.

Internet Control Message Protocol (ICMP)- ICMP provides a means for transferring messages from routers and other hosts to a host.

ARP- The address resolution protocol (ARP) is a protocol used by the Internet Protocol (IP), specifically IPv4, to map IP network addresses to the hardware addresses used by a data link protocol. The protocol operates below the network layer as a part of the interface between the OSI network and OSI data link layer.